

Artificial Intelligence

Problem solving by searching: Uninformed Search

by
Abdul Sahli Fakhardin
Faculty Computer Systems & Software Engineering
sahli@ump.edu.my

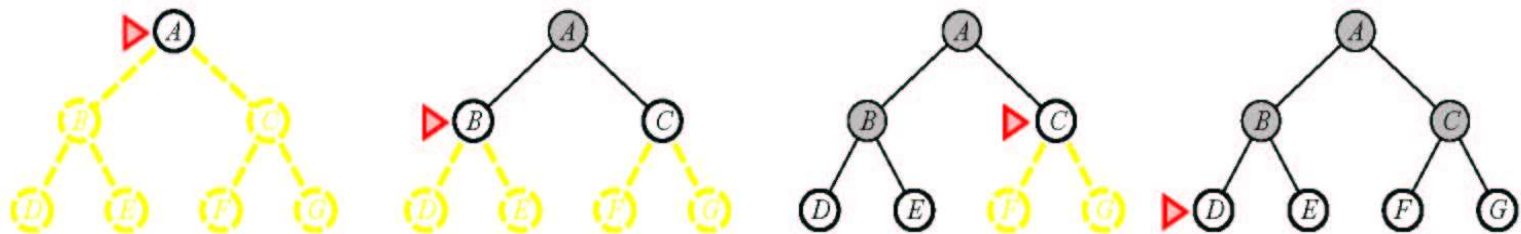
Chapter Description

- Expected Outcomes
 - Student able to review the breadth firsts search, death first search, depth limited search, iterative deepening search and uniform cost search
 - Student able to analyse and apply the searches to solve a given problem
- References
 -

Content #1

- What is artificial intelligence?
- History of artificial intelligence
- Example of artificial intelligence application

Breadth First Search (BFS)

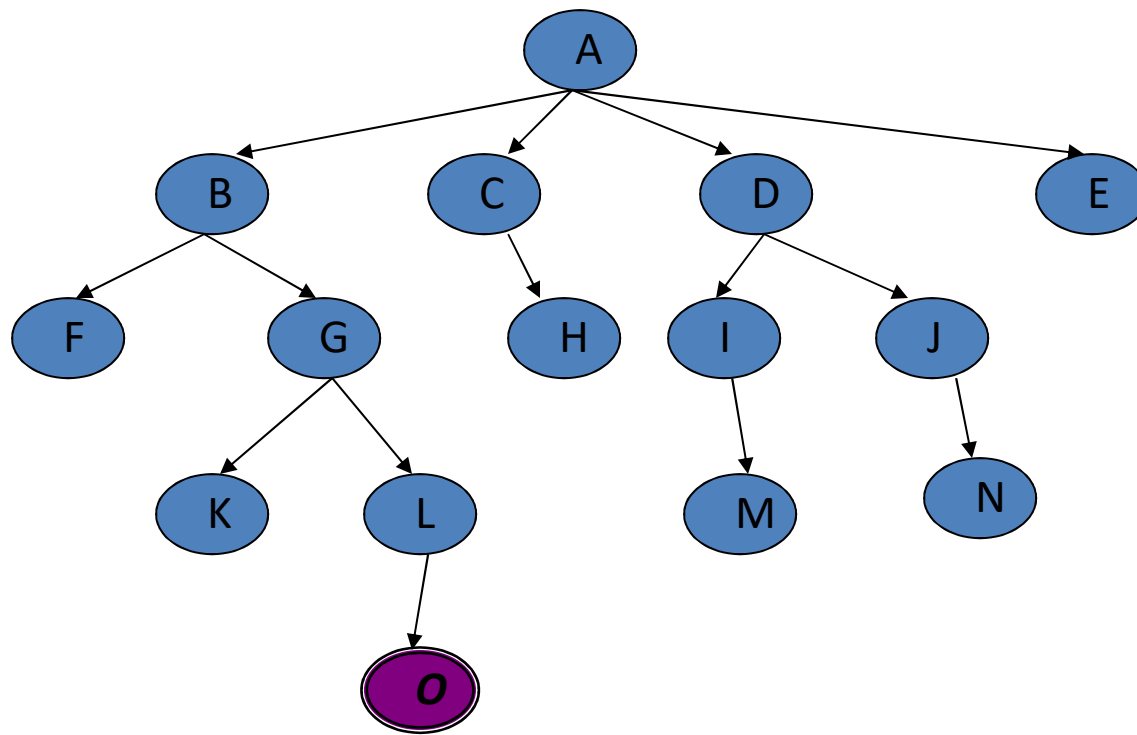


Main idea: Expand all nodes at depth (i) before expanding nodes at depth (i + 1)
Level-order Traversal.

Implementation: Use of a First-In-First-Out queue (FIFO). Nodes visited first are expanded first. Enqueue nodes in FIFO (first-in, first-out) order.

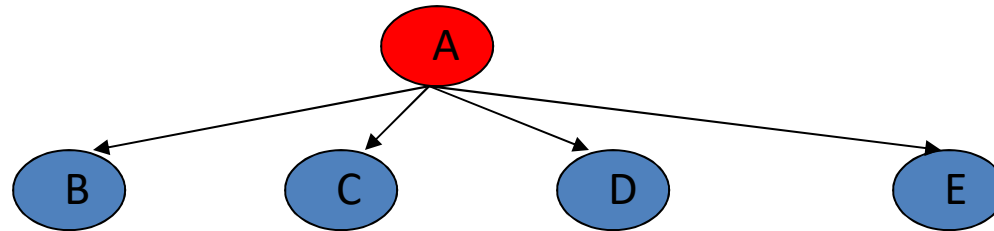
Breadth First Search

Given the following state space (tree search), give the sequence of visited nodes when using BFS (assume that the node **O** is the goal state):



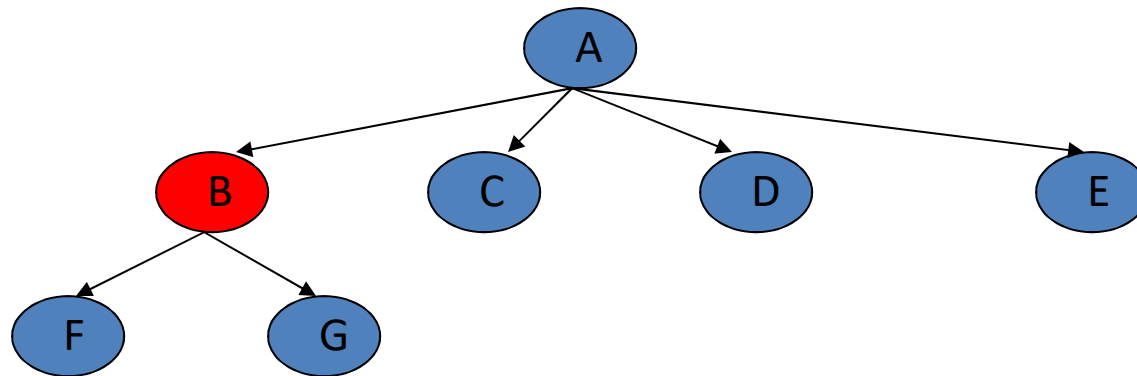
Breadth First Search

- A,



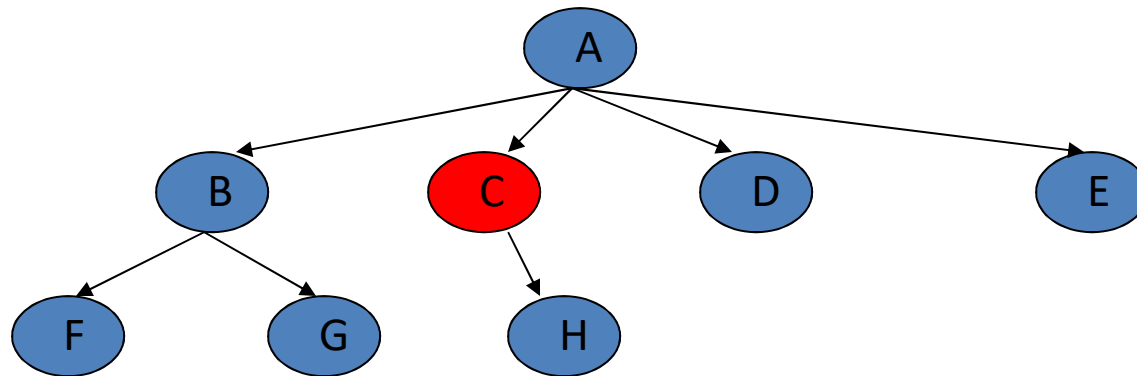
Breadth First Search

- A,
- B,



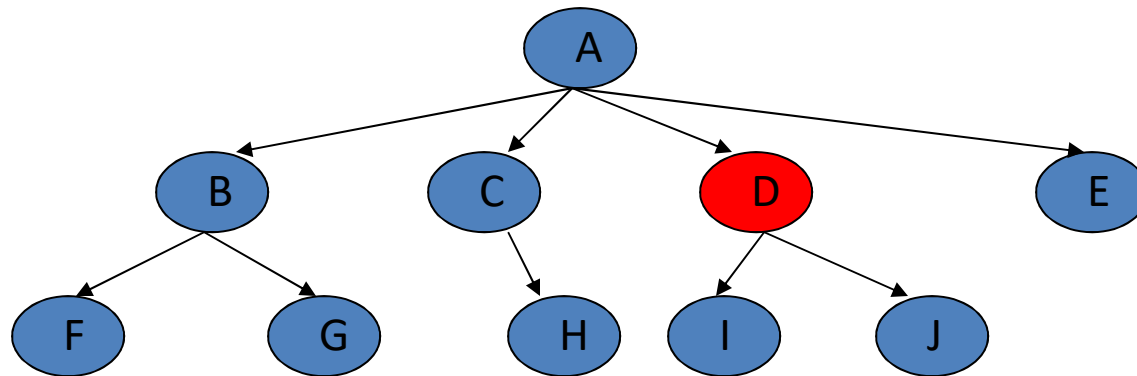
Breadth First Search

- A,
- B,C



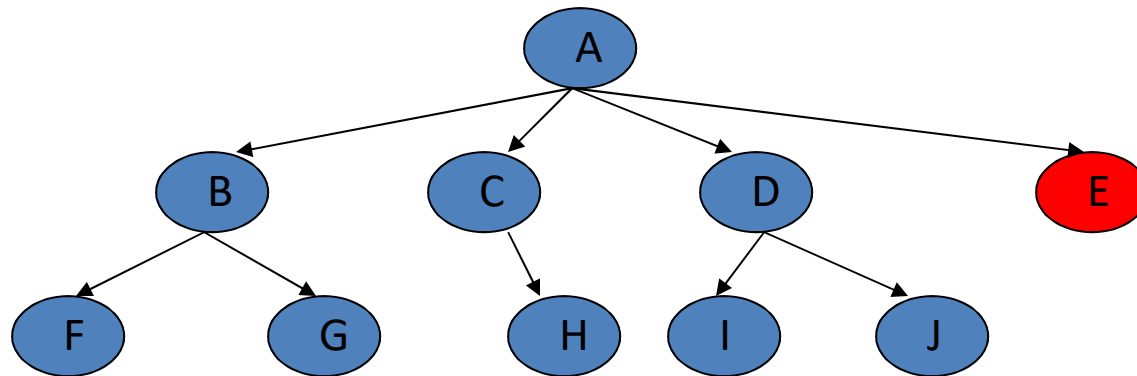
Breadth First Search

- A,
- B,C,D



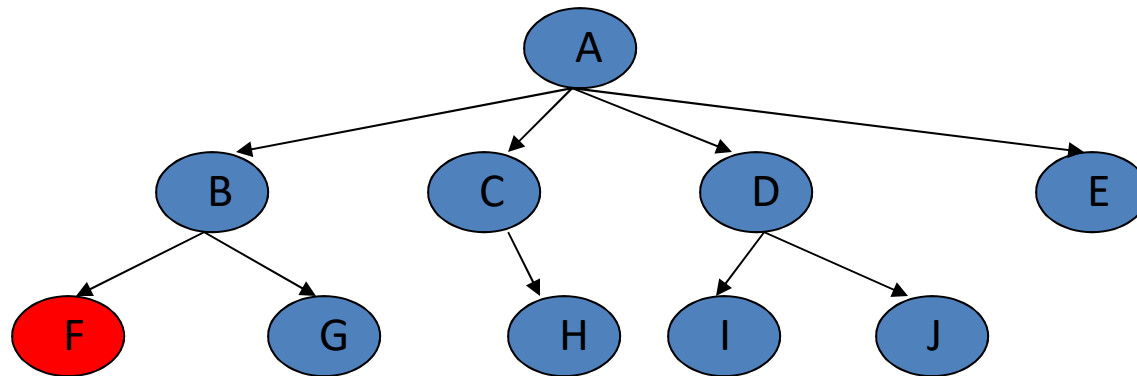
Breadth First Search

- A,
- B,C,D,E



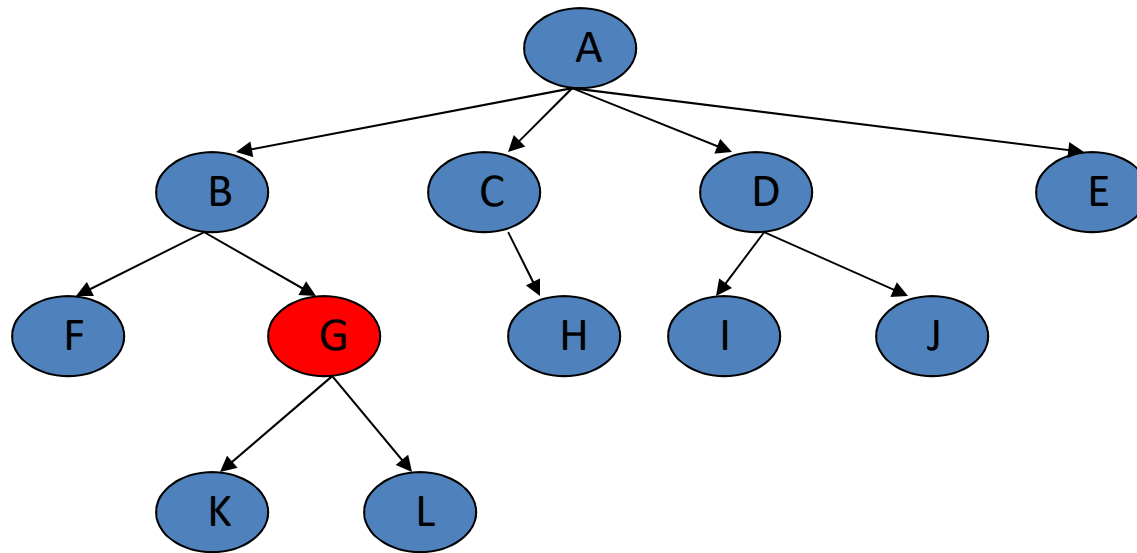
Breadth First Search

- A,
- B,C,D,E,
- F,



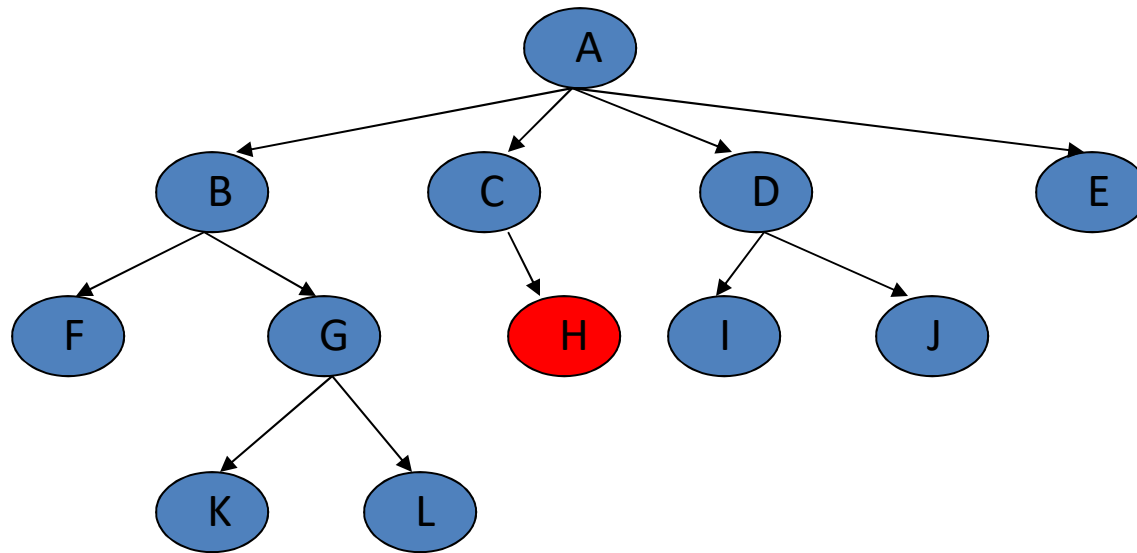
Breadth First Search

- A,
- B,C,D,E,
- F,G



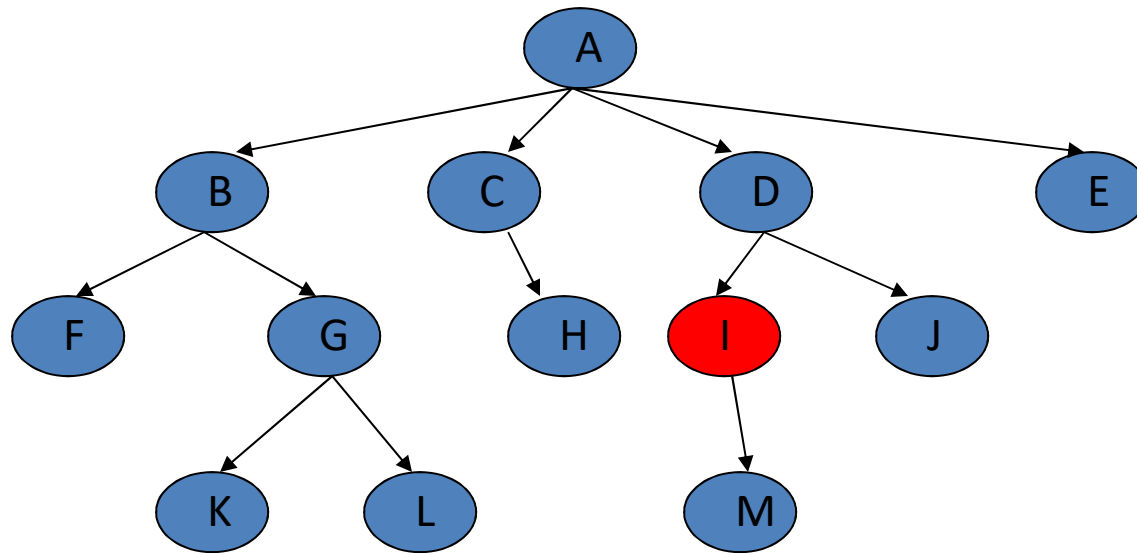
Breadth First Search

- A,
- B,C,D,E,
- F,G,H



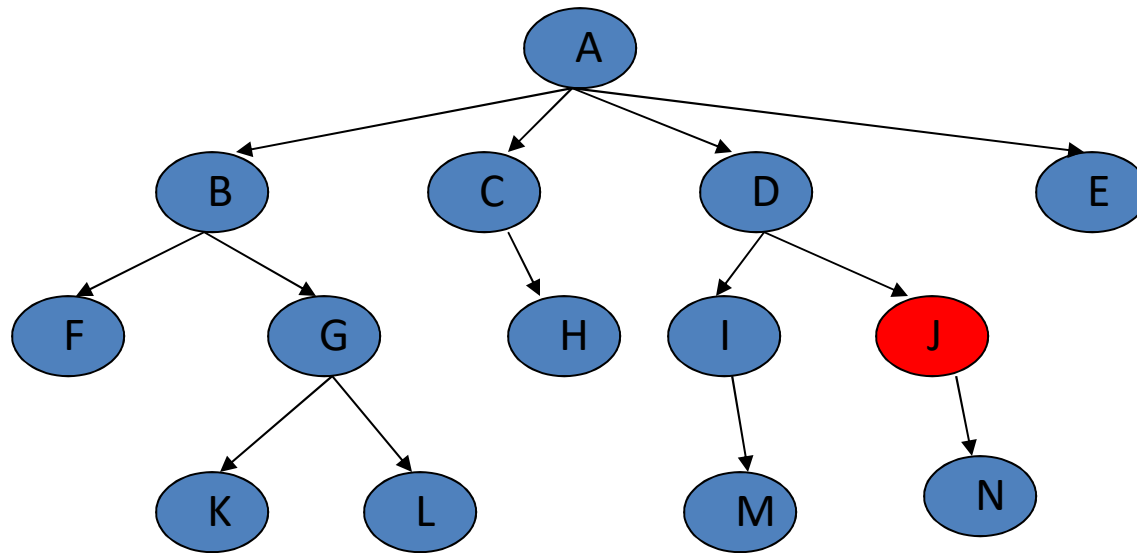
Breadth First Search

- A,
- B,C,D,E,
- F,G,H,I



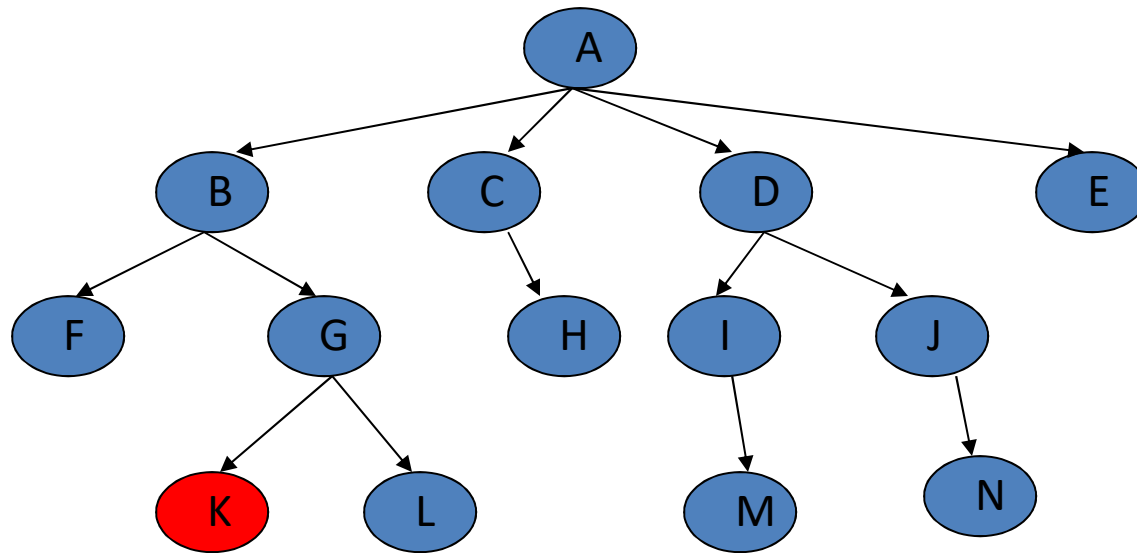
Breadth First Search

- A,
- B,C,D,E,
- F,G,H,I,J,



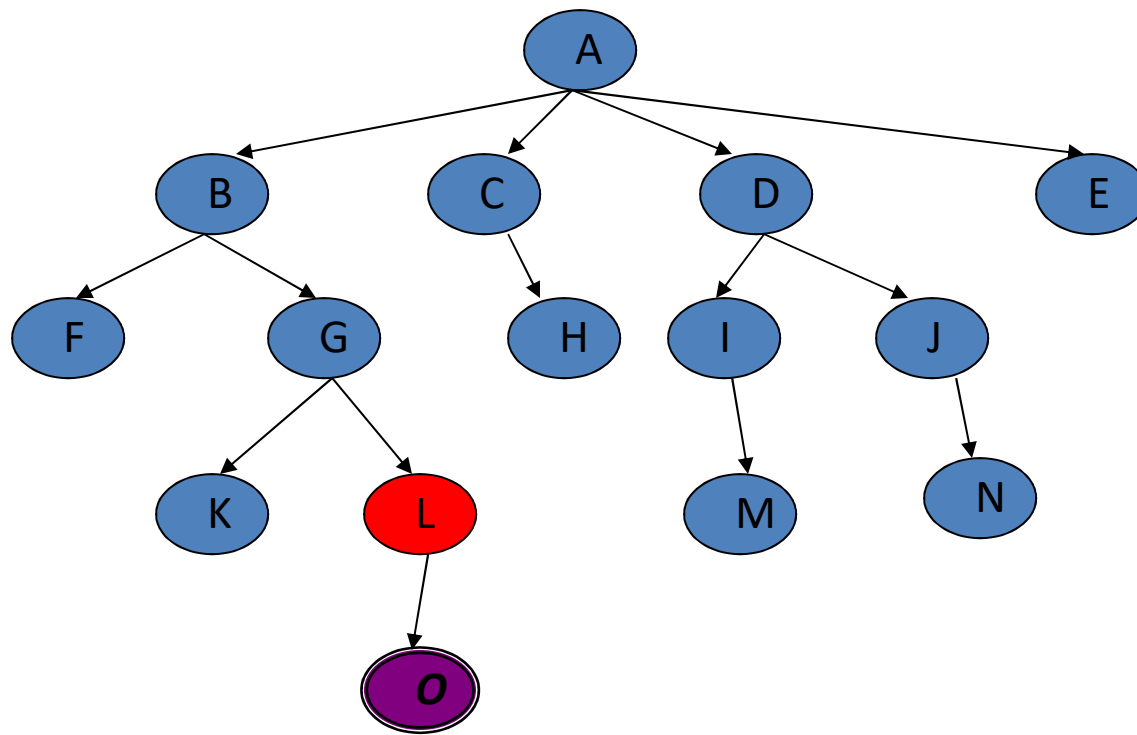
Breadth First Search

- A,
- B,C,D,E,
- F,G,H,I,J,
- K,



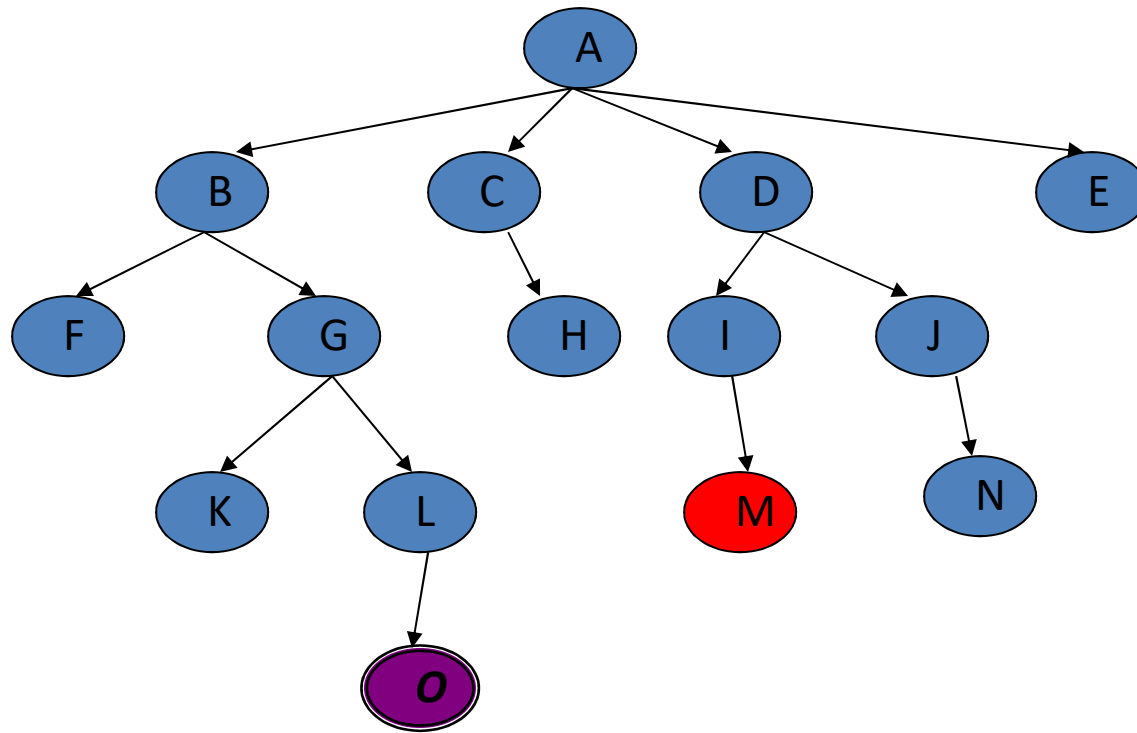
Breadth First Search

- A,
- B,C,D,E,
- F,G,H,I,J,
- K,L



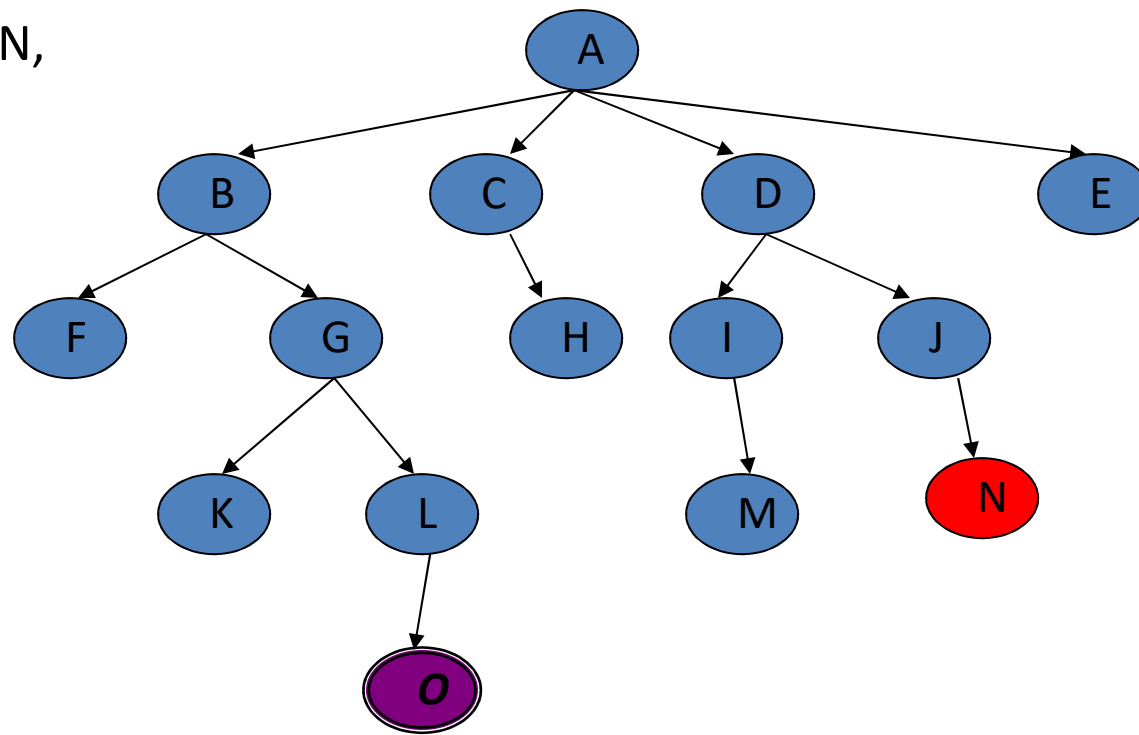
Breadth First Search

- A,
- B,C,D,E,
- F,G,H,I,J,
- K,L, M,



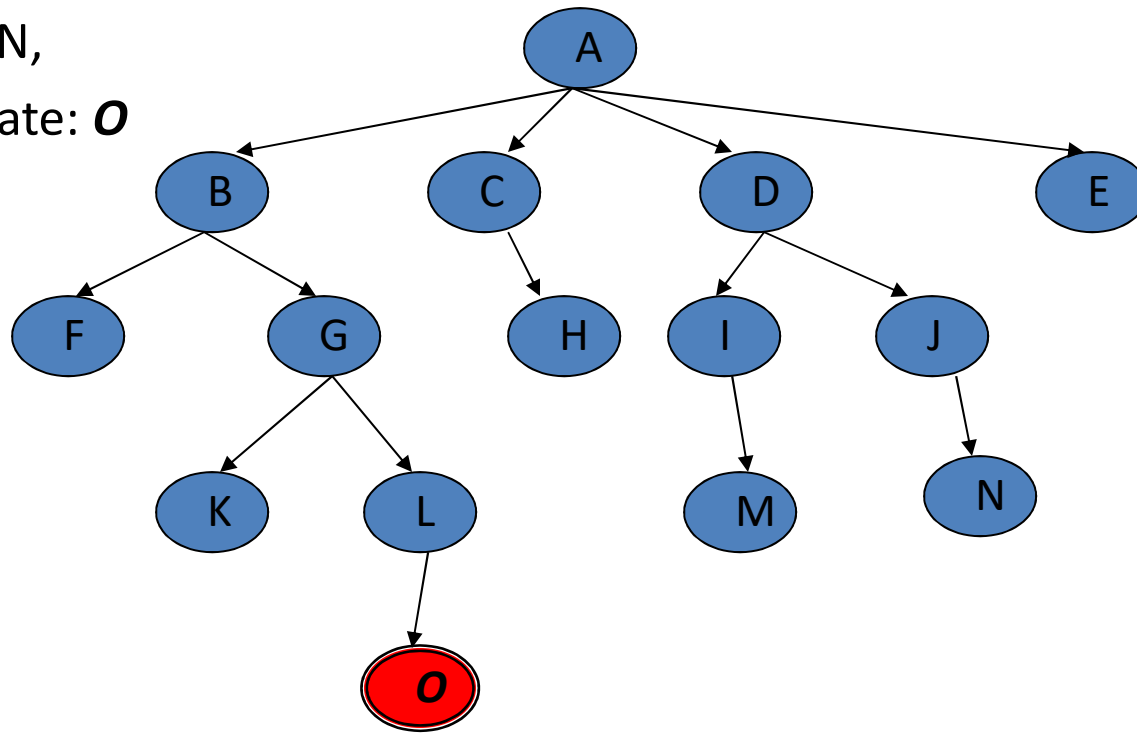
Breadth First Search

- A,
- B,C,D,E,
- F,G,H,I,J,
- K,L, M,N,



Breadth First Search

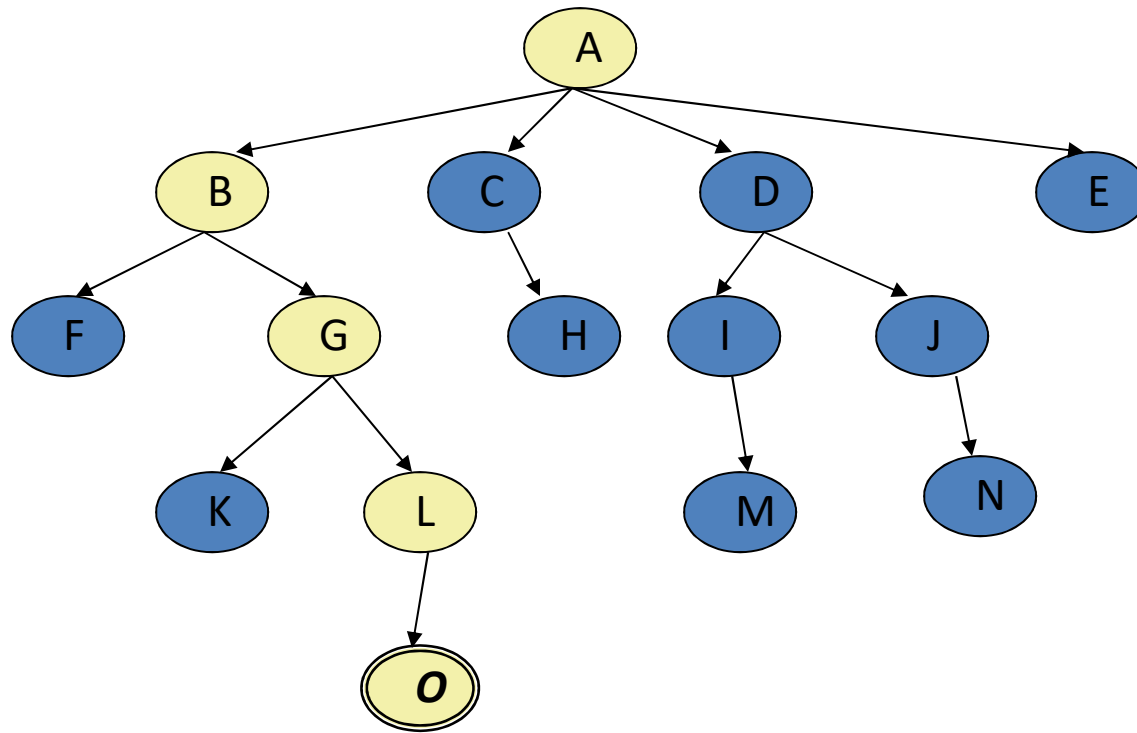
- A,
- B,C,D,E,
- F,G,H,I,J,
- K,L, M,N,
- Goal state: **O**



Breadth First Search

- The returned solution is the sequence of operators in the path:

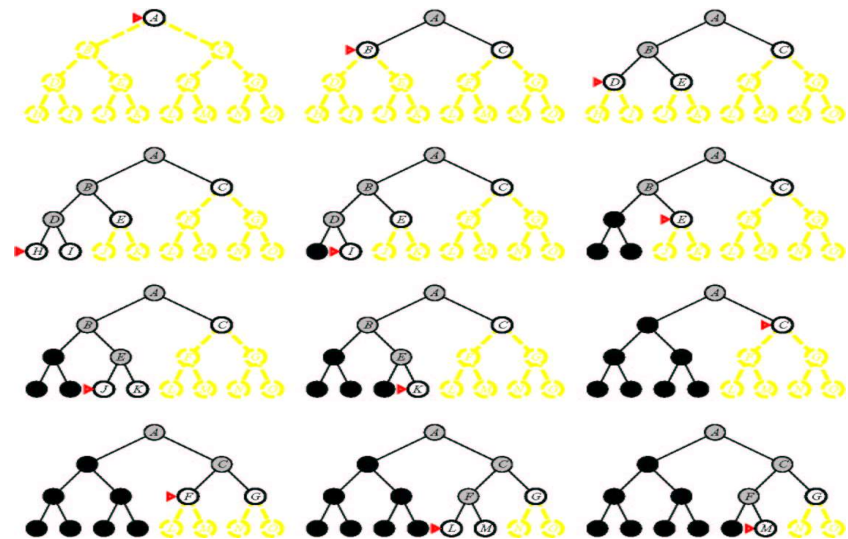
A, B, G, L, O



Depth First Search

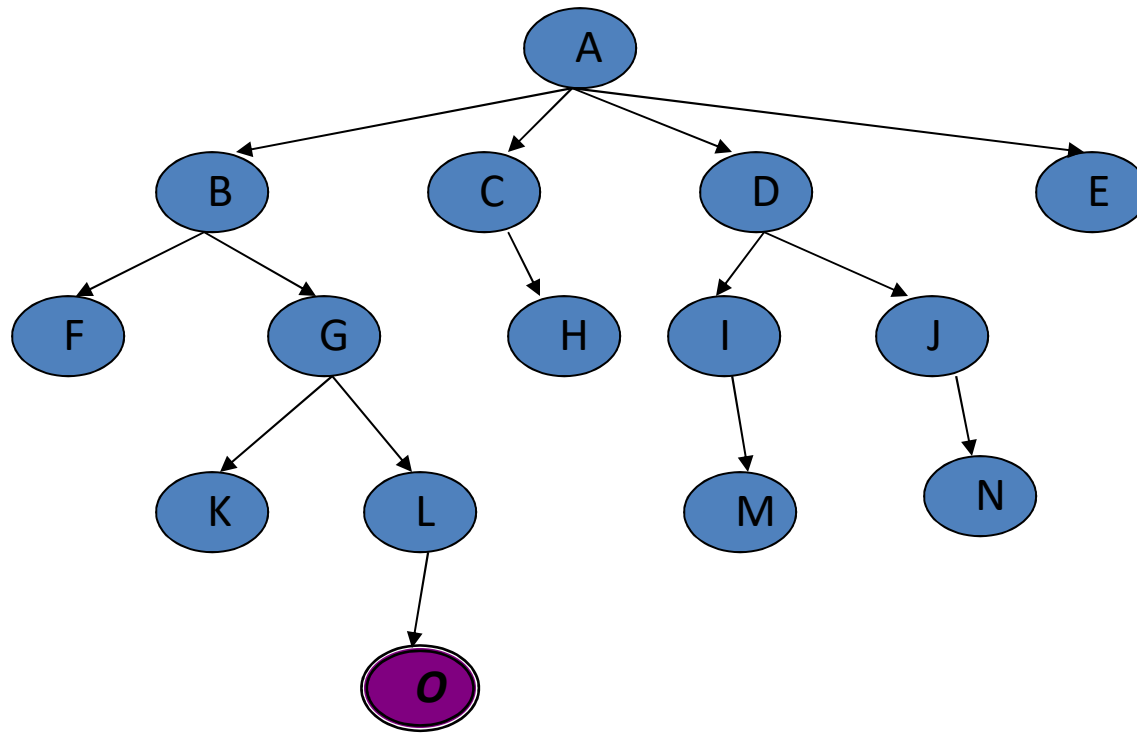
Main idea: Expand node at the deepest level (breaking ties left to right).

Implementation: use of a Last-In-First-Out(LIFO) or stack operation. Enqueue nodes in LIFO (last-in, first-out) order.



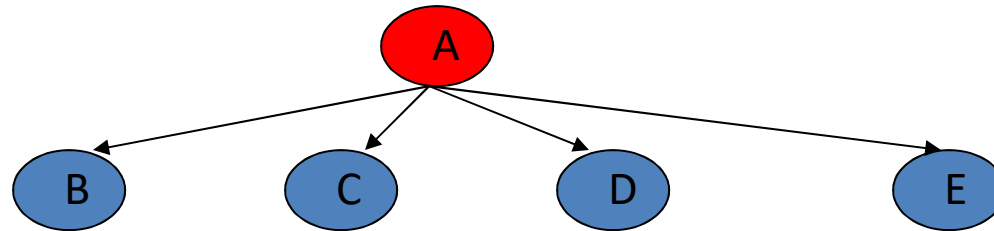
Depth First Search (DFS)

Given the following state space (tree search), give the sequence of visited nodes when using DFS (assume that the node **O** is the goal state):



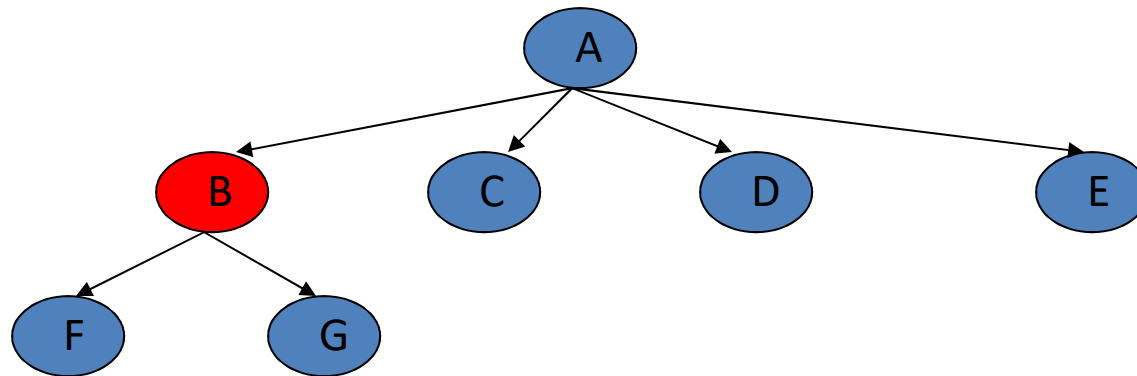
Depth First Search

- A,



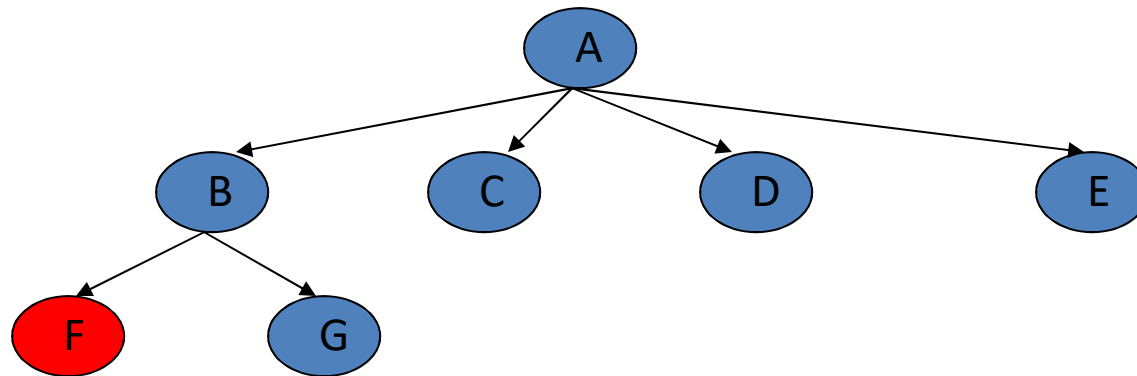
Depth First Search

- A,B,



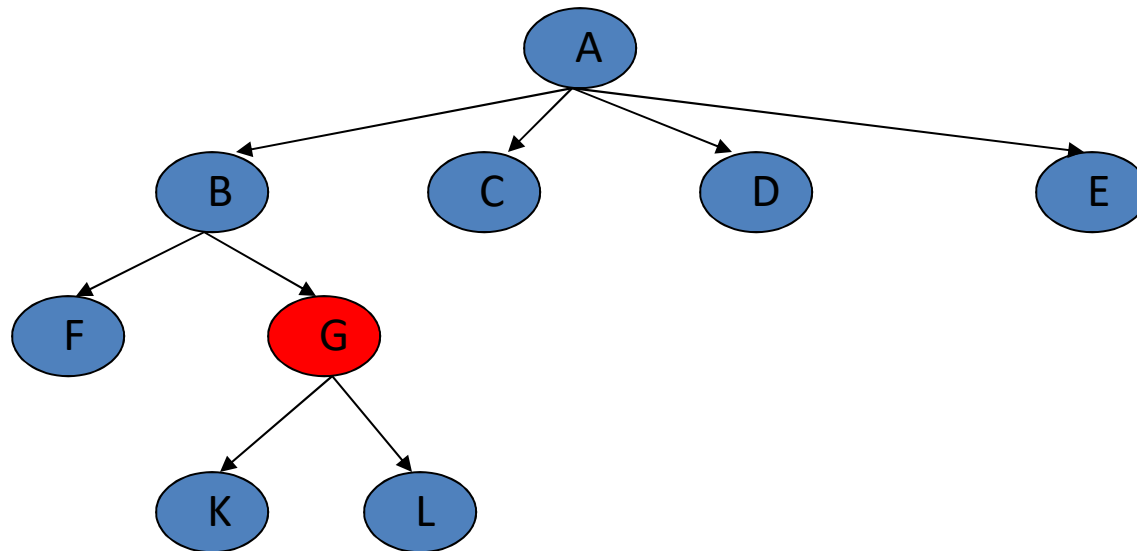
Depth First Search

- A,B,F,



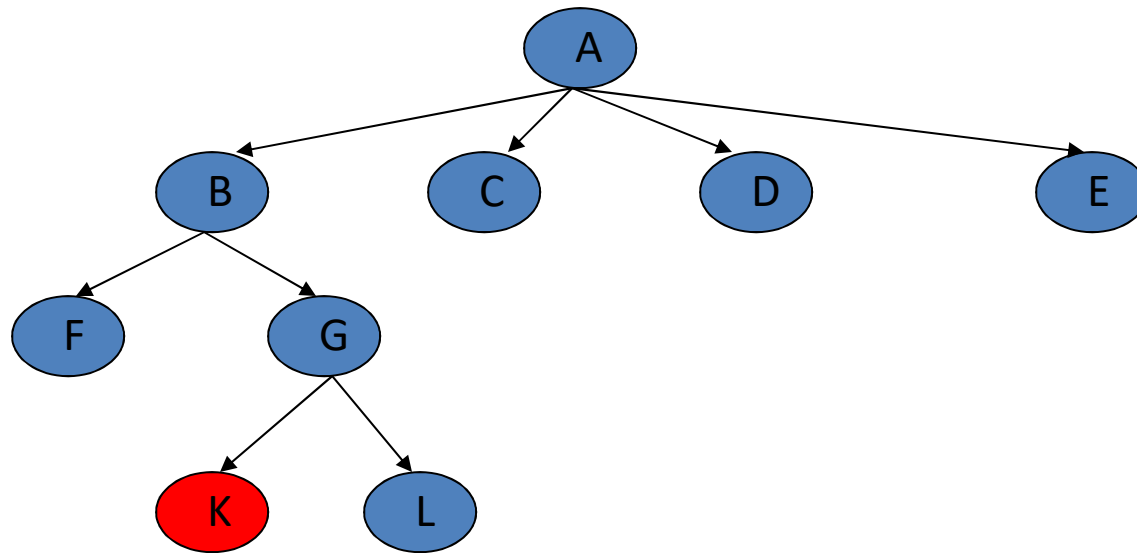
Depth First Search

- A,B,F,
- G,



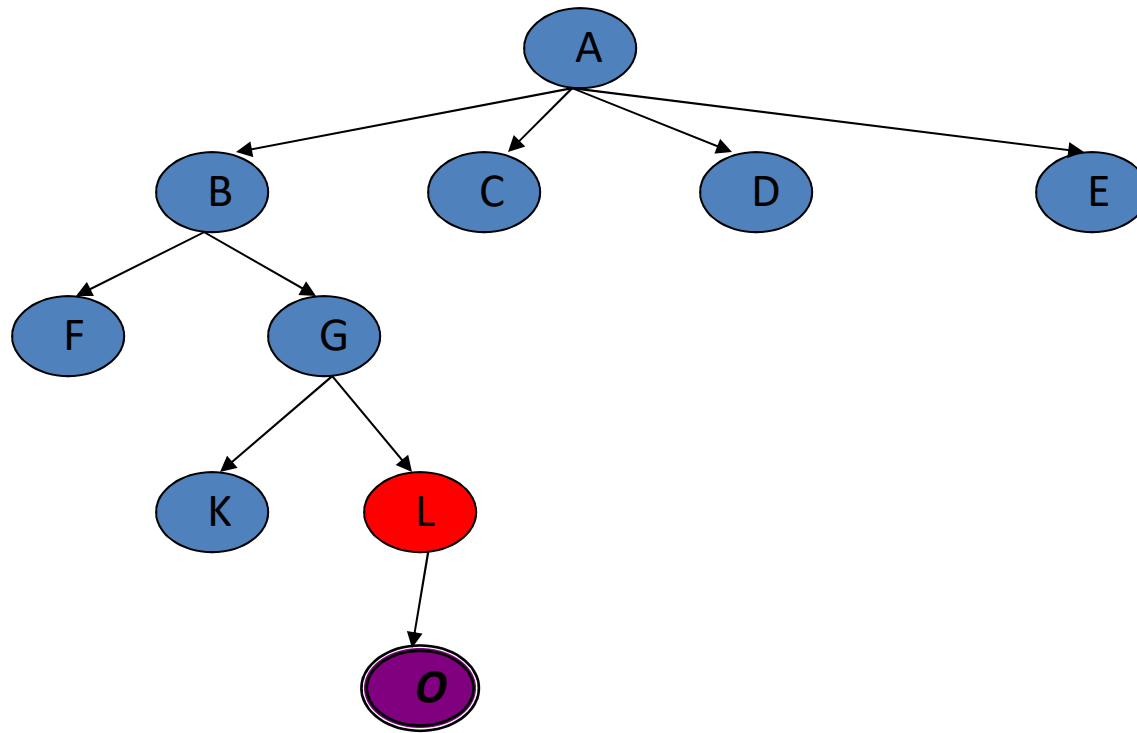
Depth First Search

- A,B,F,
- G,K,



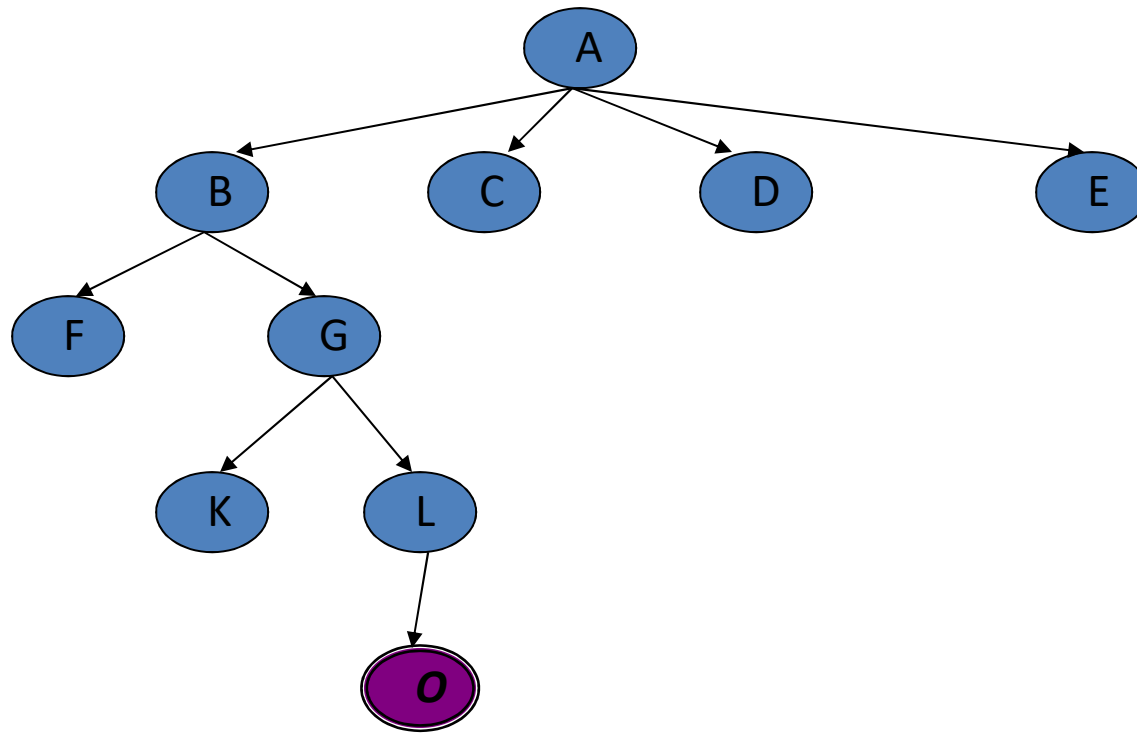
Depth First Search

- A,B,F,
- G,K,
- L,



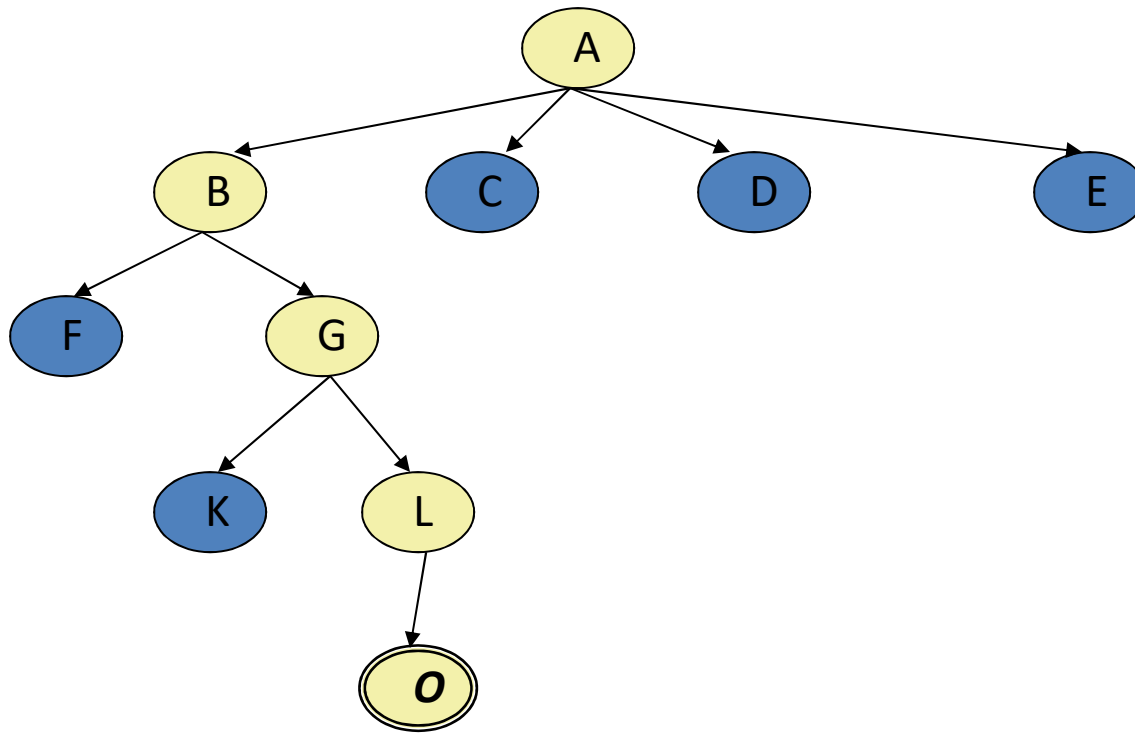
Depth First Search

- A,B,F,
- G,K,
- L, O: *Goal State*



Depth First Search

The returned solution is the sequence of operators in the path:
A, B, G, L, O



Depth-Limited Search (DLS)

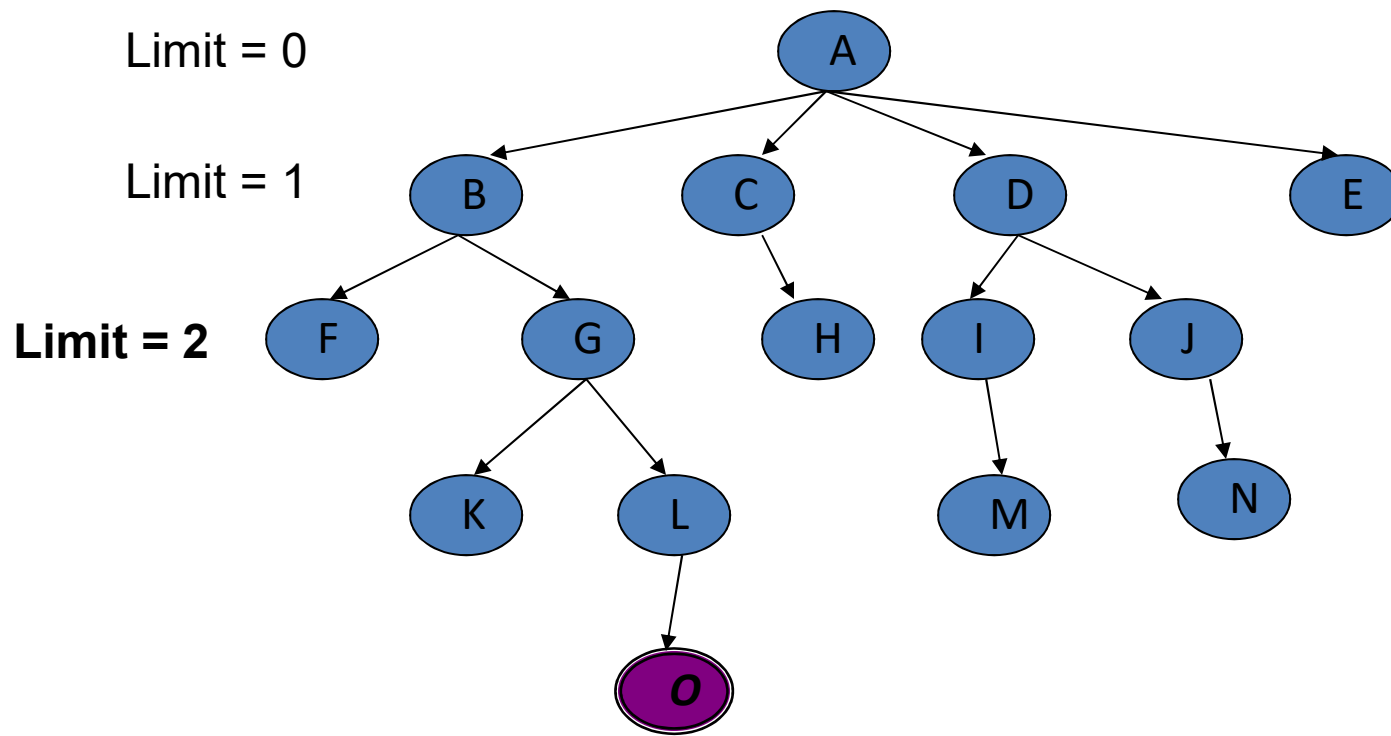
Main idea: *Expand node at the deepest level, but limit depth to L .*

Implementation:

Enqueue nodes in LIFO (last-in, first-out) order. But limit depth to L

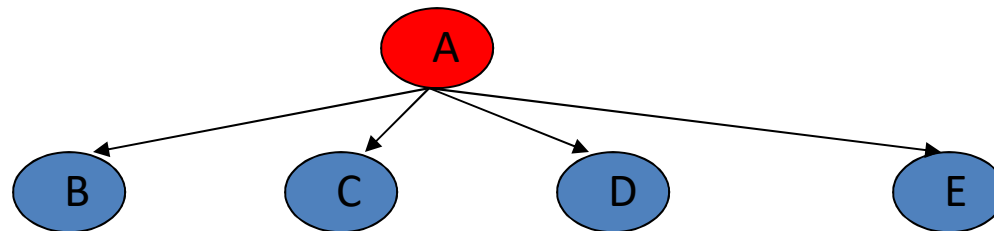
Depth-Limited Search (DLS)

Given the following state space (tree search), give the sequence of visited nodes when using DLS (Limit = 2):



Depth-Limited Search (DLS)

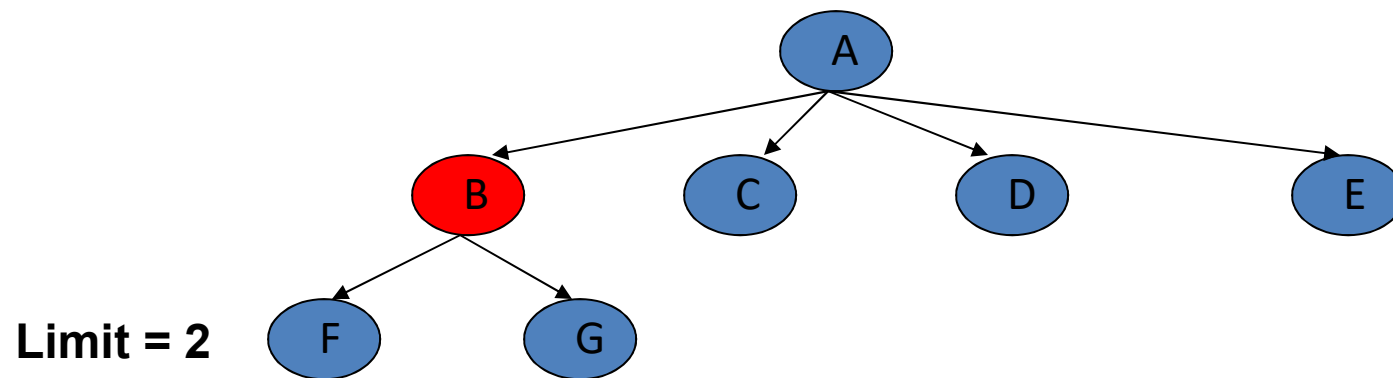
- A,



Limit = 2

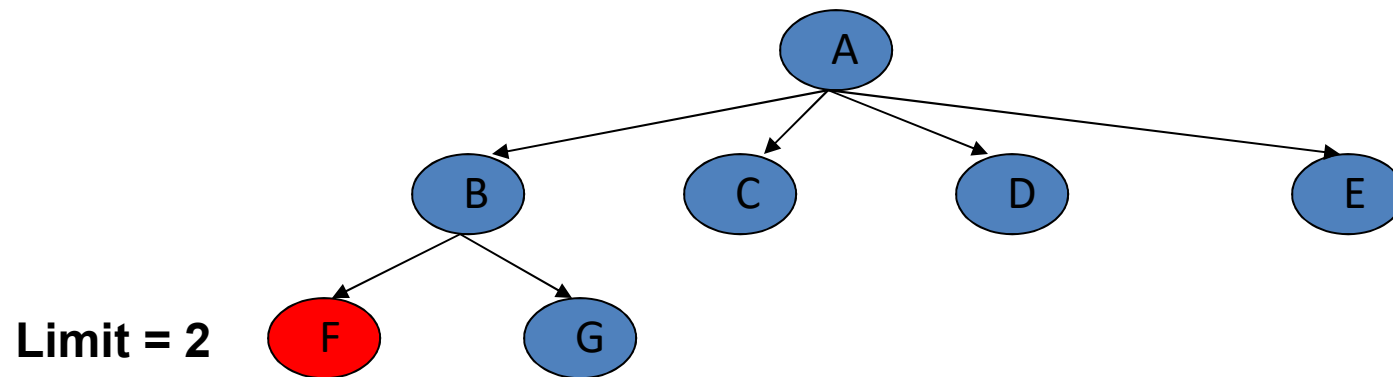
Depth-Limited Search (DLS)

- A,B,



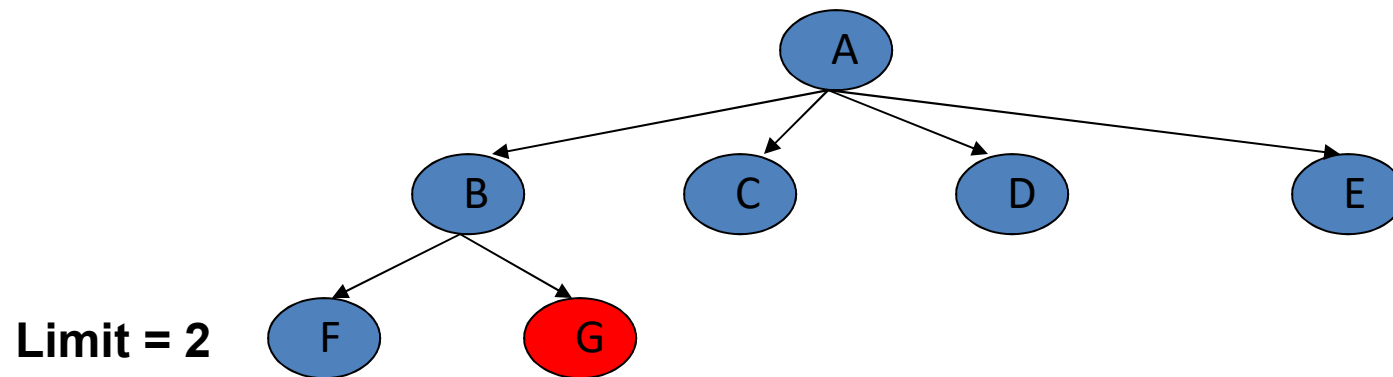
Depth-Limited Search (DLS)

- A,B,F,



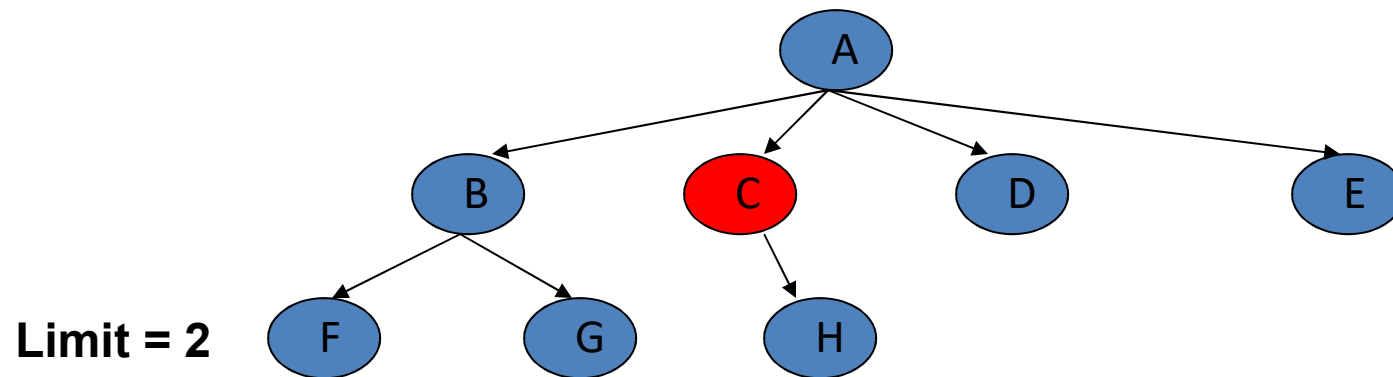
Depth-Limited Search (DLS)

- A,B,F,
- G,



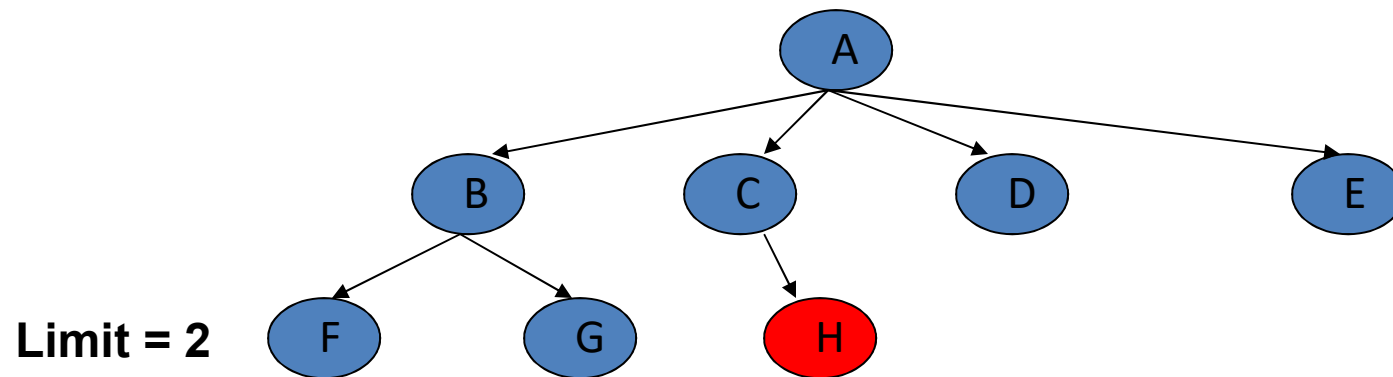
Depth-Limited Search (DLS)

- A,B,F,
- G,
- C,



Depth-Limited Search (DLS)

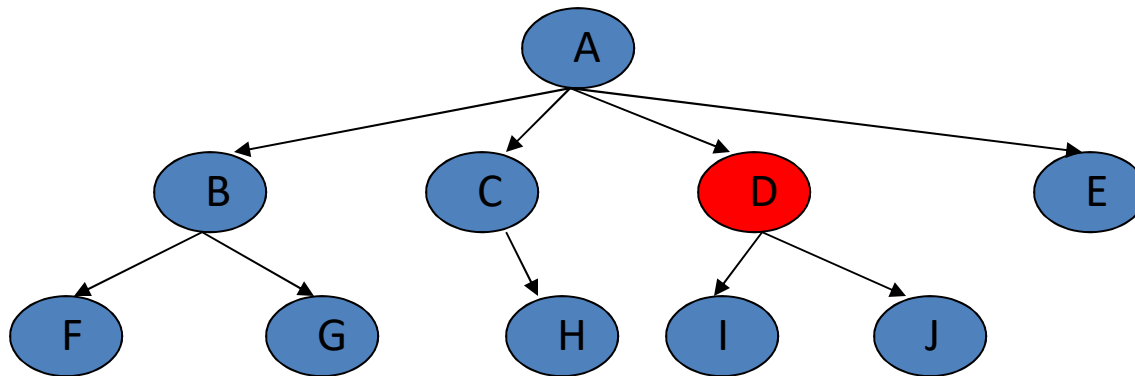
- A,B,F,
- G,
- C,H,



Depth-Limited Search (DLS)

- A,B,F,
- G,
- C,H,
- D,

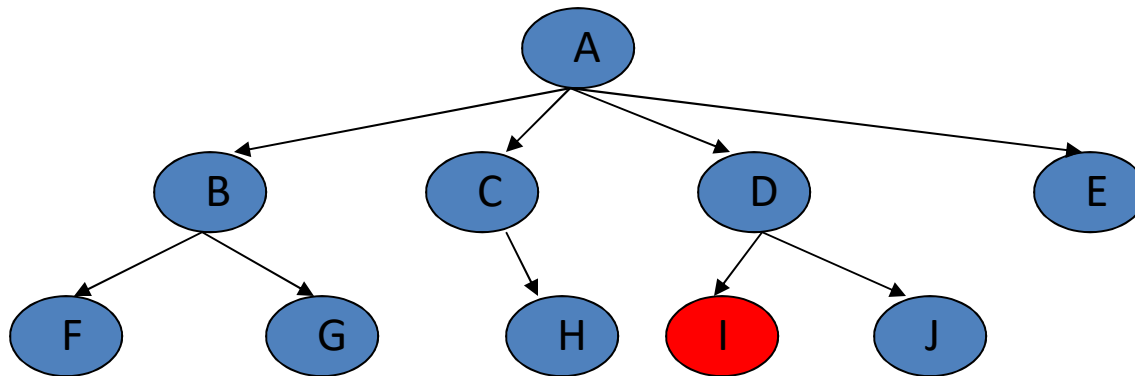
Limit = 2



Depth-Limited Search (DLS)

- A,B,F,
- G,
- C,H,
- D,I

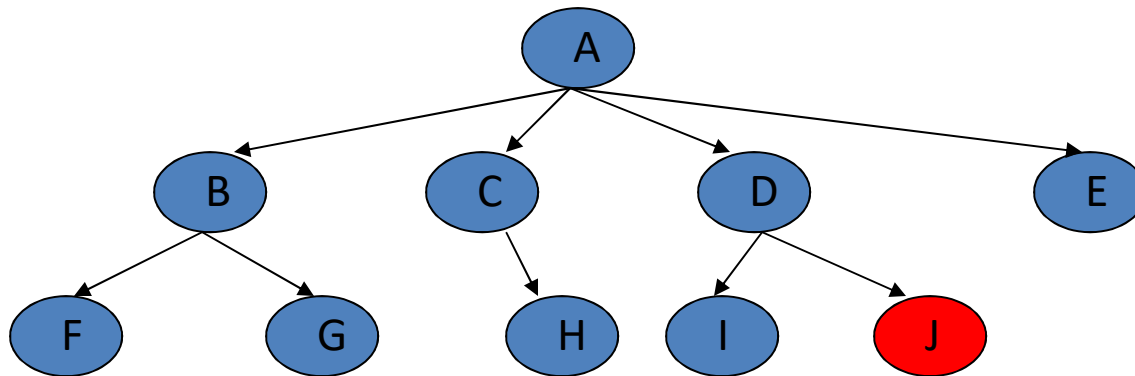
Limit = 2



Depth-Limited Search (DLS)

- A,B,F,
- G,
- C,H,
- D,I
- J,

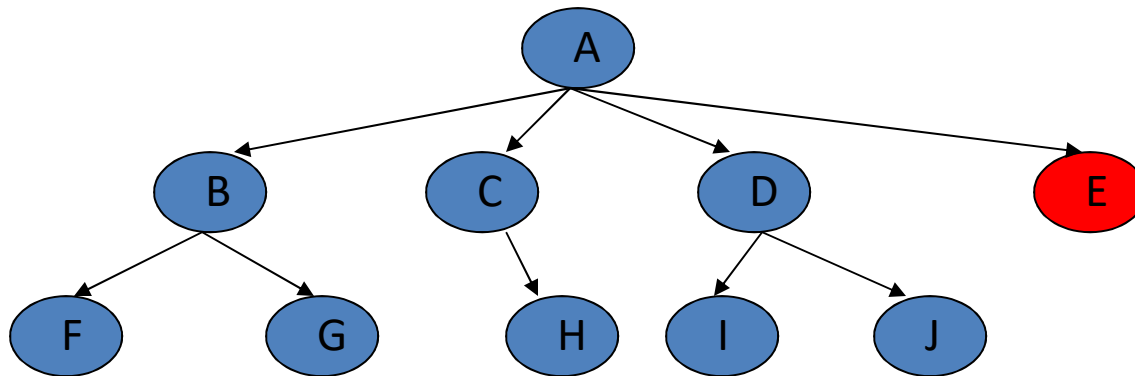
Limit = 2



Depth-Limited Search (DLS)

- A,B,F,
- G,
- C,H,
- D,I
- J,
- E

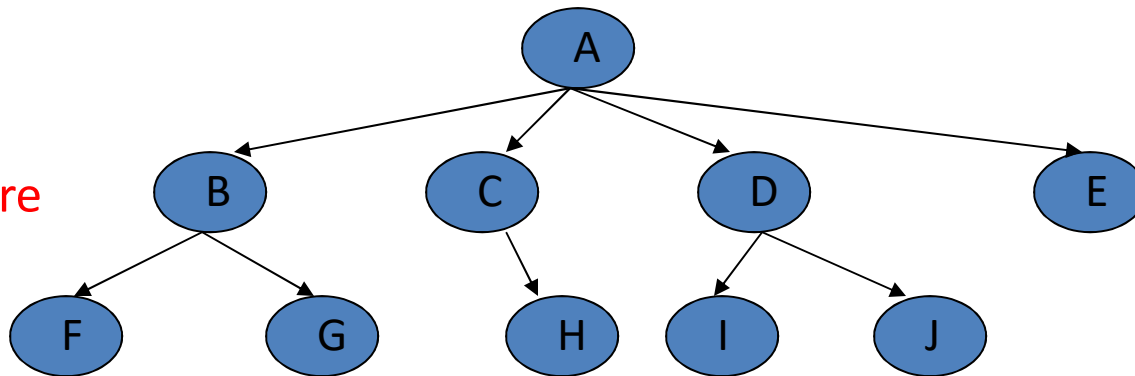
Limit = 2



Depth-Limited Search (DLS)

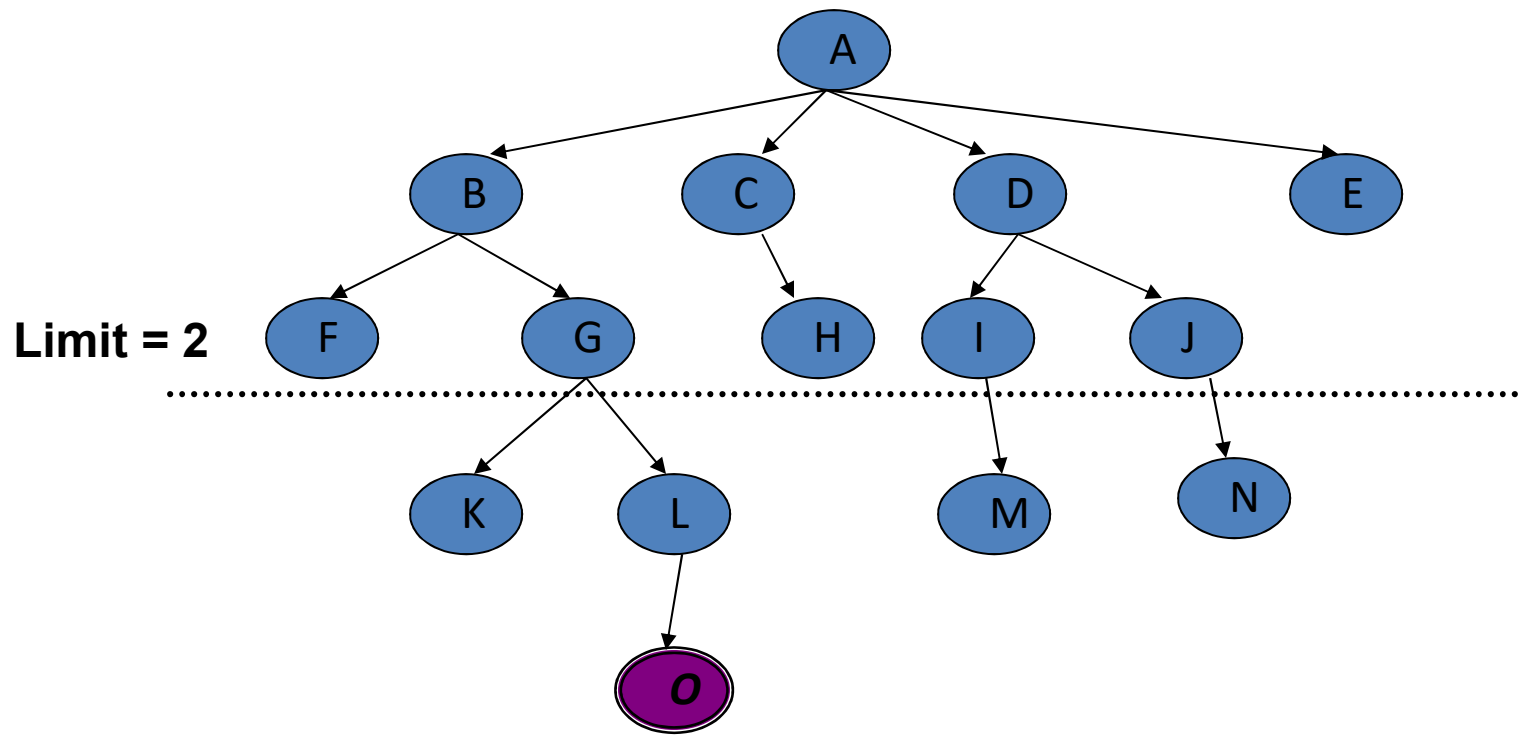
- A,B,F,
- G,
- C,H,
- D,I
- J,
- E, Failure

Limit = 2



Depth-Limited Search (DLS)

- DLS algorithm returns **Failure (no solution)**
- The reason is that the goal is beyond the limit (Limit =2): the goal depth is (d=4)



Basic Search Algorithms

Uninformed Search

Iterative Deepening Search (IDS)

Iterative Deepening Search (IDS)

function ITERATIVE-DEEPENING-SEARCH():

for depth = 0 to infinity **do**

if DEPTH-LIMITED-SEARCH(depth) succeeds

then return its result

end

return failure

Iterative Deepening Search (IDS)

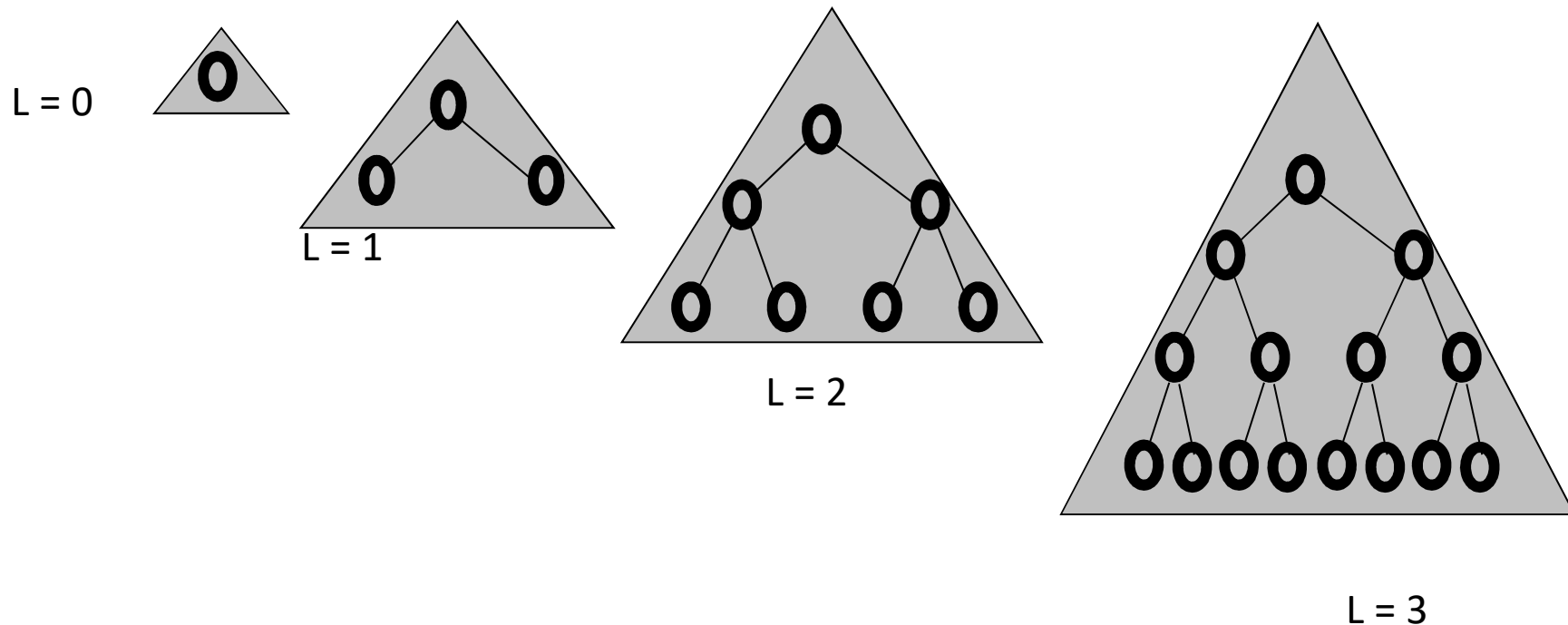
- **Key idea:** Iterative deepening search (IDS) applies DLS repeatedly with increasing depth. It terminates when a solution is found or no solutions exists.
- IDS combines the benefits of BFS and DFS: Like DFS the memory requirements are very modest ($O(bd)$). Like BFS, it is complete when the branching factor is finite.
- The total number of generated nodes is :

$$N(\text{IDS}) = (d)b + (d-1)b^2 + \dots + (1)b^d$$

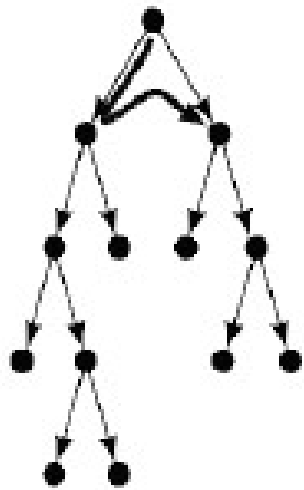
- In general, iterative deepening is the preferred uninformed search method when there is a large search space and the depth of the solution is not known.

Iterative Deepening Search (IDS)

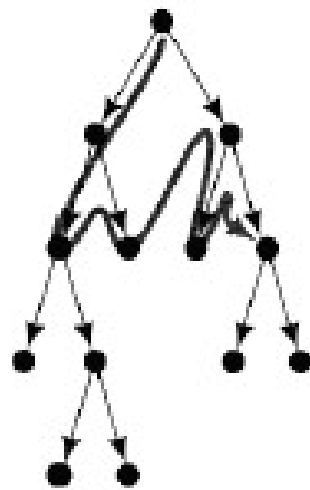
- **Key idea:** Iterative deepening search (IDS) applies DLS repeatedly with increasing depth. It terminates when a solution is found or no solutions exists.



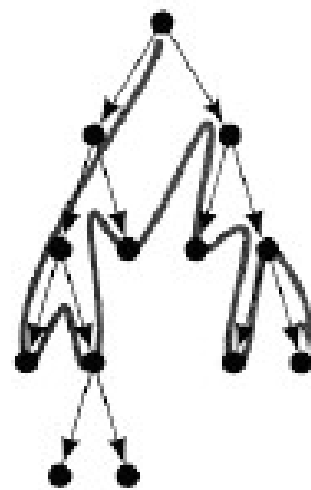
Iterative Deepening Search (IDS)



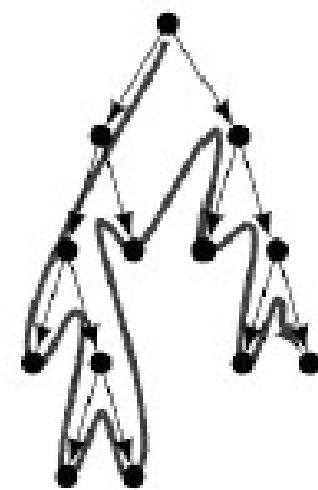
1



2



3

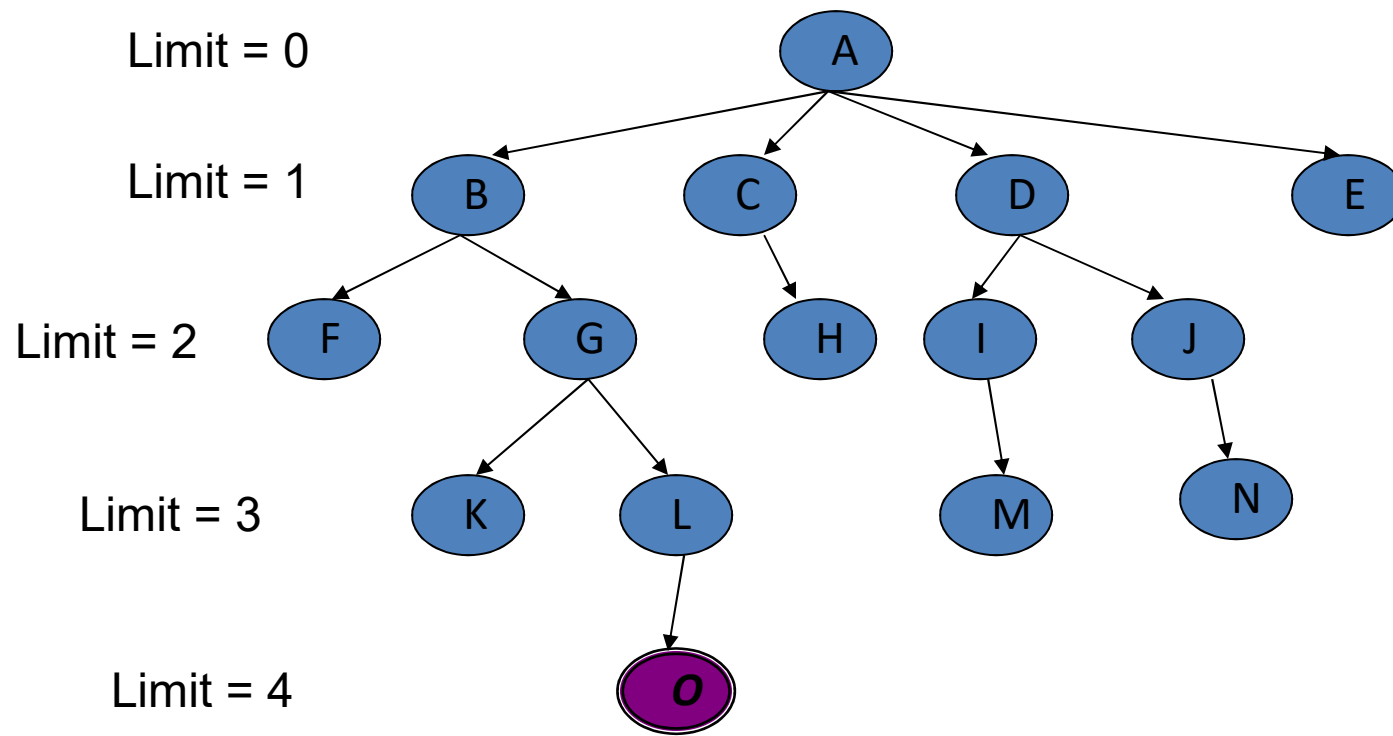


4

Depth bound

Iterative Deepening Search (IDS)

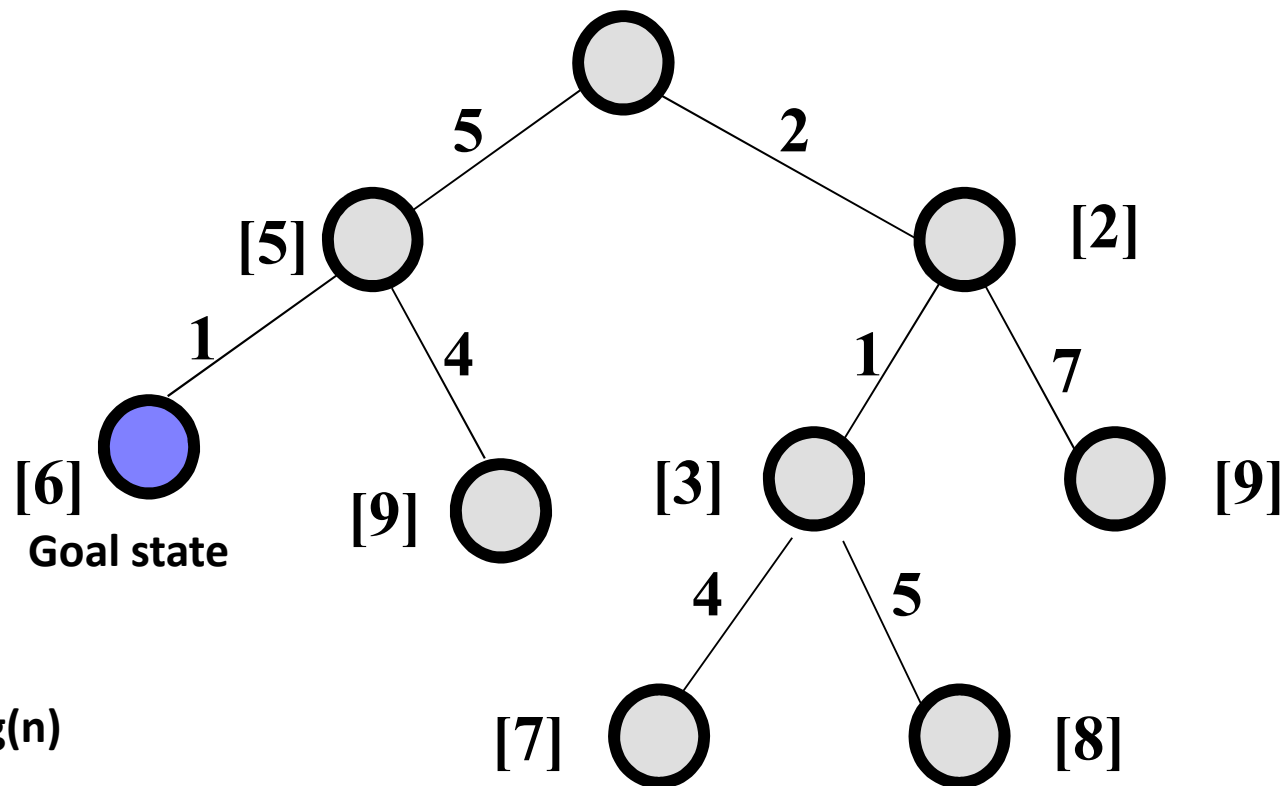
Given the following state space (tree search), give the sequence of visited nodes when using IDS:



Uniform Cost Search (UCS)

- **Main idea:** *Expand the cheapest node. Where the cost is the path cost $g(n)$.*
- **Implementation:**
Enqueue nodes in order of cost $g(n)$.
QUEUEING-FN:- insert in order of increasing path cost.
Enqueue new node at the appropriate position in the queue so that we dequeue the cheapest node.

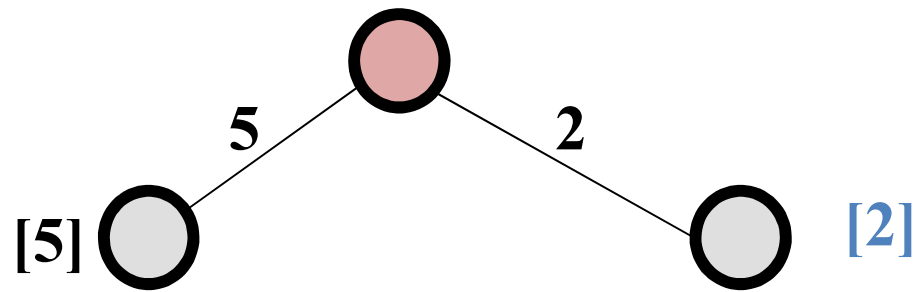
Uniform Cost Search (UCS)



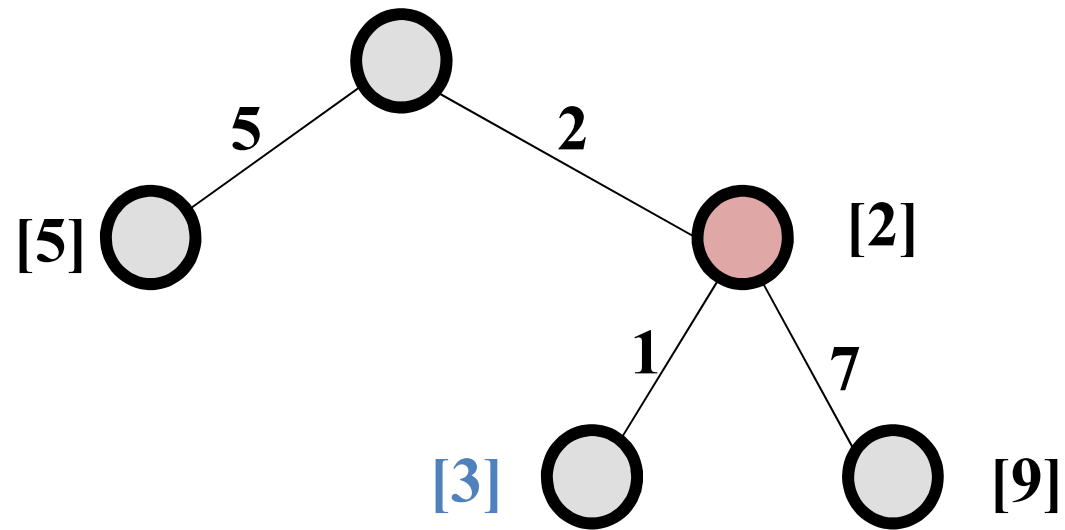
$[x] = g(n)$

path cost of node n

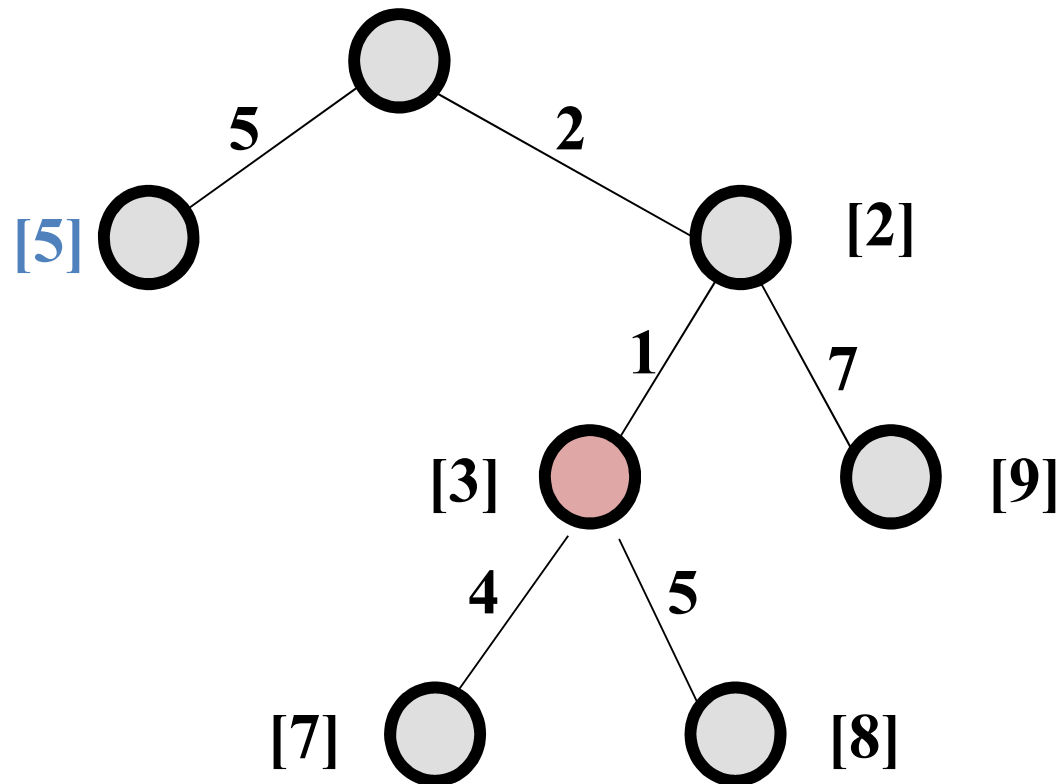
Uniform Cost Search (UCS)



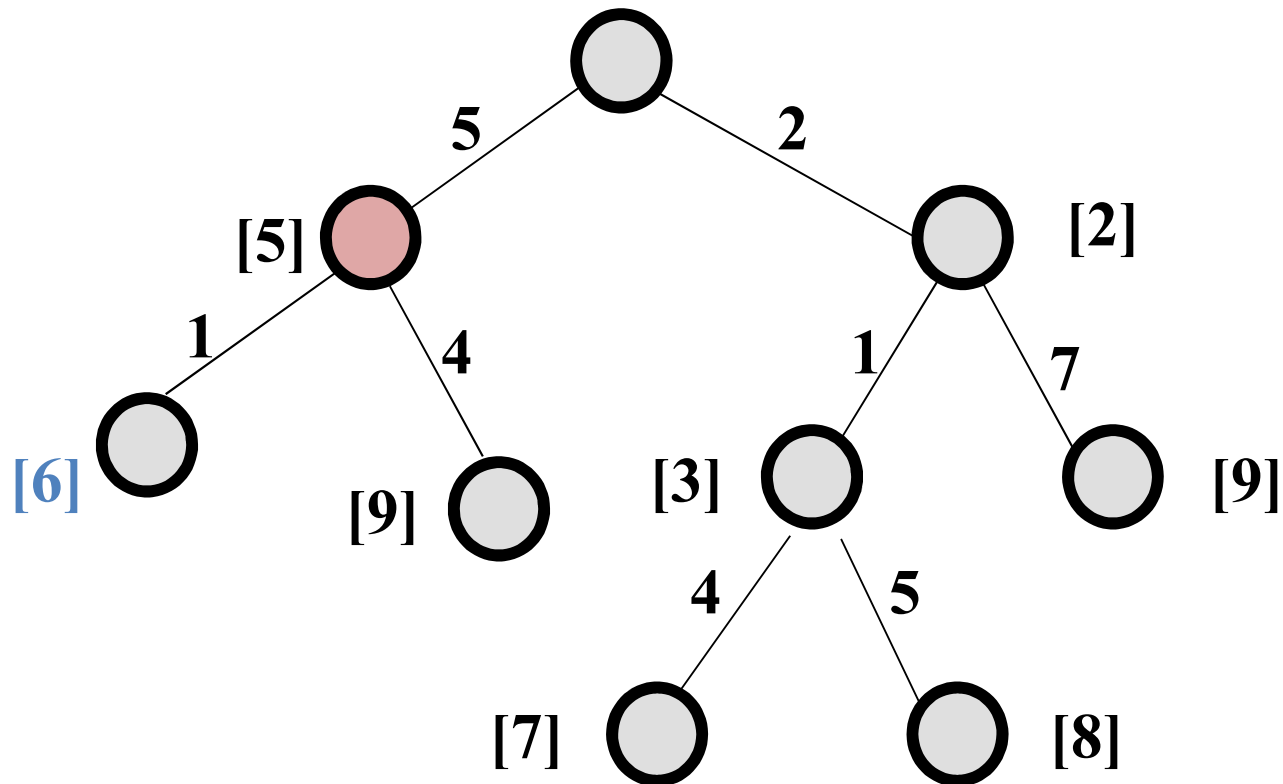
Uniform Cost Search (UCS)



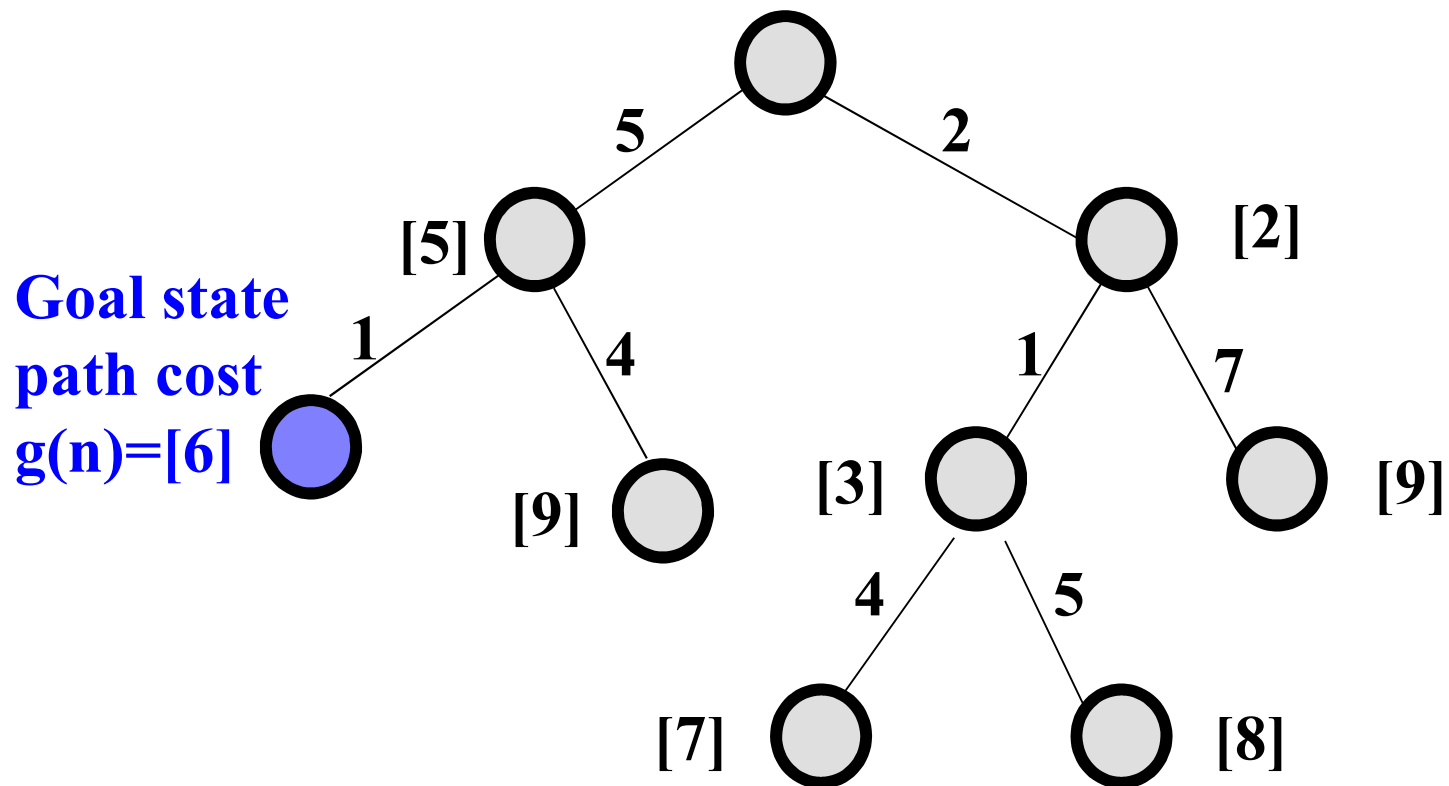
Uniform Cost Search (UCS)



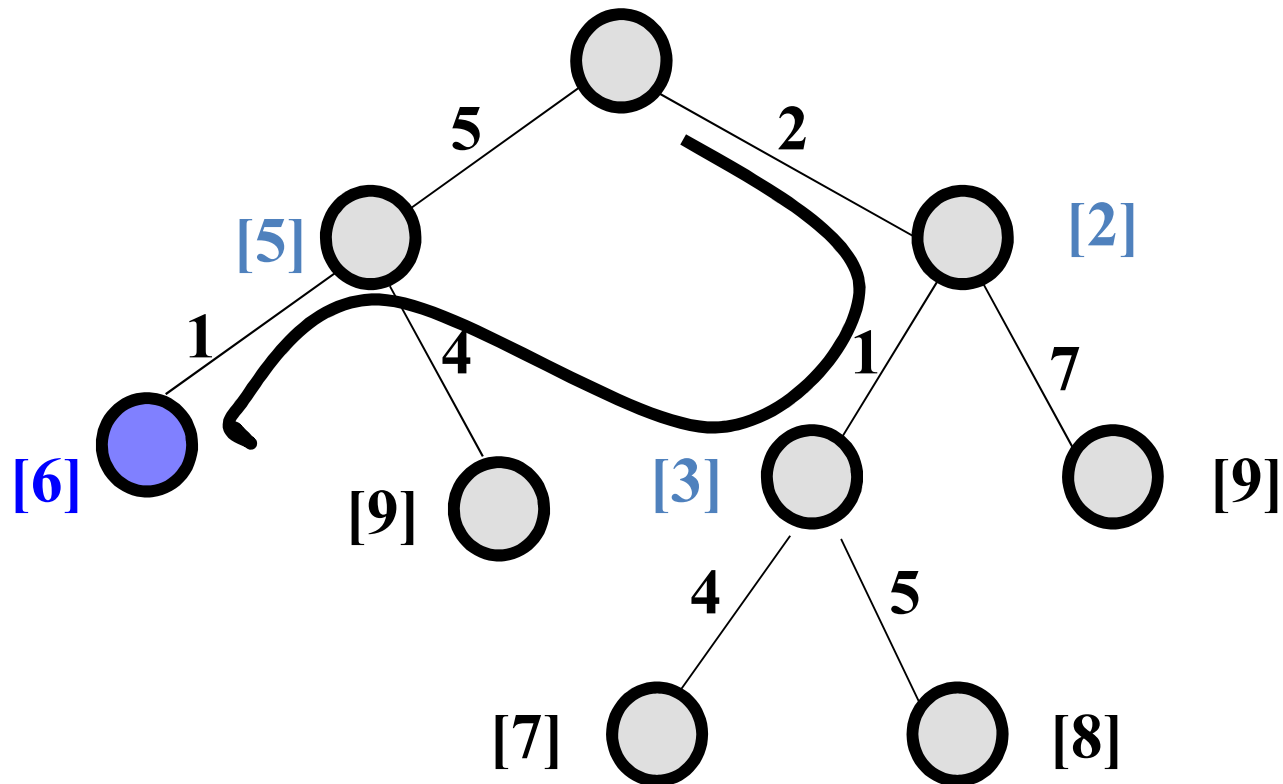
Uniform Cost Search (UCS)



Uniform Cost Search (UCS)



Uniform Cost Search (UCS)



Conclusion of The Chapter

- Conclusion #1
 - BFS implement FIFO (queue) for the search operation
- Conclusion #2
 - DFS implement LIFO (stack) for the search operation
- Conclusion #3
 - DLS implement DFS with level limitation
- Conclusion #4
 - IDS implement DLS with level increment
- Conclusion #5
 - UCS use cheapest cost node to expand