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NUMERICAL METHODS & OPTIMISATION

Part I: Numerical Differentiation

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Numerical Differentiation

By Raihana Edros

<http://ocw.ump.edu.my/course/view.php?id=608¬ifieditingon=1>

Chapter Description

- Aims
 - Apply numerical methods in solving engineering problem and optimisation
- Expected Outcomes
 - Calculate the area under the curve by using different differentiation and integration methods
 - Apply the different differentiation and integration methods to solve engineering problems
- References
 - Steven C. Chapra and Raymond P. Canale (2009), Numerical Methods for Engineers, McGraw-Hill, 6th Edition

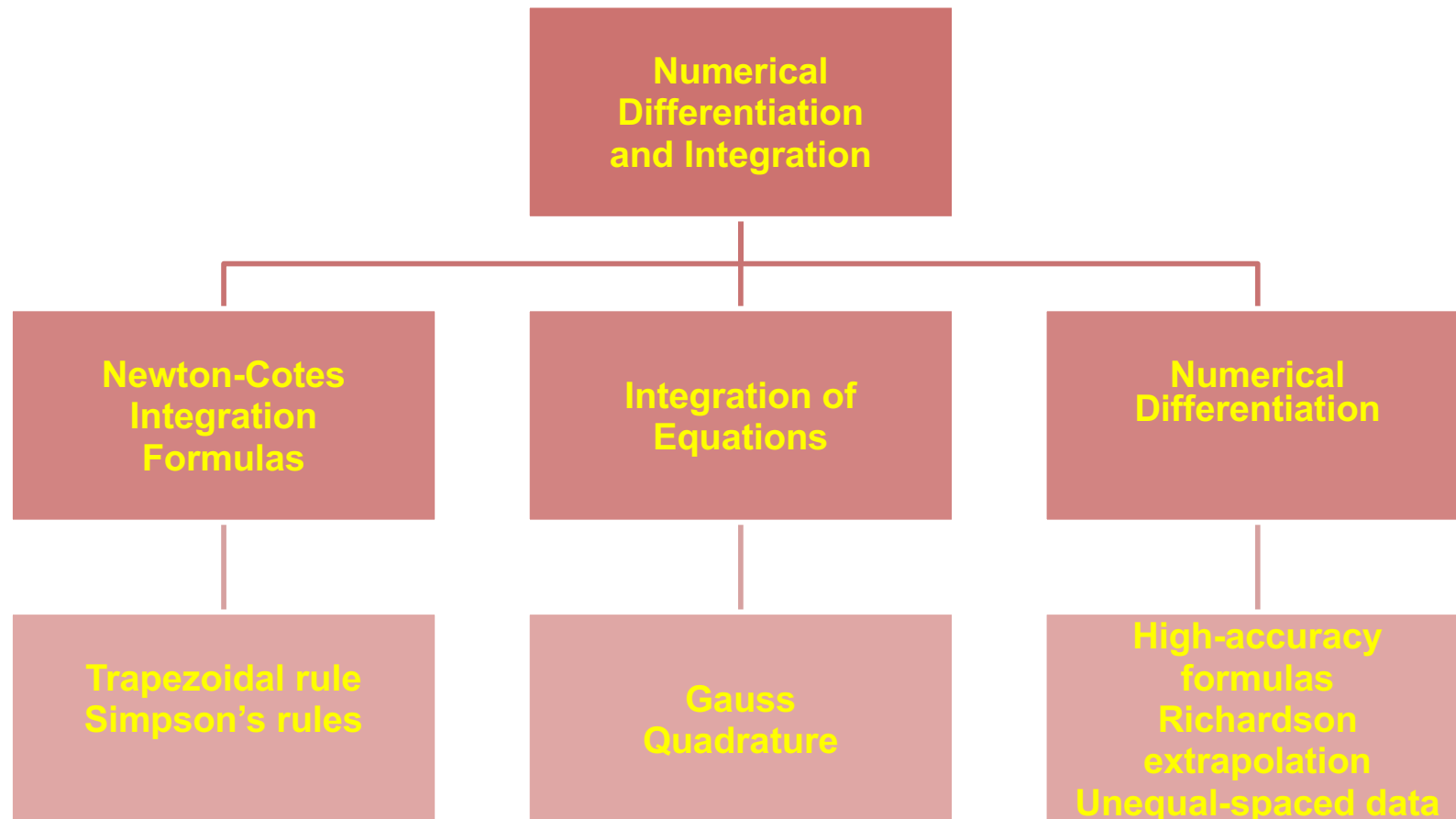


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Overview



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Numerical methods for differentiation and integration

- The function to be differentiated or integrated will typically be in one of the following three forms:
 - A simple continuous function such as polynomial, an exponential, or a trigonometric function.
 - A complicated continuous function that is difficult or impossible to differentiate or integrate directly.
 - A tabulated function where values of x and $f(x)$ are given at a number of discrete points, as is often the case with experimental or field data.



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New Cotes Integration Formulas

- Most common numerical integration schemes
- Based on strategy of replacing a complicated function or tabulated data with an approximating function

$$I = \int_a^b f(x) dx \cong \int_a^b f_n(x) dx$$

$$f_n(x) = a_0 + a_1x + \cdots + a_{n-1}x^{n-1} + a_nx^n$$

- n is the order of polynomial
 - a) First order polynomial is used as approximation
 - b) Parabola for the same purpose



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The Trapezoidal Rule

- The *Trapezoidal rule* is the first of Newton-Cotes integration formulas, for cases in which the polynomial is **first order**:

$$I = \int_a^b f(x)dx \cong \int_a^b f_1(x)dx$$

- The area under curve is an estimate of $f(x)$ between the limits of a and b :

$I \cong \text{width} \times \text{average height}$

$$I = (b - a) \left[\frac{f(a) + f(b)}{2} \right]$$



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The Multiple Application of Trapezoidal Rule

- One way to improve the accuracy of the trapezoidal rule is to divide the integration interval from a to b into n number of segments and apply the method to each segment.
- The areas of individual segments can then be added to yield the integral for the entire interval.

$$h = \frac{b-a}{n} \quad a = x_0 \quad b = x_n$$

$$I = \int_{x_0}^{x_1} f(x)dx + \int_{x_1}^{x_2} f(x)dx + \cdots + \int_{x_{n-1}}^{x_n} f(x)dx$$



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The Simpson's Rule

- A more accurate estimation of an integral can be obtained if a higher-order polynomial is used to connect the points.
- The formulas that result from taking the integrals under such polynomials are called *Simpson's rules*.

Simpson's 1/3 Rule

- Results when a **second-order Lagrange** interpolating polynomial is used.

$$I \cong (b-a) \left[\frac{f(x_0) + 4f(x_1) + f(x_2)}{6} \right]$$

$$E_a = -\frac{(b-a)^5}{2880} f^{(4)}(\xi)$$



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Multiple Application of Simpson's 1/3 Rule

- Just as the trapezoidal rule, Simpson's rule can be improved by dividing the integration interval into a number of segments of equal width.
- Yields accurate results and considered superior to trapezoidal rule for most applications.
- Can be employed only if the number of segments is even

$$I \cong (b-a) \left[\frac{f(x_0) + 4 \sum_{i=1,3,5}^{n-1} f(x_i) + 2 \sum_{j=2,4,6}^{n-2} f(x_j) + f(x_n)}{3n} \right]$$

$$E_a = -\frac{(b-a)^5}{180n^4} f^{(4)}$$



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Simpson's 3/8 Rule: Cubic

- Results when a **third-order Lagrange** interpolating polynomial is used.
- This polynomial can be fit to four points and integrated to yield:

$$I \cong (b-a) \left[\frac{f(x_0) + 3f(x_1) + 3f(x_2) + f(x_3)}{8} \right]$$

$$E_a = -\frac{(b-a)^5}{6480} f^{(4)}(\xi)$$

Illustration of how Simpson's rule 1/3 and 3/8 can be applied in tandem to handle multiple application with odd numbers of intervals



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Conclusion

- The area under the curve can be estimated by using different differentiation and integration methods
- Different differentiation and integration methods can be applied to solve engineering problems



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