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# NUMERICAL METHODS & OPTIMISATION

## Part II: Modelling & Error Analysis

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Modelling & Error Analysis

By Raihana Edros

<http://ocw.ump.edu.my/course/view.php?id=608&notifyeditingon=1>

# Chapter Description

- Aims
  - Apply numerical methods in solving engineering problem and optimisation
- Expected Outcomes
  - Apply both exact and numerical solutions in mathematical modelling to solve engineering problem.
  - Calculate true percent error, percent relative error & percent tolerance
  - Estimate the truncation error by using Taylor Series
- References
  - Steven C. Chapra and Raymond P. Canale (2009), Numerical Methods for Engineers, McGraw-Hill, 6<sup>th</sup> Edition



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# Approximation & round-off errors

- The numerical methods usually yield estimates that are closed to the exact analytical solution
- Though the values are closed, but they are not the same
- The discrepancy between the two values is called error
- Numerical methods involved approximation to the exact values using mathematical model
- Errors give information on how accurate is the numerical methods used to solve engineering problems



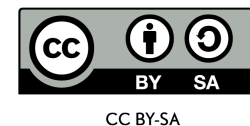
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# Accuracy & precision

- **Errors** can be characterized based on their accuracy & precision
- **Precision:** How closely the individual computed or measured values agree with each other
- **Accuracy:** How closely a computed or measured value agrees to the true value



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# Error definitions

- Error definitions:

- **Truncation errors**: when approximations are used to represent exact mathematical procedures (e.g.: Taylor series)
- **Round-off errors**: when numbers having limited significant errors are used to represent exact numbers
- For both types:

$$\text{True} = \text{approximation} + \text{error} \quad E_t = \text{true} - \text{approximation}$$

- $E_t$  is the true error  $\text{True fractional relative error} = \frac{\text{true error}}{\text{true value}}$

$$\text{True percent relative error}, \varepsilon_t = \frac{\text{true error}}{\text{true value}} \times 100\%$$



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## Error definitions (cont'd)

- In most of engineering problems, the true value remains unknown – error has to be estimated in the absence of the true value
- Certain numerical methods use iterative approaches to compute answer where a present approximation is made on the basis of a previous approximation
- The approximation error is given by:

$$\varepsilon_a = \frac{\text{current approximation} - \text{previous approximation}}{\text{current approximation}} \times 100\%$$

- $\varepsilon_a$  can be either positive or negative value; rather, an absolute value  $|\varepsilon_a|$



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# Error definitions (cont'd)

- The iteration will continue until:

$$|\varepsilon_a| < \varepsilon_S$$

where  $\varepsilon_S$  is the prespecified acceptable percent tolerance and can be determined using:

$$\varepsilon_S = (0.5 \times 10^{2-n})\%$$

where  $n$  is the significant figures



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# Round-off errors

- Originate from the fact that computers retain only a fixed number of significant figures
- Therefore, the numbers can not be represented exactly by the computer
- The discrepancy introduced by omission of significant figures is called round-off errors
- Computer representation of numbers:
  - Integer representation
  - Floating-point representation



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# Round-off errors (cont'd)

- Number systems:
  - A convention for representing quantities
  - The most popular – decimal or base-10 number system
  - ‘base’ – the number used as the reference for constructing the system & uses the 10 digits: 0, 1, 2, 3, 4, 5, 6, 7, 8, 9 to represent numbers
  - Computer has base-2 number system i.e. the binary code, 1 and 0
  - E.g.: binary system = 11 is equivalent to  $(1 \times 2^1) + (1 \times 2^0) = 2+1 = 3$



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# Round-off errors – Integer representation

- Base-10 numbers can be represented by base-2 system: how numbers are represented on a computer
- Signed magnitude representation: first bit (leftmost) indicates the sign (i.e. 1 for positive & 0 for negative) while the rest indicates the magnitude
- E.g.:  
1001 1000 → total 8 bits: first bit 1 → positive while  $2^5 + 2^4 = 32 + 8 = 40$   
Thus: The magnitude is 40 in 7-bit binary
- 2's complement technique: incorporate the sign into the number's magnitude
- Computers have limited capability to represent integers: numbers out of range can't be represented, so does the fractional quantities – floating-point



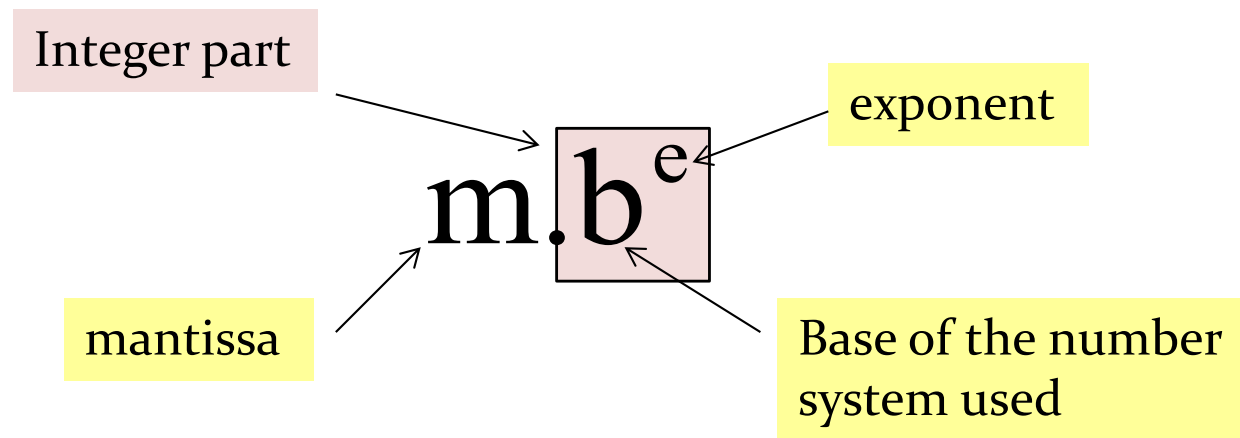
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# Round-off errors – Floating-point representation

- Fractional quantities are represented in computers using floating-point form
- The number is expressed as a fractional part – mantissa or significand - and fractional part – exponent or characteristic:



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# Round-off errors – Floating-point representation

- Significant figures are those number can be used with confidence.
- E.g: 0.0123  
0.00123  
0.000123
- All above are three significant figures
- Zeros are not always significant figures because they may necessary just to locate a decimal point.
- E.g: 45700
- 3,4 or 5 significant figures depend whether zeros are known with confidence.



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# Round-off errors – Floating-point representation

- Using scientific notation:
  - 4.57 x 10<sup>4</sup> - 3 significant figures
  - 4.570 x 10<sup>4</sup> - 4 significant figures
  - 4.5700 x 10<sup>4</sup> - 5 significant figures
- Generally:
  - Non zero digits are always significant e.g : 486912 (6SF)
  - Any zero between two significant numbers are significant e.g : 708 (3SF)
  - Final zero or trailing zero in a decimal portion only significant e.g 0.008980 (4SF)



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# Truncation errors – The Taylor Series

- Those that results from using an approximation in place of an exact mathematical procedure – the difference equation only approximates the true value of the derivative
- Mathematical formulation that is used widely to express functions in an approximate fashion
- It was built term by term, started with zero-order approximation.
- The higher the order of approximation applied, the lower the truncation error

$$\begin{aligned} f(x) &= f(x_0) + f'(x_0)(x - x_0) + \frac{f''(x_0)}{2!}(x - x_0)^2 \\ &\quad + \frac{f'''(x_0)}{3!}(x - x_0)^3 + \frac{f^{(4)}(x_0)}{4!}(x - x_0)^4 + \dots \\ &= \sum_{n=0}^{\infty} \frac{f^{(n)}(x_0)}{n!} (x - x_0)^n. \end{aligned}$$

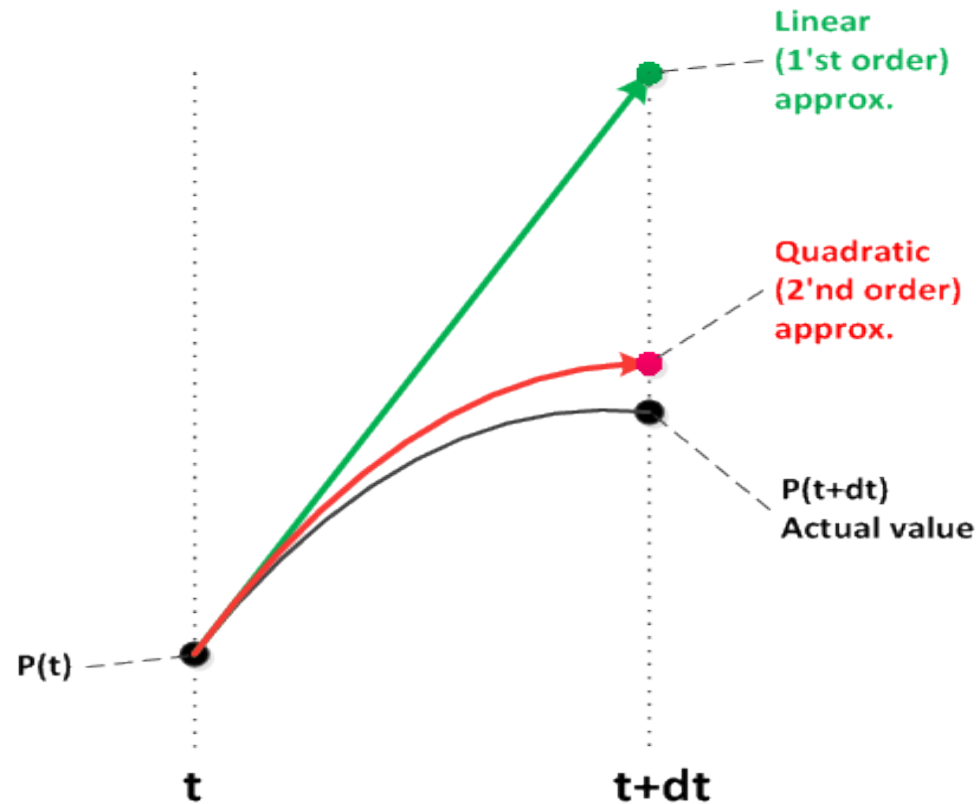


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# Truncation errors – The Taylor Series



Source: <https://www.clear.rice.edu/comp130/12spring/predprey/>



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# Truncation errors – The Taylor Series (cont'd)

- The  $n$ -th order of Taylor series expansion will be exact for the  $n$ -th order polynomial but not for:
  - Differentiable functions
  - Continuous functions
- Each additional terms will contribute to some improvement to the approximation
- The error is proportional to the step size,  $h$  but not the number of terms added - lower number of terms gives better approximation
  - (Example 4.2)



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# The remainder of Taylor Series Expansion

- The lower order derivatives account for a greater share of the remainder than the higher order terms
- It is inconvenient to deal with the remainder in infinite series format, one simplification can be used to truncate the remainder itself to:

$$R_1 = \frac{f''(\xi)}{2!} h^2$$



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# Numerical Differentiation

- In order to solve the derivatives of an equation, numerical differentiation of Taylor Series can be used with the following approximations:

- Forward difference approximation

$$f'(x_i) = \frac{f(x_{i+1}) - f(x_i)}{x_{i+1} - x_i} + O(x_{i+1} - x_i)$$

- Backward difference approximation

$$f'(x_i) \cong \frac{f(x_i) - f(x_{i-1})}{h}$$

- Centered difference approximation

$$f'(x_i) = \frac{f(x_{i+1}) - f(x_{i-1}))}{2h} - O(h^2)$$



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# Conclusion

- Percent error, percent relative error & percent tolerance can be calculated for engineering problems
- Truncation error can be estimated by using Taylor Series



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## Main Reference

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