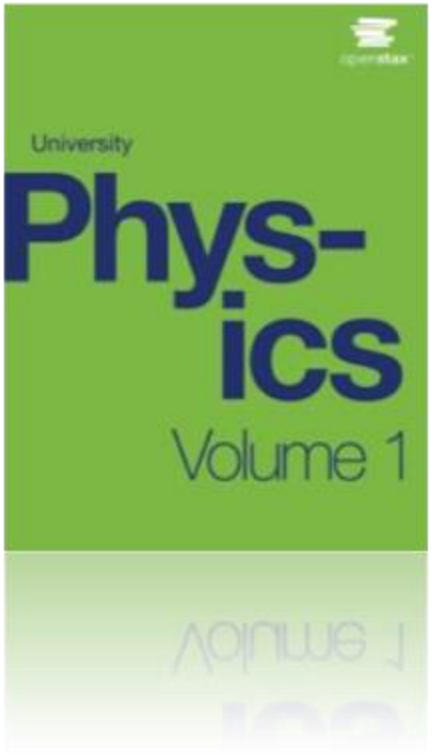
UNIVERSITY PHYSICS

Chapter 6 APPLICATIONS OF NEWTON'S LAWS

PowerPoint Image Slideshow

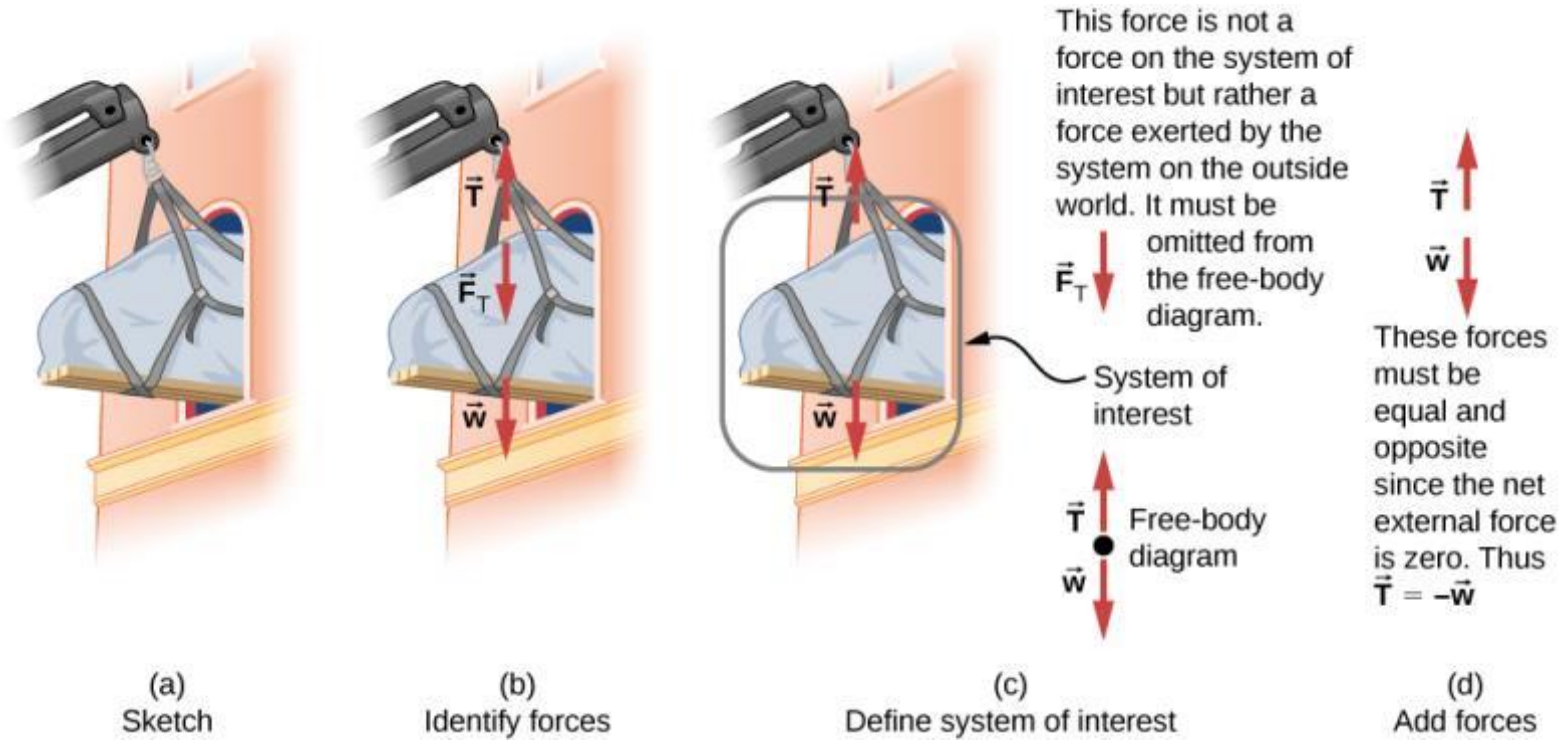


openstax™

FIGURE 6.1

Stock cars racing in the Grand National Divisional race at Iowa Speedway in May, 2015. Cars often reach speeds of 200 mph (320 km/h).

FIGURE 6.2



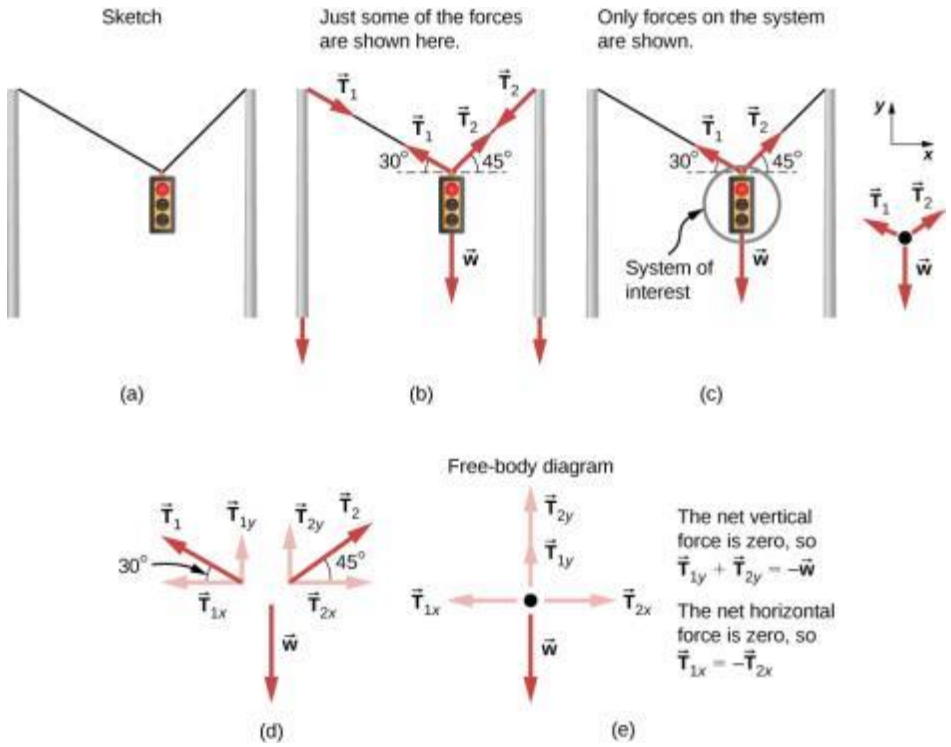
(a) A grand piano is being lifted to a second-story apartment.

(b) Arrows are used to represent all forces: $\vec{\mathbf{T}}$ is the tension in the rope above the piano, $\vec{\mathbf{F}}_T$ is the force that the piano exerts on the rope, and $\vec{\mathbf{w}}$ is the weight of the piano. All other forces, such as the nudge of a breeze, are assumed to be negligible.

(c) Suppose we are given the piano's mass and asked to find the tension in the rope. We then define the system of interest as shown and draw a free-body diagram. Now $\vec{\mathbf{F}}_T$ is no longer shown, because it is not a force acting on the system of interest; rather, $\vec{\mathbf{F}}_T$ acts on the outside world.

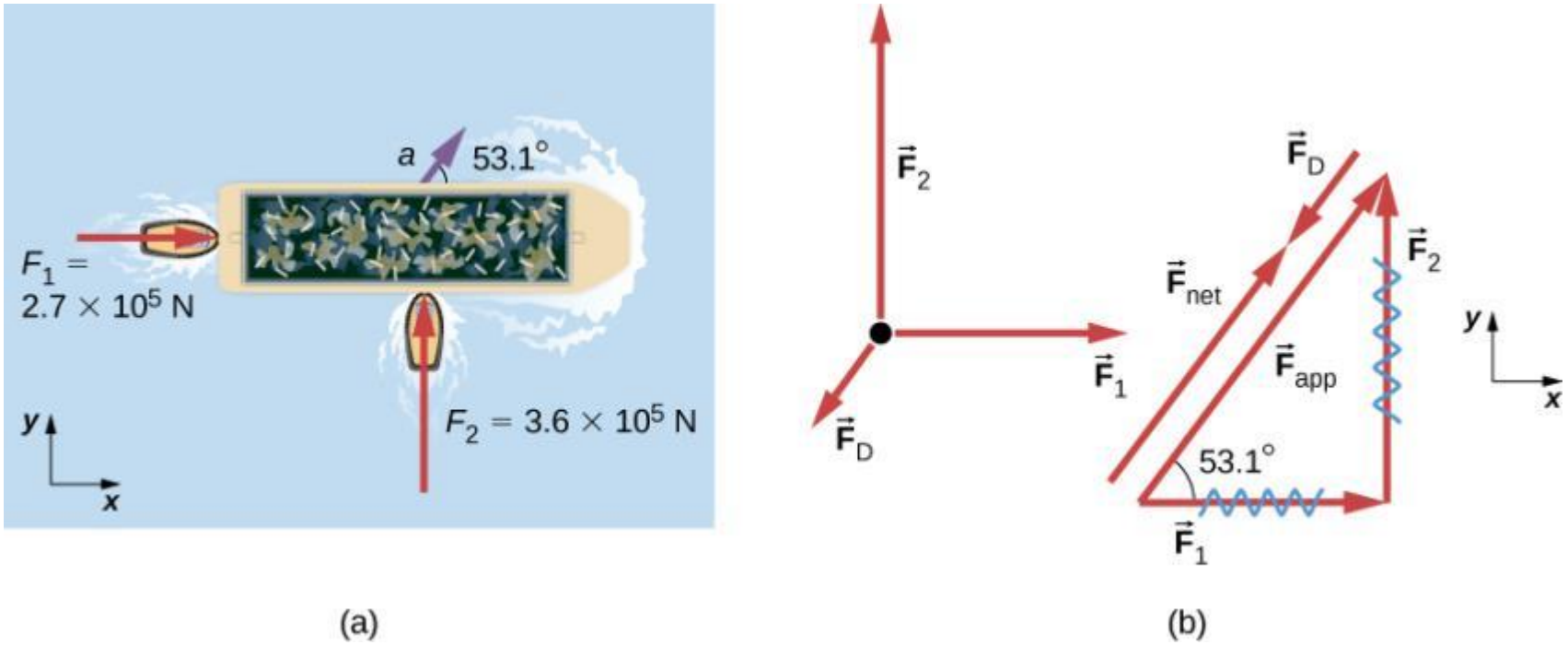
(d) Showing only the arrows, the head-to-tail method of addition is used. It is apparent that if the piano is stationary, $\vec{\mathbf{T}} = -\vec{\mathbf{w}}$.

FIGURE 6.3



A traffic light is suspended from two wires. (b) Some of the forces involved. (c) Only forces acting on the system are shown here. The free-body diagram for the traffic light is also shown. (d) The forces projected onto vertical (*y*) and horizontal (*x*) axes. The horizontal components of the tensions must cancel, and the sum of the vertical components of the tensions must equal the weight of the traffic light. (e) The free-body diagram shows the vertical and horizontal forces acting on the traffic light.

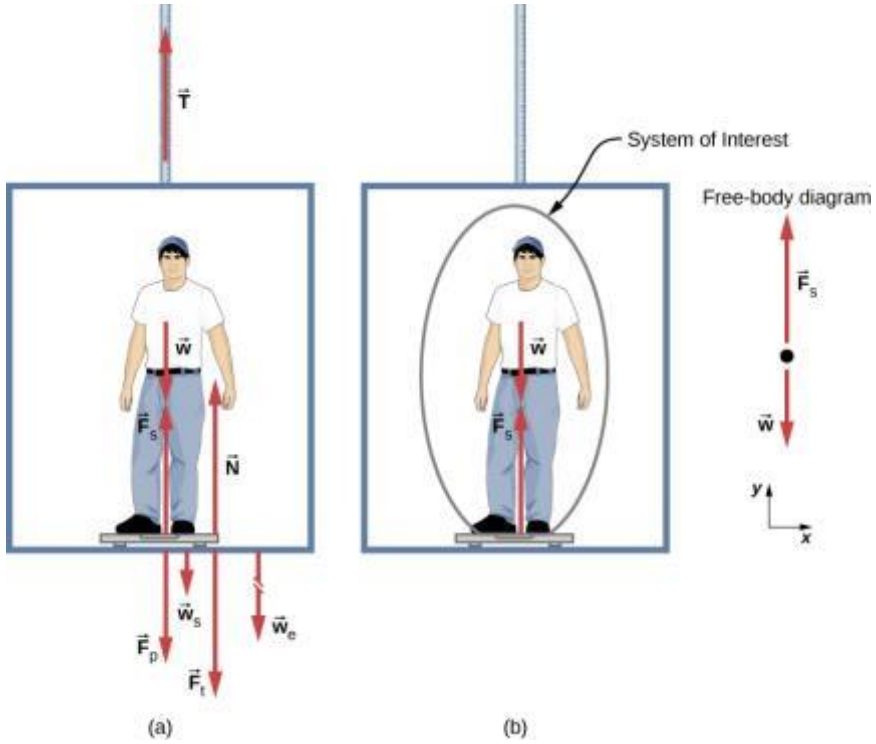
FIGURE 6.4



(a) A view from above of two tugboats pushing on a barge.

(b) The free-body diagram for the ship contains only forces acting in the plane of the water. It omits the two vertical forces—the weight of the barge and the buoyant force of the water supporting it cancel and are not shown. Note that $\vec{\mathbf{F}}_{\text{app}}$ is the total applied force of the tugboats.

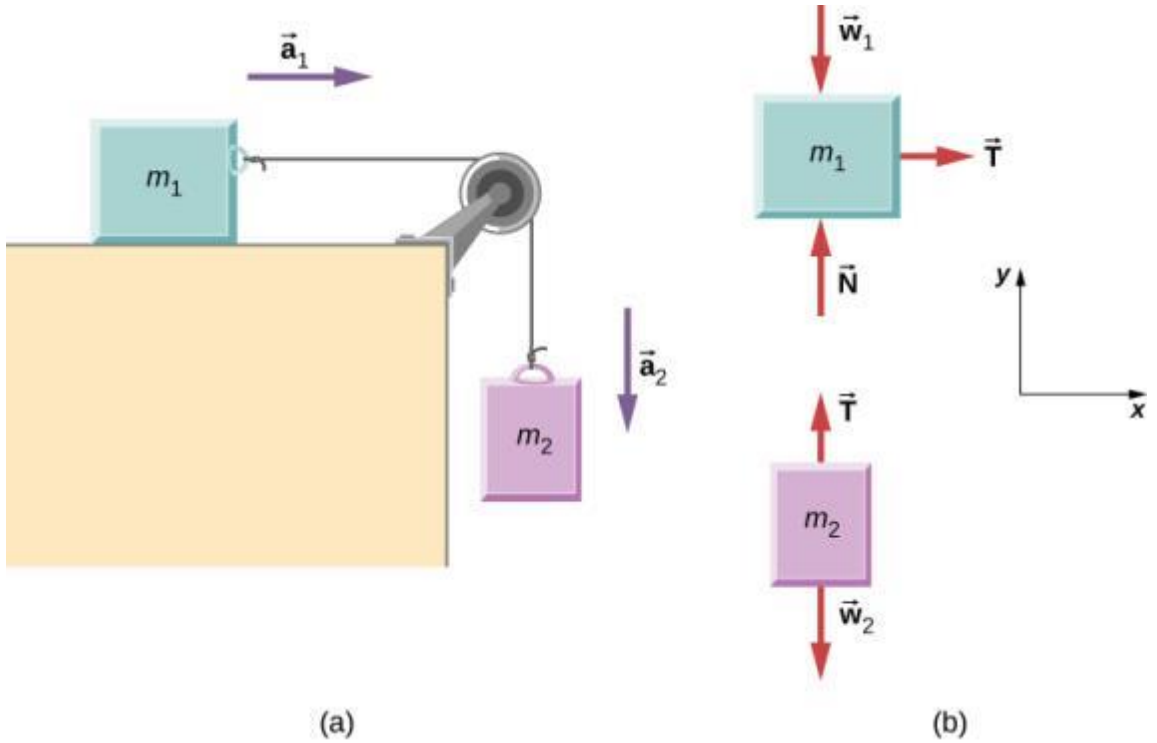
FIGURE 6.5



(a) The various forces acting when a person stands on a bathroom scale in an elevator. The arrows are approximately correct for when the elevator is accelerating upward—broken arrows represent forces too large to be drawn to scale. $\vec{\mathbf{T}}$ is the tension in the supporting cable, $\vec{\mathbf{w}}$ is the weight of the person, $\vec{\mathbf{w}}_s$ is the weight of the scale, $\vec{\mathbf{w}}_e$ is the weight of the elevator, $\vec{\mathbf{F}}_s$ is the force of the scale on the person, $\vec{\mathbf{F}}_p$ is the force of the person on the scale, $\vec{\mathbf{F}}_t$ is the force of the scale on the floor of the elevator, and $\vec{\mathbf{N}}$ is the force of the floor upward on the scale.

(b) The free-body diagram shows only the external forces acting on the designated system of interest—the person—and is the diagram we use for the solution of the problem.

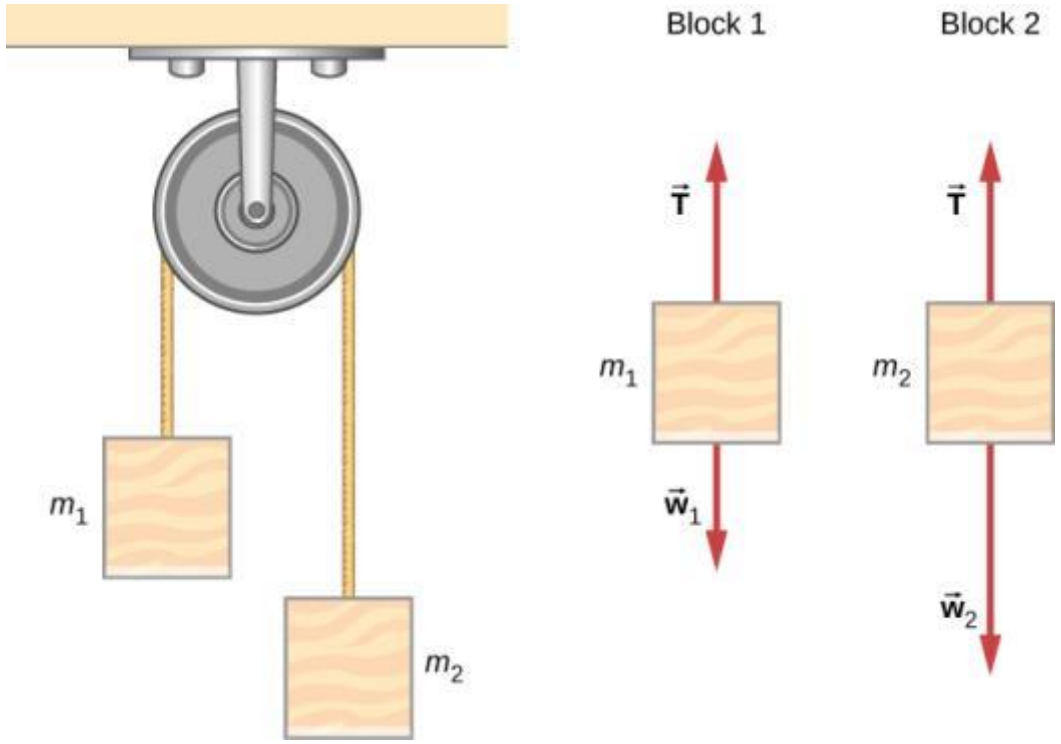
FIGURE 6.6



(a) Block 1 is connected by a light string to block 2.

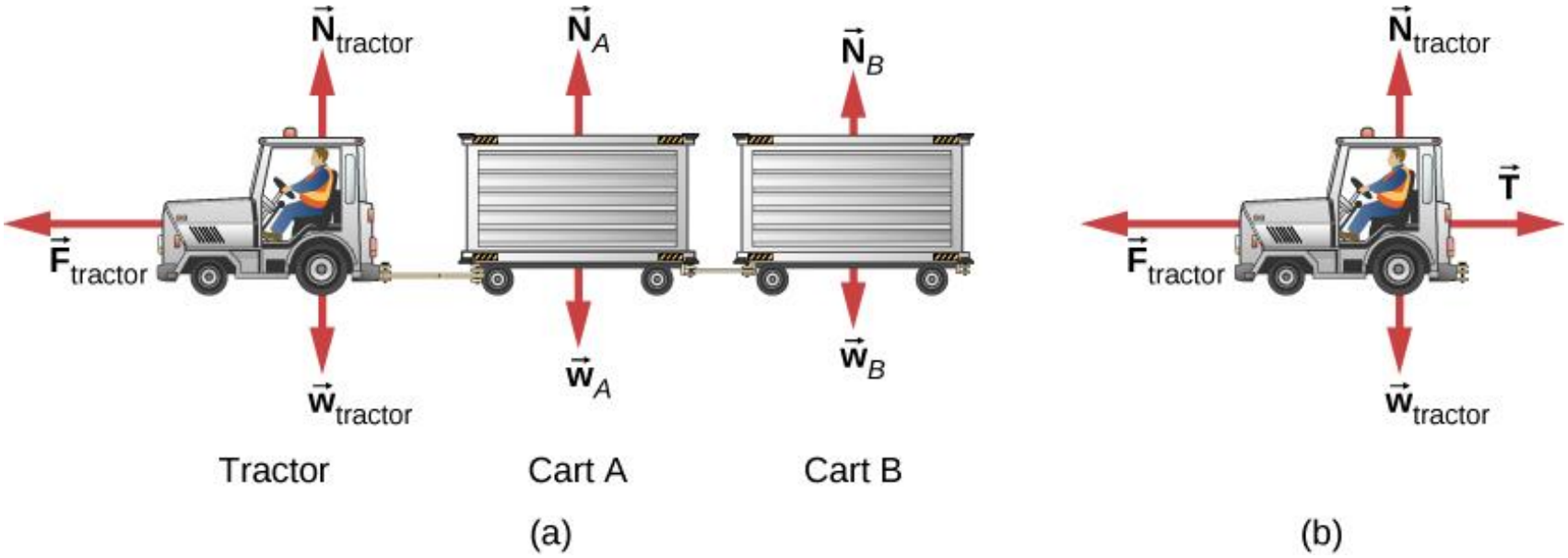
(b) The free-body diagrams of the blocks.

FIGURE 6.7



An Atwood machine and free-body diagrams for each of the two blocks.

FIGURE 6.8



(a) A free-body diagram is shown, which indicates all the external forces on the system consisting of the tractor and baggage carts for carrying airline luggage.

(b) A free-body diagram of the tractor only is shown isolated in order to calculate the tension in the cable to the carts.

FIGURE 6.9

(a) The mortar fires a shell straight up; we consider the friction force provided by the air.

(b) A free-body diagram is shown which indicates all the forces on the mortar shell.

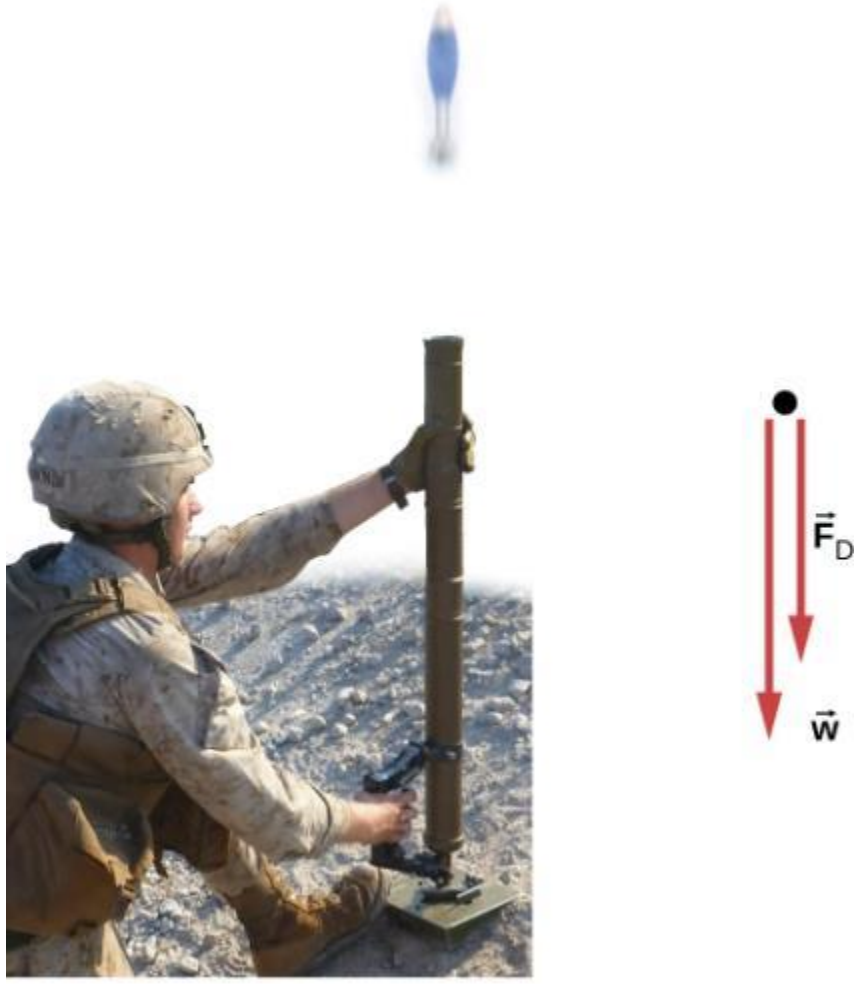
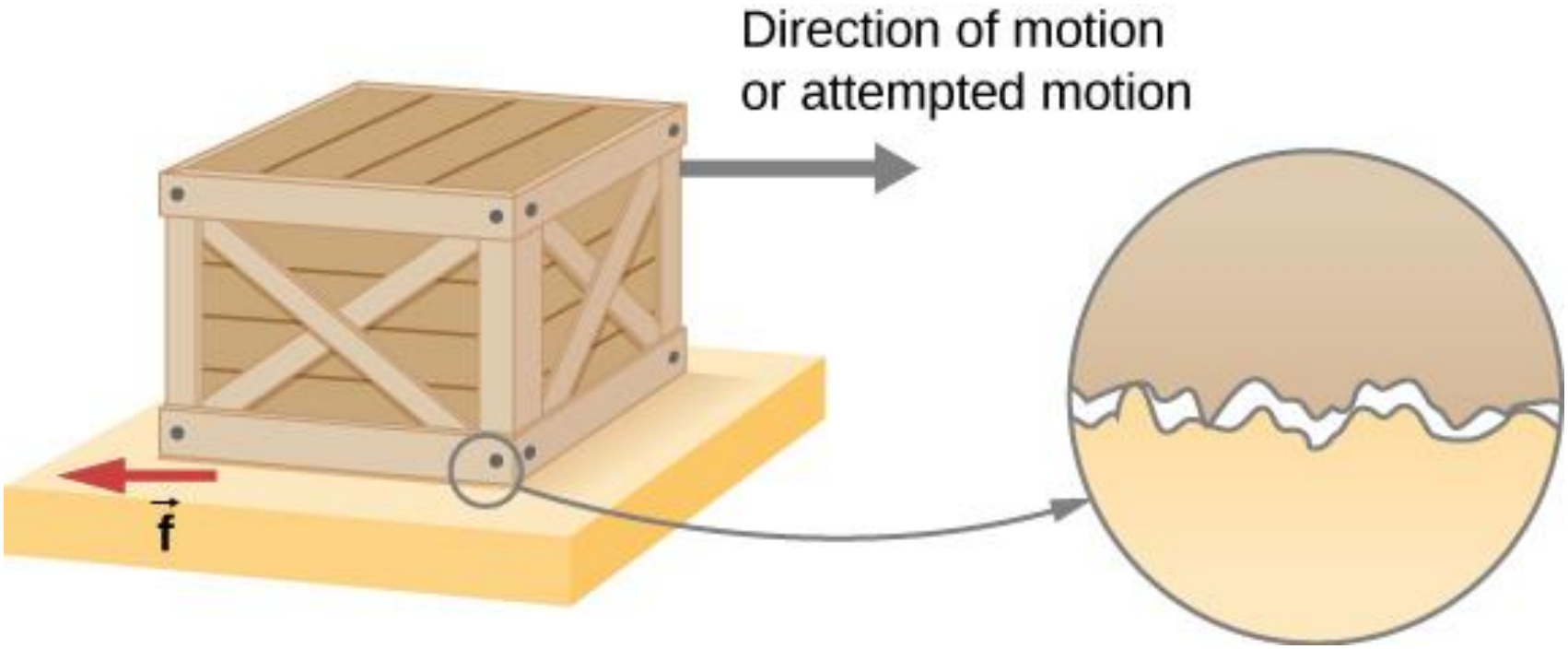
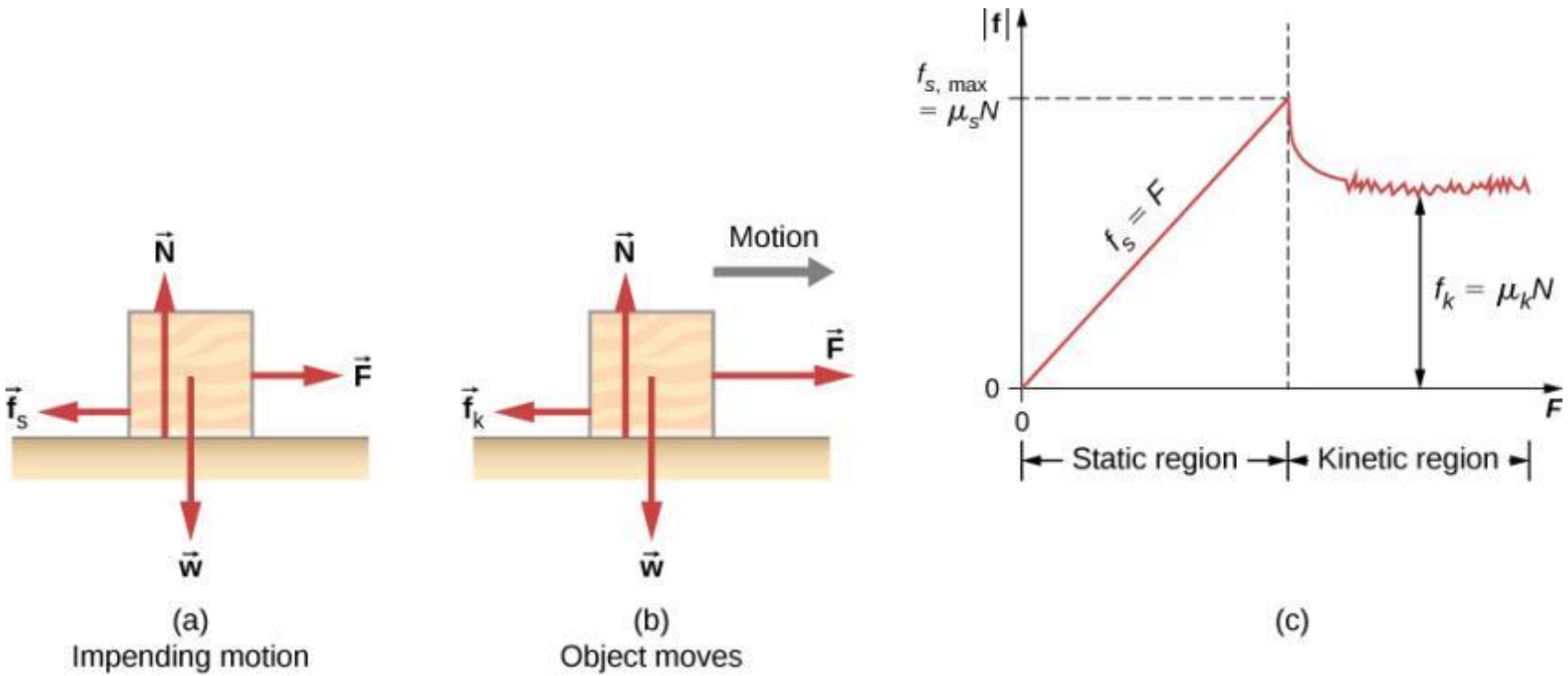


FIGURE 6.10



Frictional forces, such as $\vec{\mathbf{f}}$, always oppose motion or attempted motion between objects in contact. Friction arises in part because of the roughness of the surfaces in contact, as seen in the expanded view. For the object to move, it must rise to where the peaks of the top surface can skip along the bottom surface. Thus, a force is required just to set the object in motion. Some of the peaks will be broken off, also requiring a force to maintain motion. Much of the friction is actually due to attractive forces between molecules making up the two objects, so that even perfectly smooth surfaces are not friction-free. (In fact, perfectly smooth, clean surfaces of similar materials would adhere, forming a bond called a “cold weld.”)

FIGURE 6.11

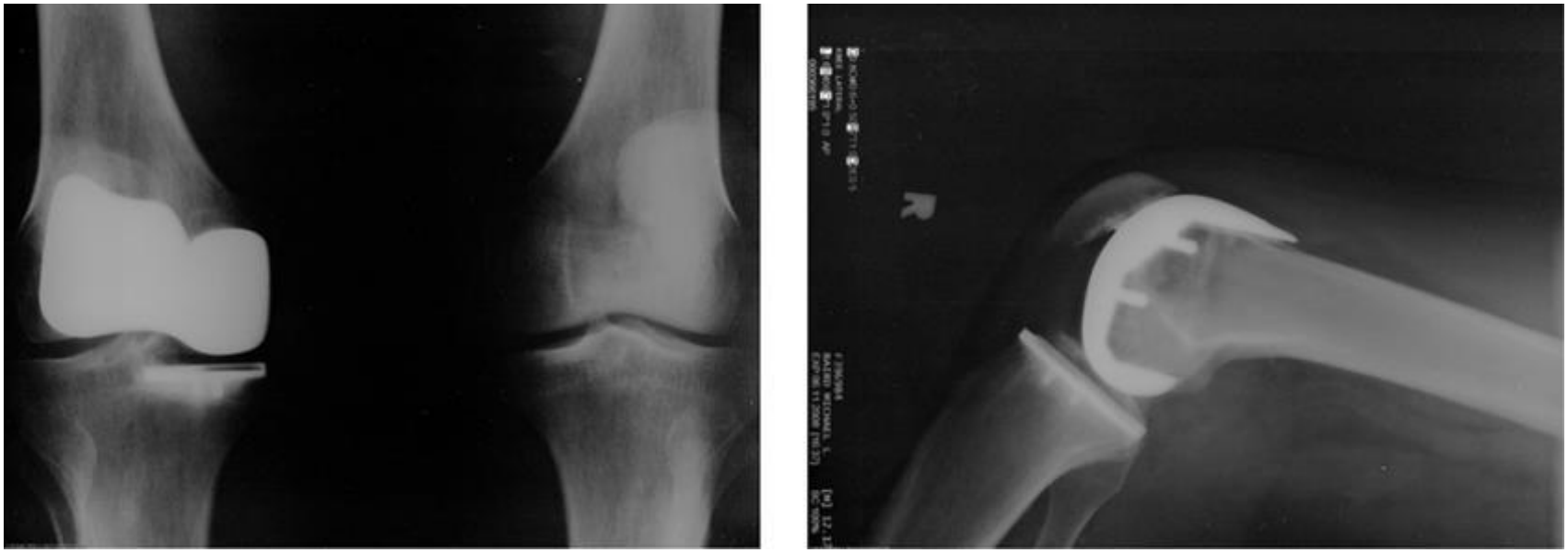


(a) The force of friction $\vec{\mathbf{f}}$ between the block and the rough surface opposes the direction of the applied force $\vec{\mathbf{F}}$. The magnitude of the static friction balances that of the applied force. This is shown in the left side of the graph in (c).

(b) At some point, the magnitude of the applied force is greater than the force of kinetic friction, and the block moves to the right. This is shown in the right side of the graph.

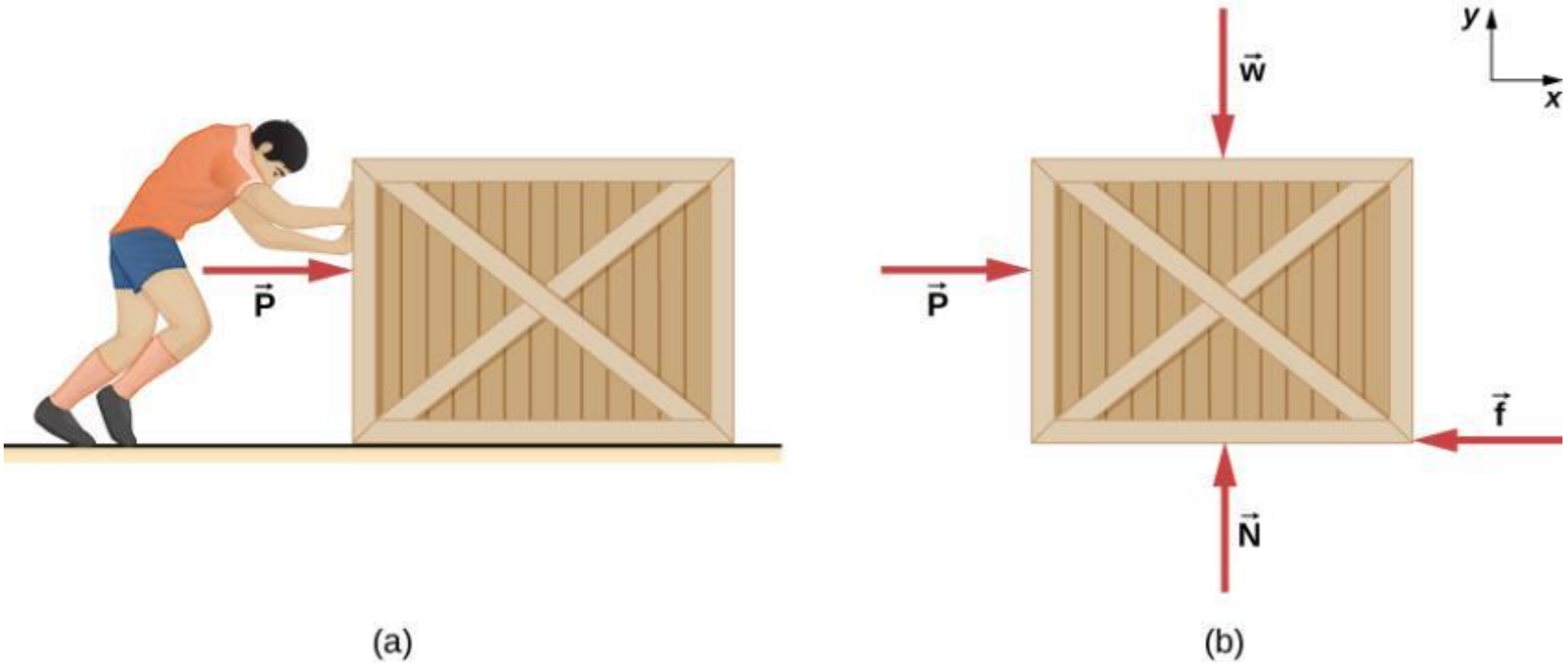
(c) The graph of the frictional force versus the applied force; note that $f_{\mathrm{s}}(\mathrm{max}) > f_{\mathrm{k}}$. This means that $\mu_{\mathrm{s}} > \mu_{\mathrm{k}}$.

FIGURE 6.12



Artificial knee replacement is a procedure that has been performed for more than 20 years. These post-operative X-rays show a right knee joint replacement. (credit: Mike Baird)

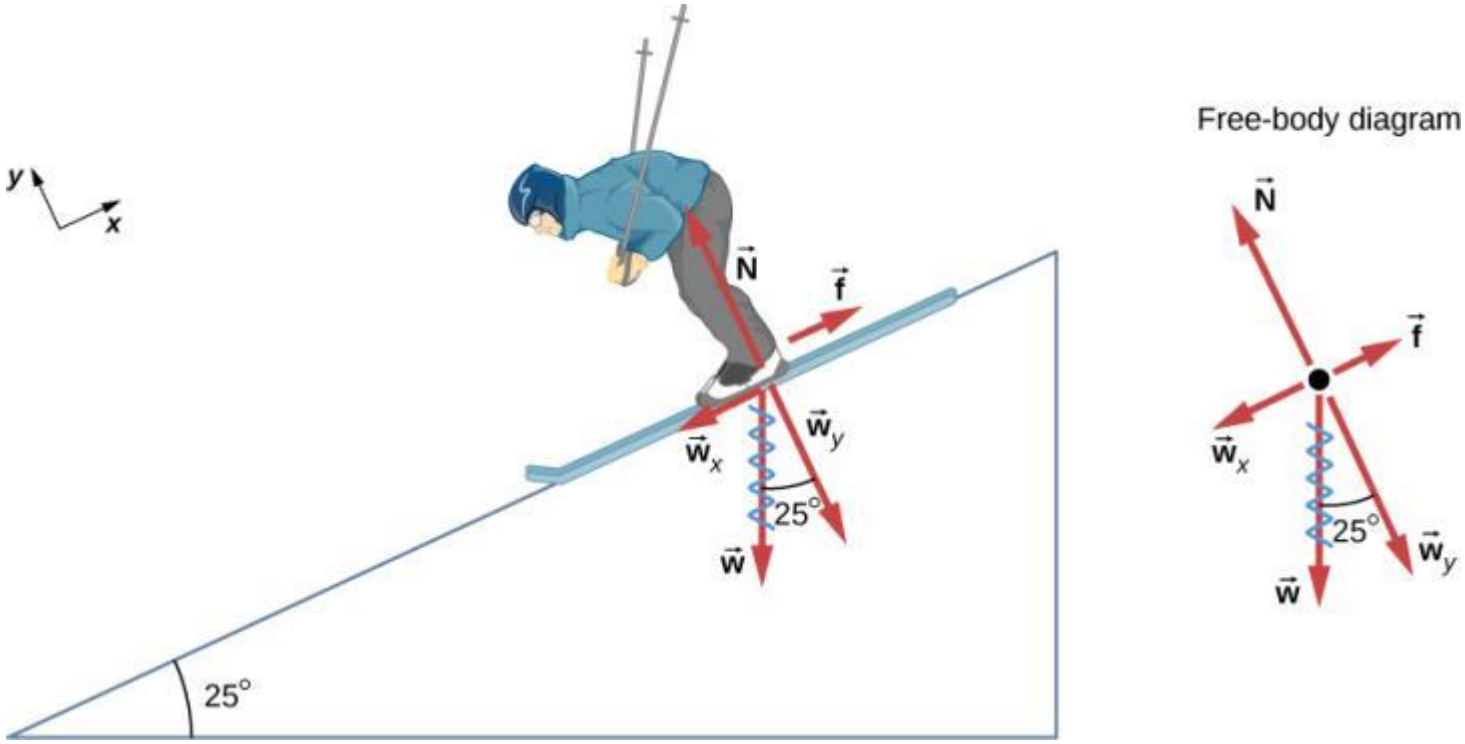
FIGURE 6.13



(a) A crate on a horizontal surface is pushed with a force $\vec{\mathbf{P}}$.

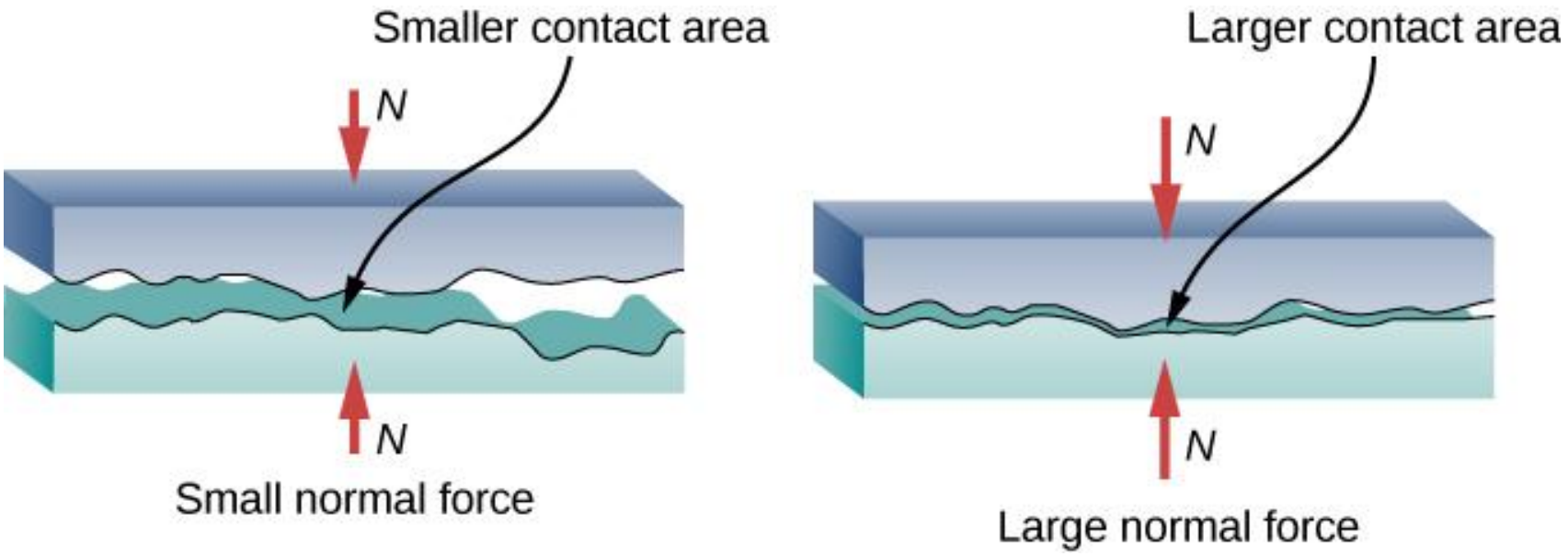
(b) The forces on the crate. Here, $\vec{\mathbf{f}}$ may represent either the static or the kinetic frictional force.

FIGURE 6.14



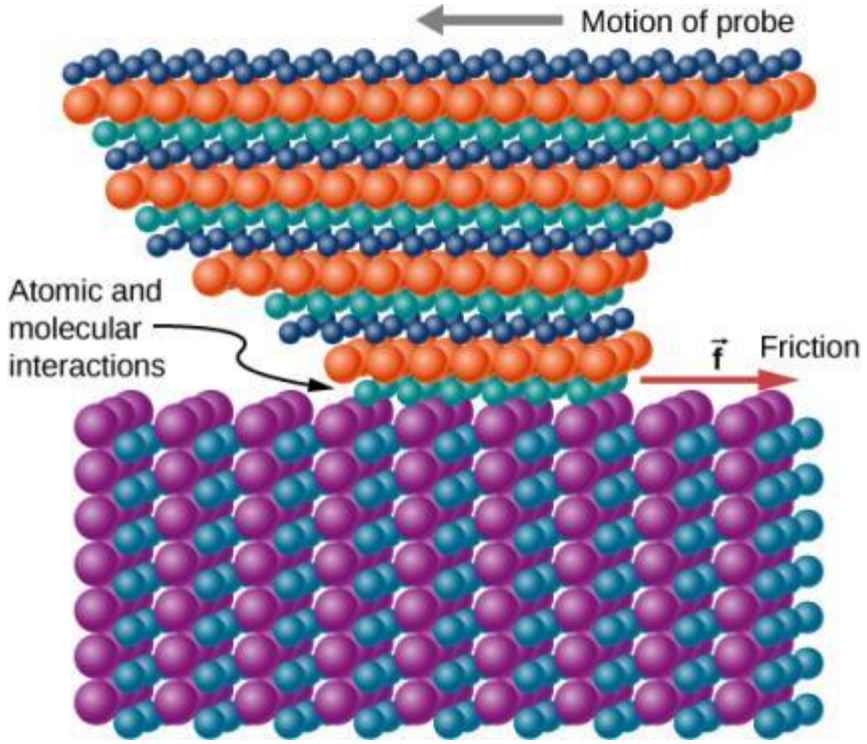
The motion of the skier and friction are parallel to the slope, so it is most convenient to project all forces onto a coordinate system where one axis is parallel to the slope and the other is perpendicular (axes shown to left of skier). The normal force $\vec{\mathbf{N}}$ is perpendicular to the slope, and friction $\vec{\mathbf{f}}$ is parallel to the slope, but the skier's weight $\vec{\mathbf{w}}$ has components along both axes, namely $\vec{\mathbf{w}}_y$ and $\vec{\mathbf{w}}_x$. The normal force $\vec{\mathbf{N}}$ is equal in magnitude to $\vec{\mathbf{w}}_y$, so there is no motion perpendicular to the slope. However, $\vec{\mathbf{f}}$ is less than $\vec{\mathbf{w}}_x$ in magnitude, so there is acceleration down the slope (along the *x*-axis).

FIGURE 6.15



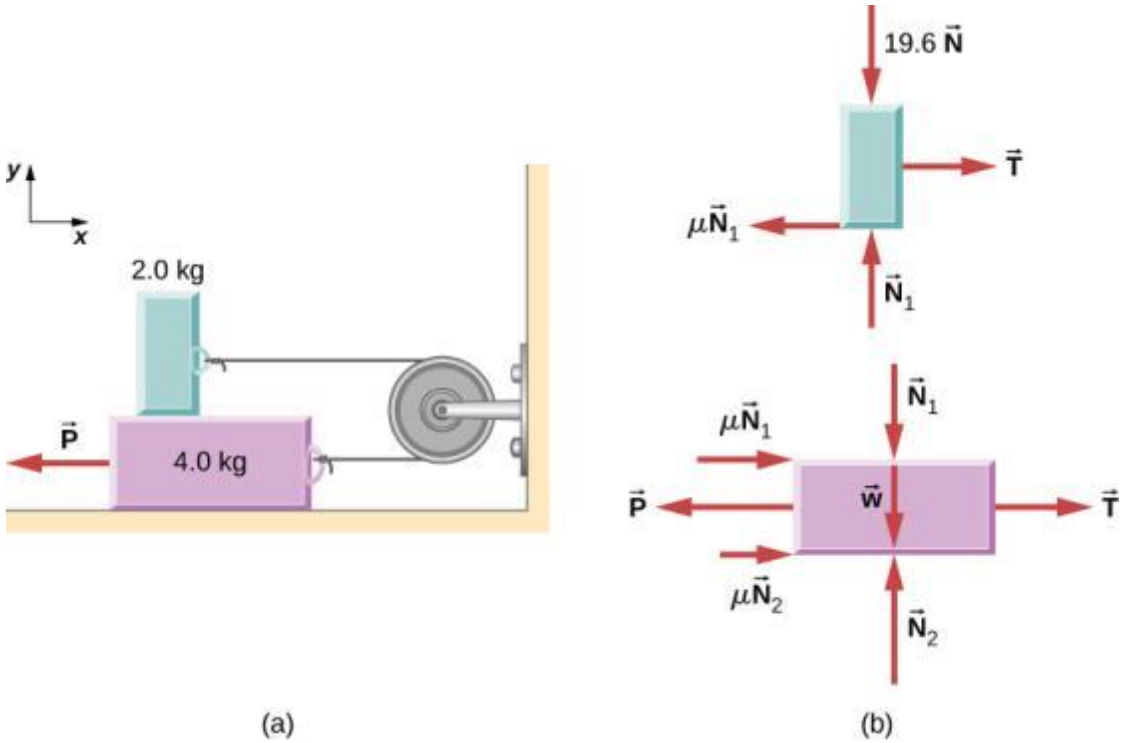
Two rough surfaces in contact have a much smaller area of actual contact than their total area. When the normal force is larger as a result of a larger applied force, the area of actual contact increases, as does friction.

FIGURE 6.16



The tip of a probe is deformed sideways by frictional force as the probe is dragged across a surface. Measurements of how the force varies for different materials are yielding fundamental insights into the atomic nature of friction.

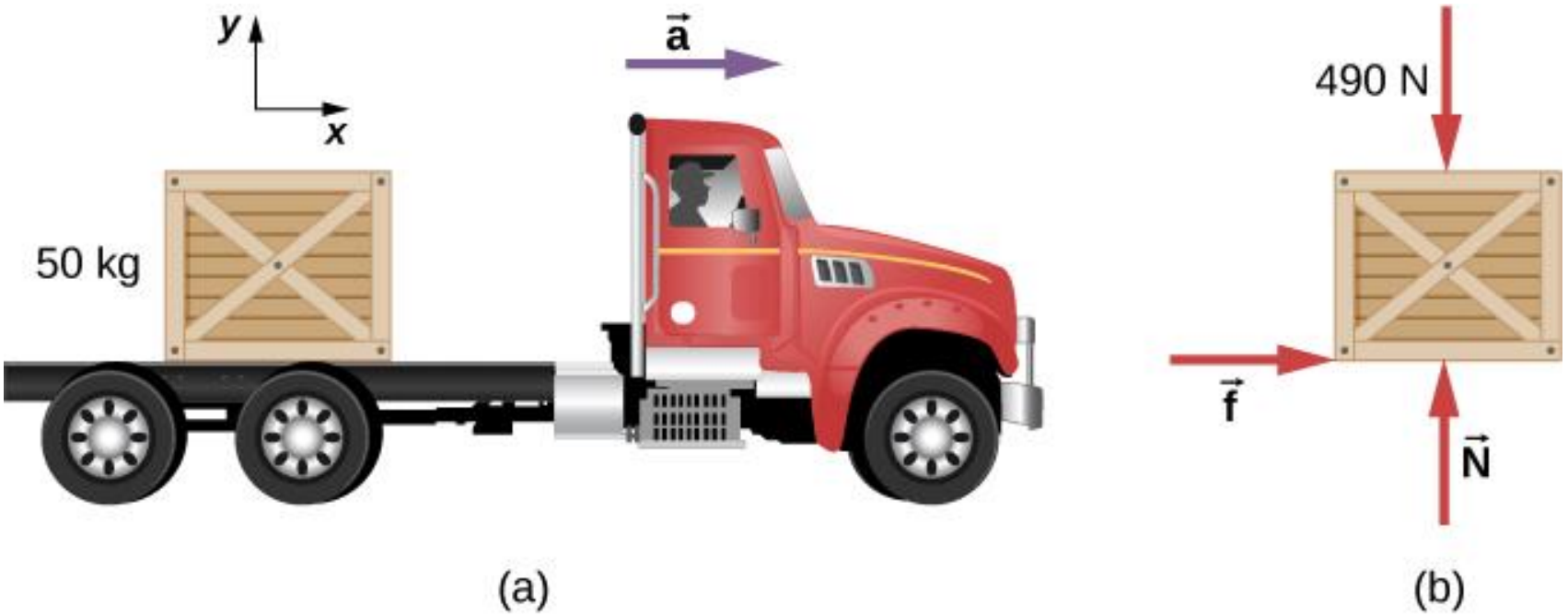
FIGURE 6.17



(a) Each block moves at constant velocity.

(b) Free-body diagrams for the blocks.

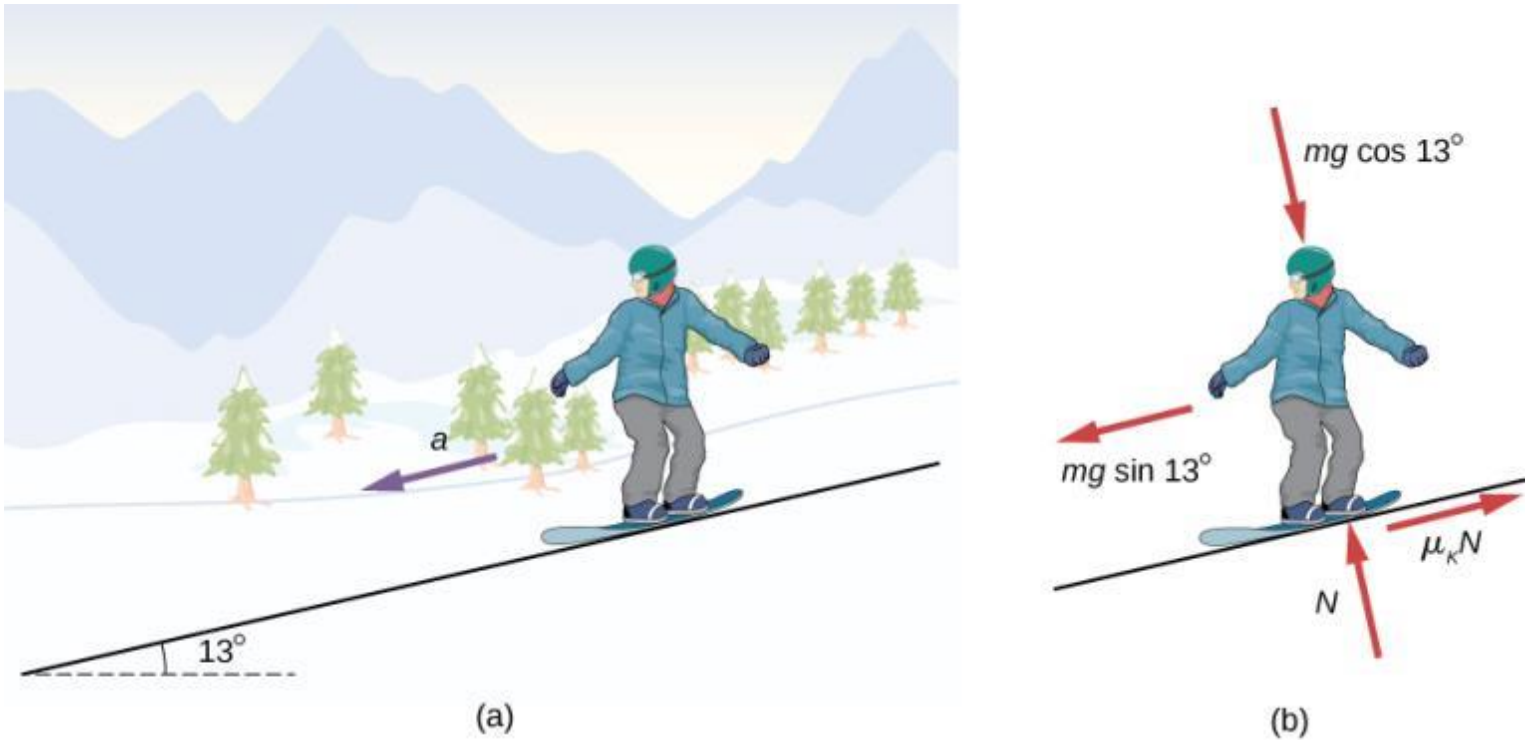
FIGURE 6.18



(a) A crate rests on the bed of the truck that is accelerating forward.

(b) The free-body diagram of the crate.

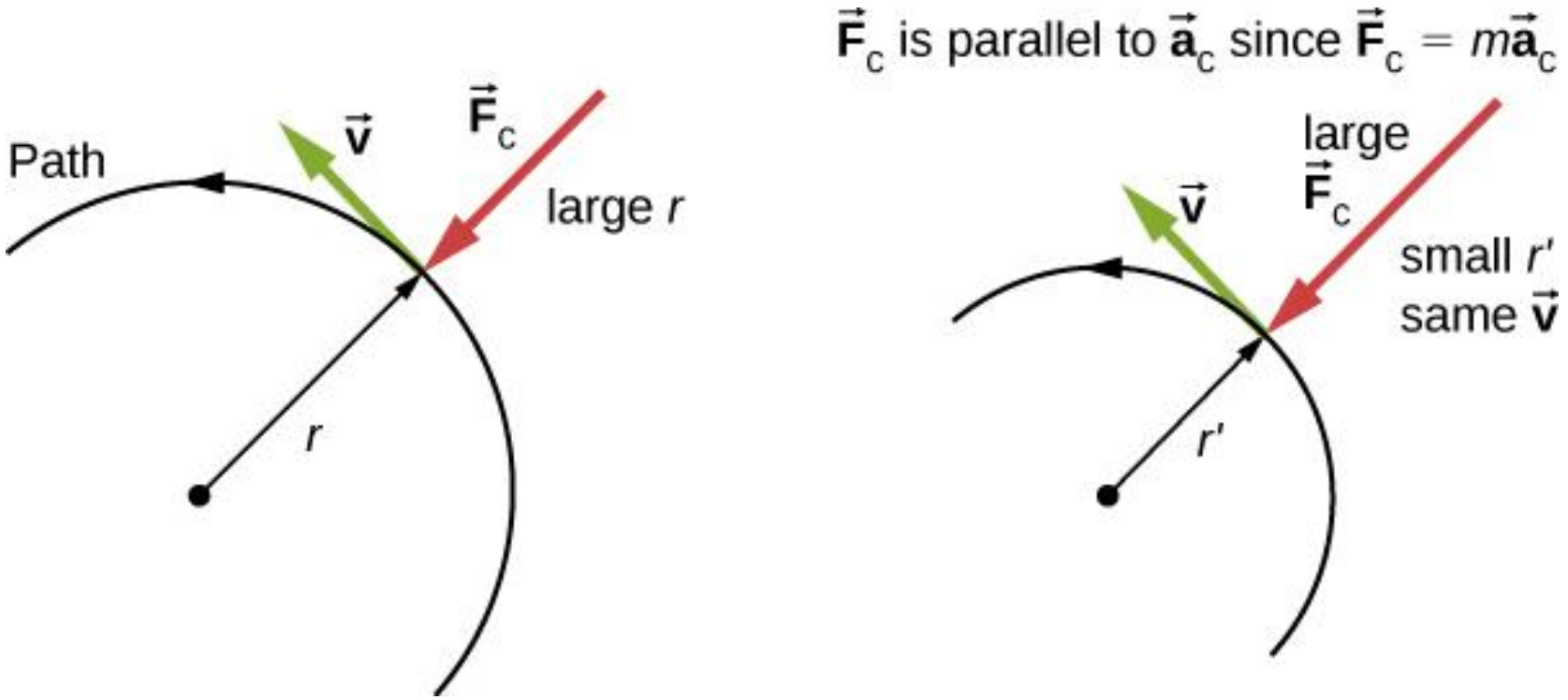
FIGURE 6.19



(a) A snowboarder glides down a slope inclined at 13° to the horizontal.

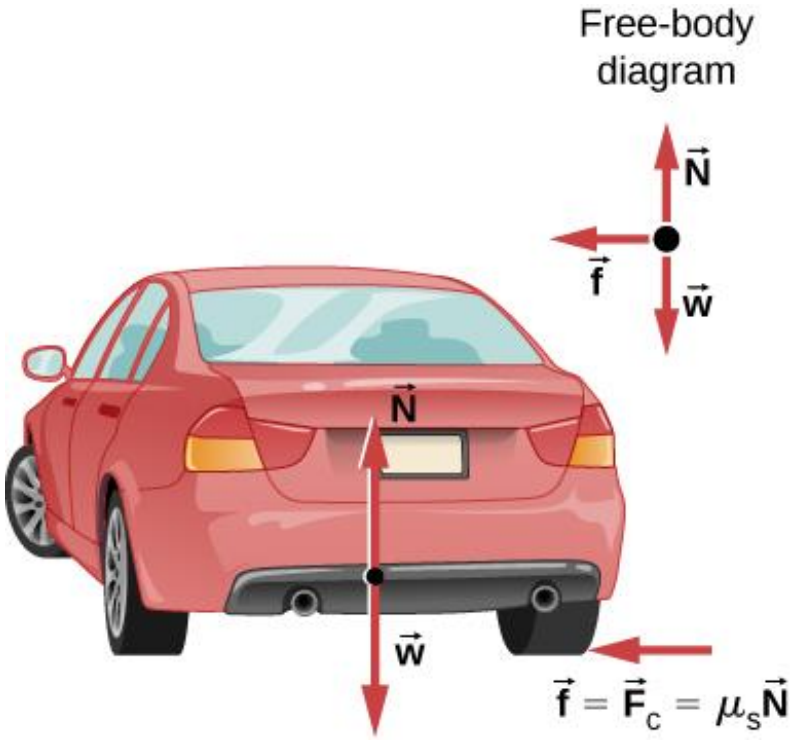
(b) The free-body diagram of the snowboarder.

FIGURE 6.20



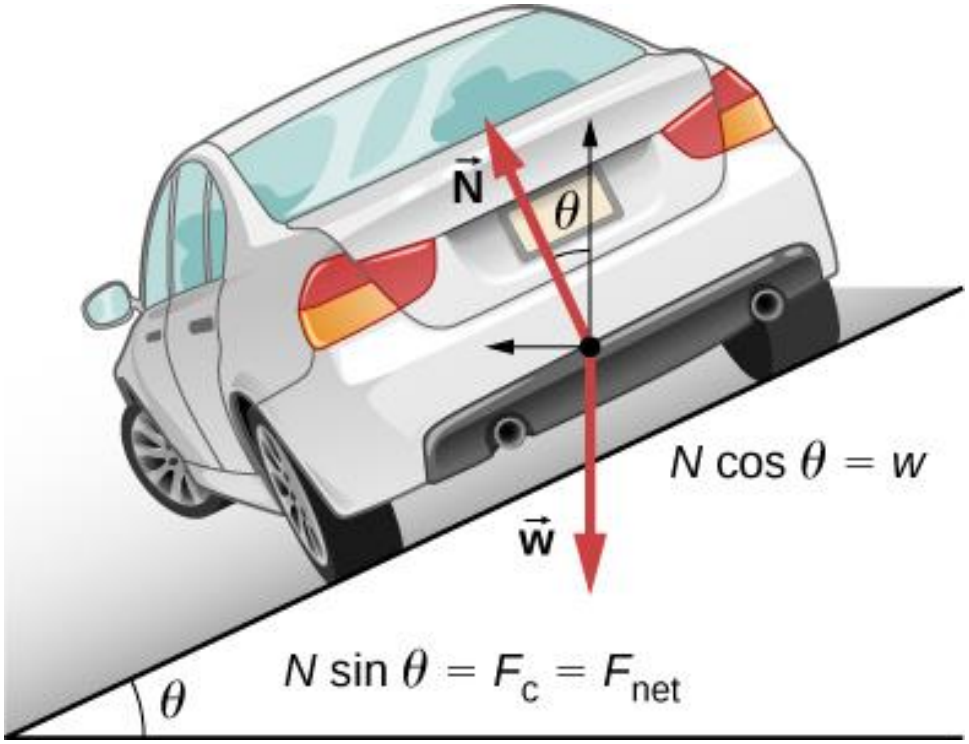
The frictional force supplies the centripetal force and is numerically equal to it. Centripetal force is perpendicular to velocity and causes uniform circular motion. The larger the F_c, the smaller the radius of curvature r and the sharper the curve. The second curve has the same v, but a larger F_c produces a smaller r'.

FIGURE 6.21



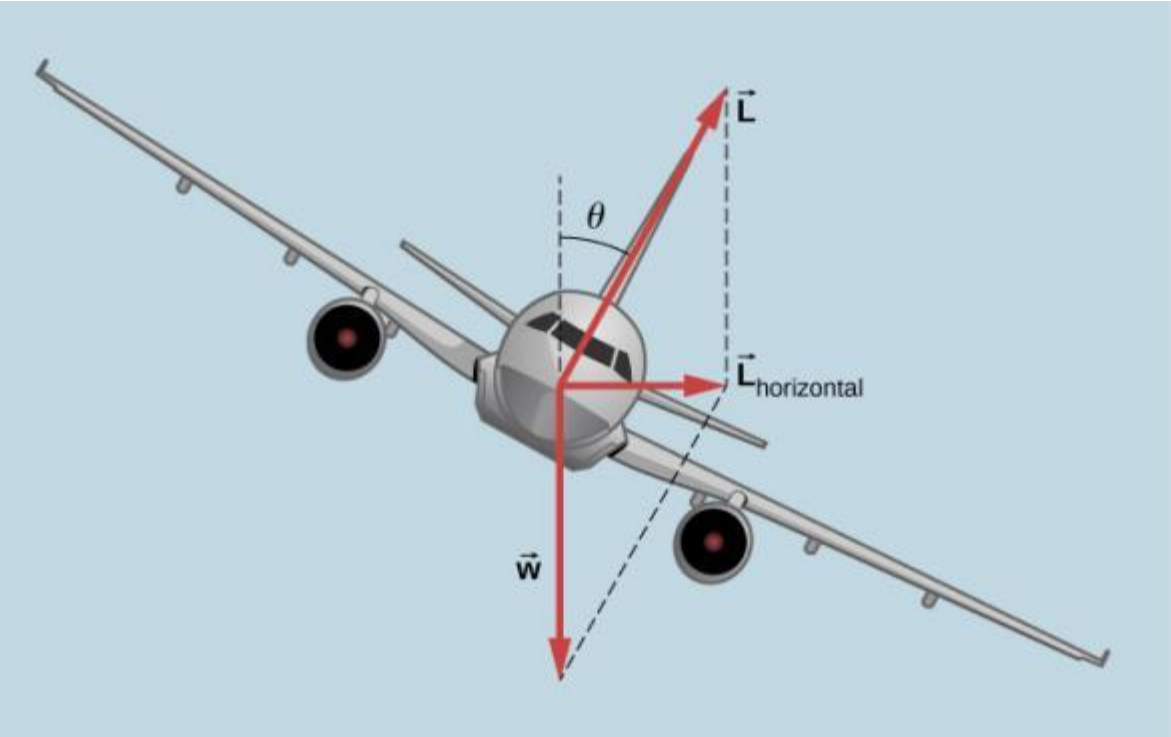
This car on level ground is moving away and turning to the left. The centripetal force causing the car to turn in a circular path is due to friction between the tires and the road. A minimum coefficient of friction is needed, or the car will move in a larger-radius curve and leave the roadway.

FIGURE 6.22



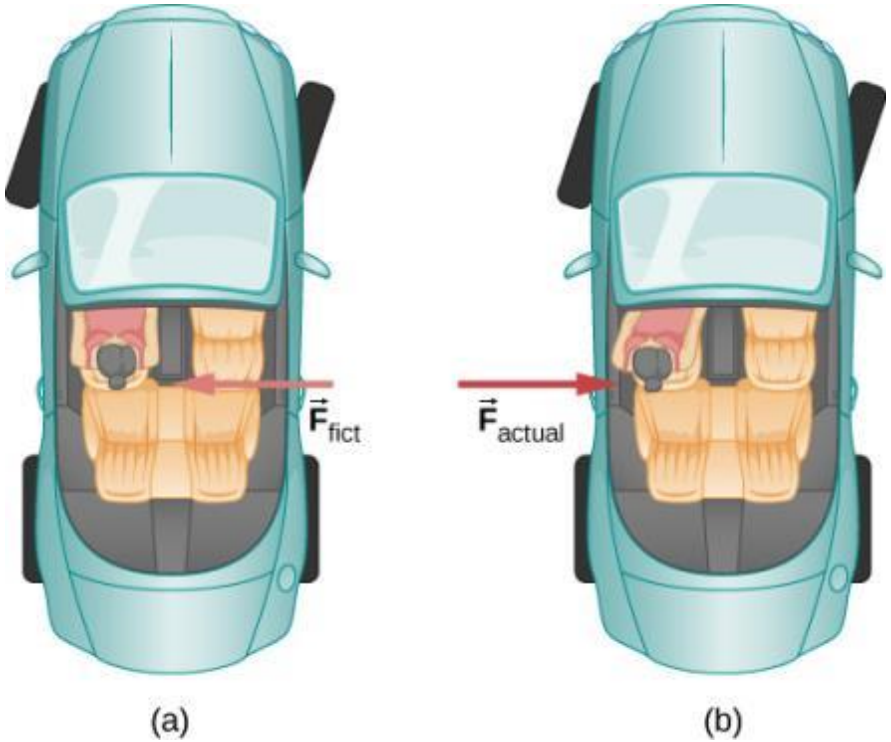
The car on this banked curve is moving away and turning to the left.

FIGURE 6.23



In a banked turn, the horizontal component of lift is unbalanced and accelerates the plane. The normal component of lift balances the plane's weight. The banking angle is given by θ. Compare the vector diagram with that shown in **Figure 6.22**.

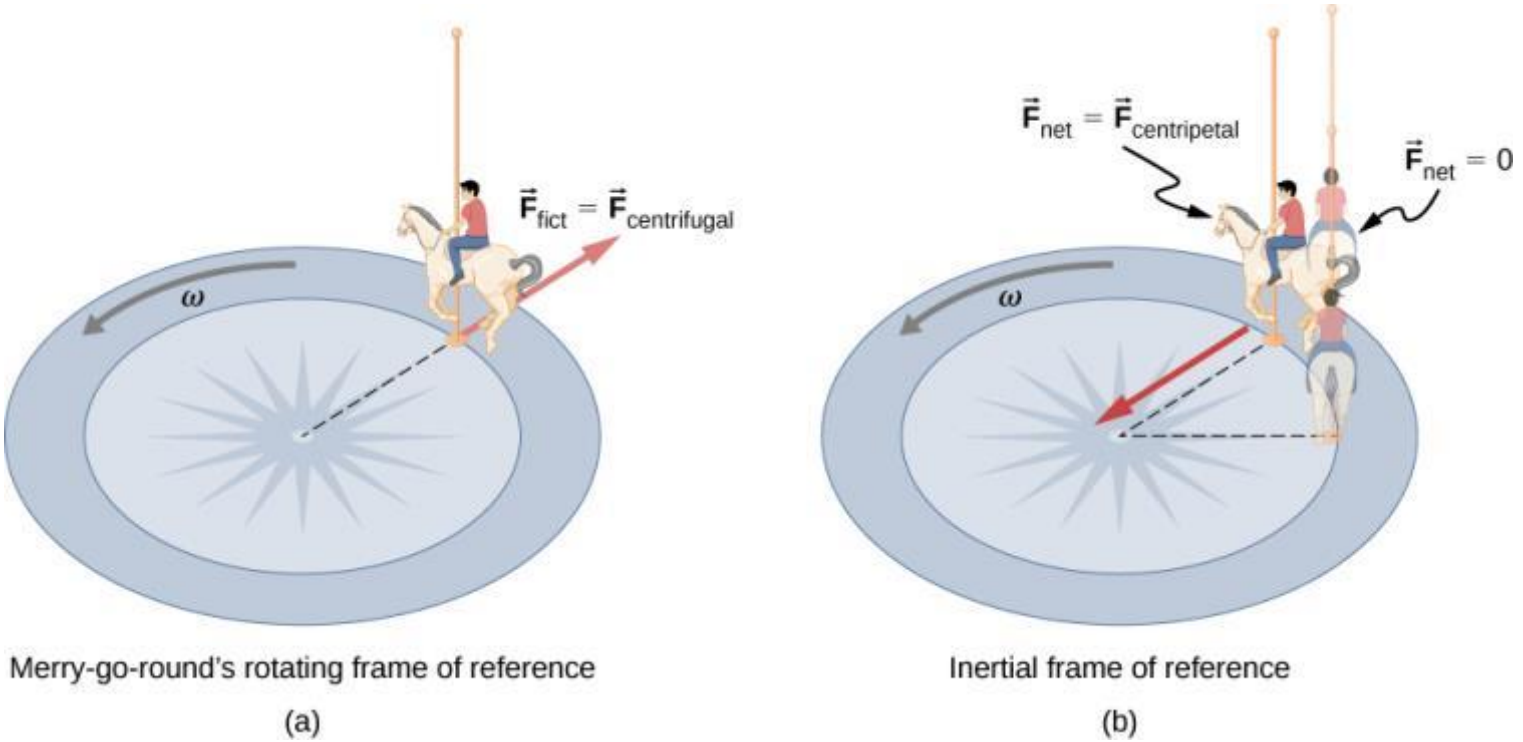
FIGURE 6.24



(a) The car driver feels herself forced to the left relative to the car when she makes a right turn. This is an inertial force arising from the use of the car as a frame of reference.

(b) In Earth's frame of reference, the driver moves in a straight line, obeying Newton's first law, and the car moves to the right. There is no force to the left on the driver relative to Earth. Instead, there is a force to the right on the car to make it turn.

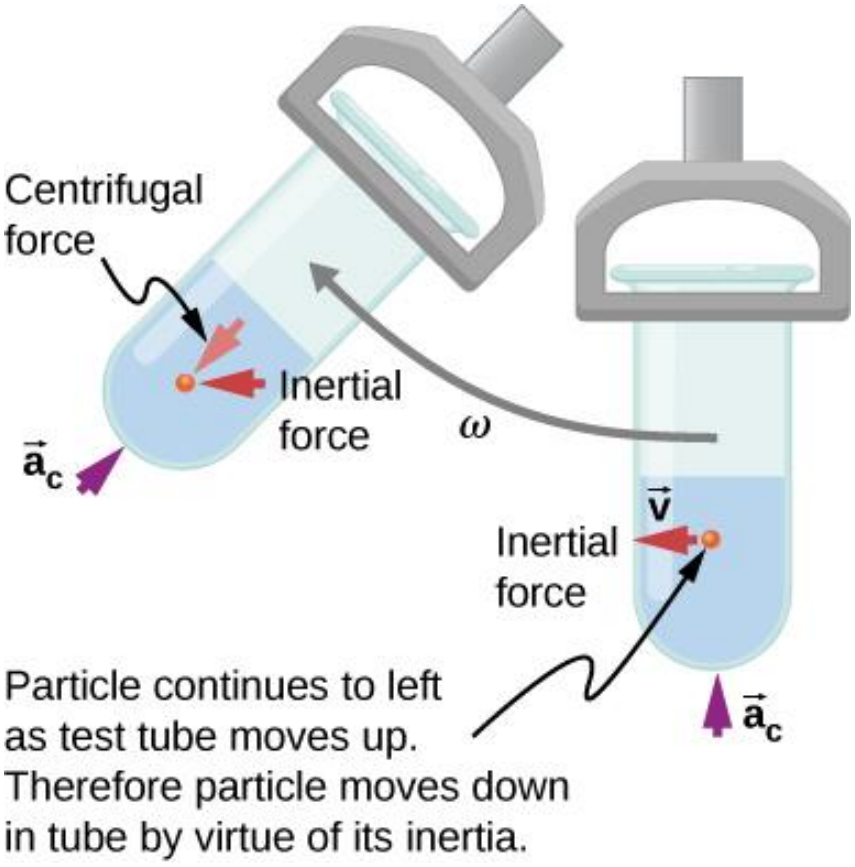
FIGURE 6.25



(a) A rider on a merry-go-round feels as if he is being thrown off. This inertial force is sometimes mistakenly called the centrifugal force in an effort to explain the rider's motion in the rotating frame of reference.

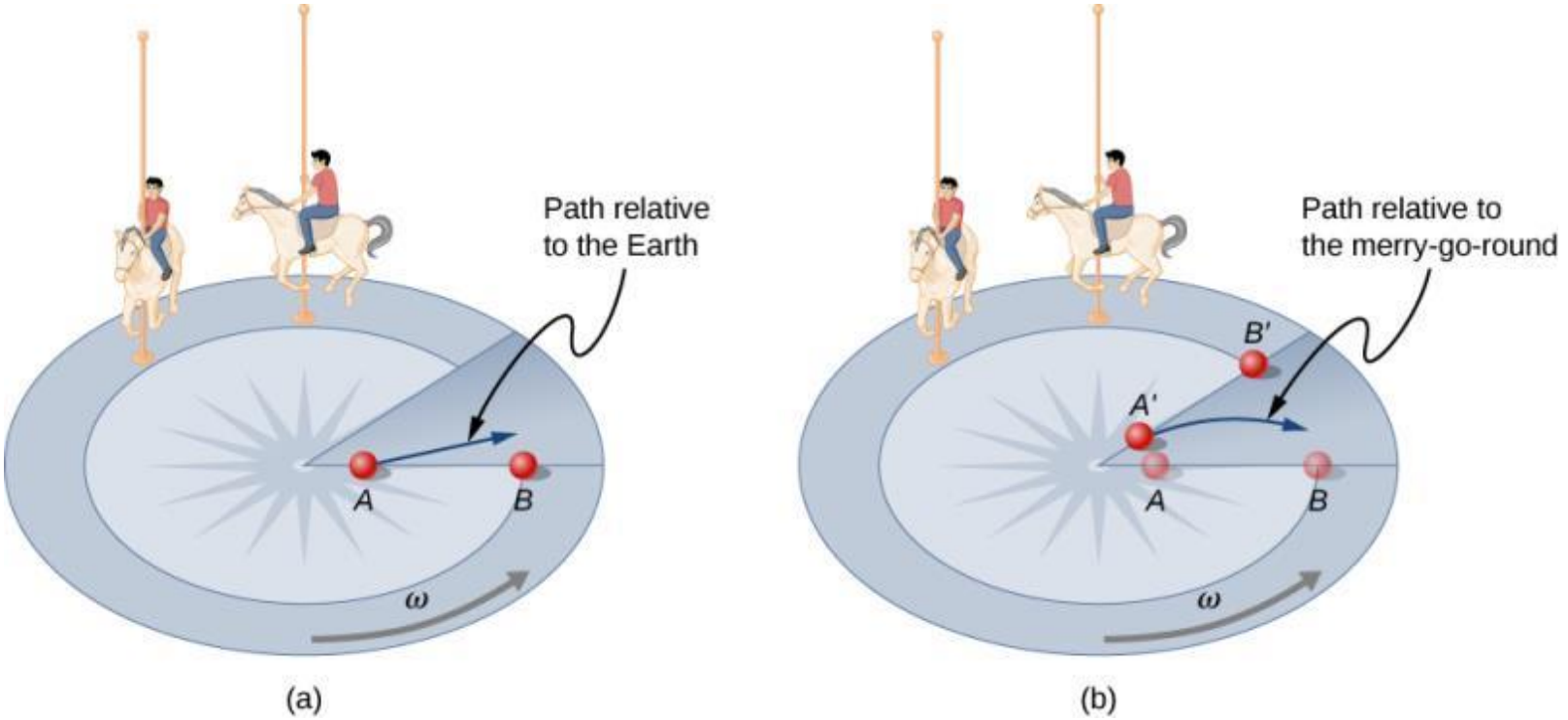
(b) In an inertial frame of reference and according to Newton's laws, it is his inertia that carries him off (the unshaded rider has and heads in a straight line). A force, , is needed to cause a circular path.

FIGURE 6.26



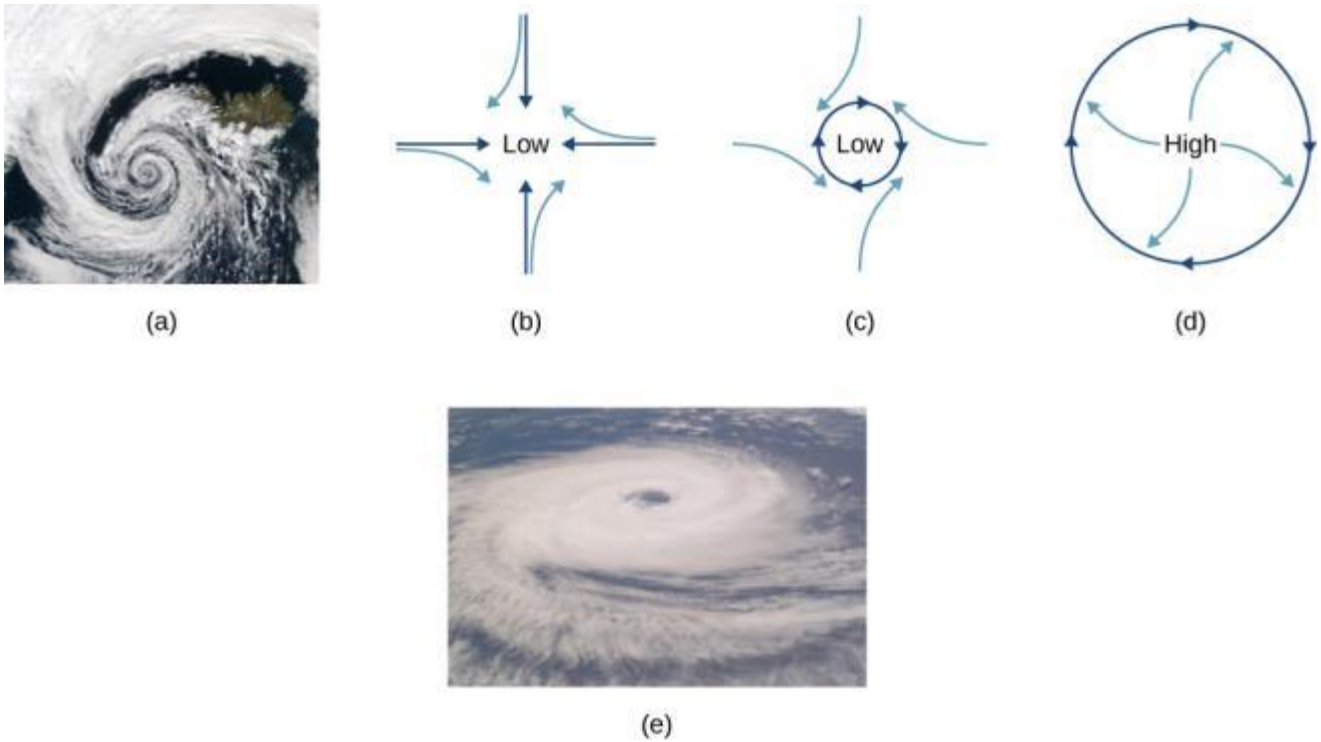
Centrifuges use inertia to perform their task. Particles in the fluid sediment settle out because their inertia carries them away from the center of rotation. The large angular velocity of the centrifuge quickens the sedimentation. Ultimately, the particles come into contact with the test tube walls, which then supply the centripetal force needed to make them move in a circle of constant radius.

FIGURE 6.27



Looking down on the counterclockwise rotation of a merry-go-round, we see that a ball slid straight toward the edge follows a path curved to the right. The person slides the ball toward point *B*, starting at point *A*. Both points rotate to the shaded positions (*A*' and *B*') shown in the time that the ball follows the curved path in the rotating frame and a straight path in Earth's frame.

FIGURE 6.28



(a) The counterclockwise rotation of this Northern Hemisphere hurricane is a major consequence of the Coriolis force.

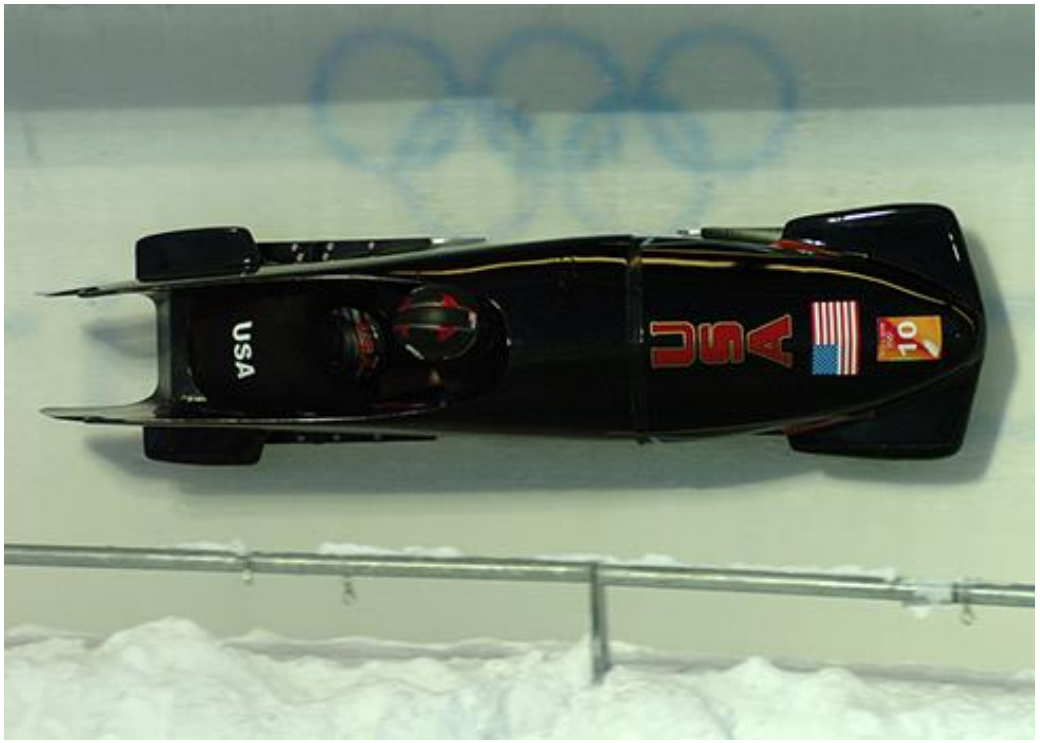
(b) Without the Coriolis force, air would flow straight into a low-pressure zone, such as that found in tropical cyclones.

(c) The Coriolis force deflects the winds to the right, producing a counterclockwise rotation.

(d) Wind flowing away from a high-pressure zone is also deflected to the right, producing a clockwise rotation.

(e) The opposite direction of rotation is produced by the Coriolis force in the Southern Hemisphere, leading to tropical cyclones. (credit a and credit e: modifications of work by NASA)

FIGURE 6.29



From racing cars to bobsled racers, aerodynamic shaping is crucial to achieving top speeds. Bobsleds are designed for speed and are shaped like a bullet with tapered fins. (credit: “U.S. Army”/Wikimedia Commons)

FIGURE 6.30

NASA researchers test a model plane in a wind tunnel. (credit: NASA/Ames)

FIGURE 6.31

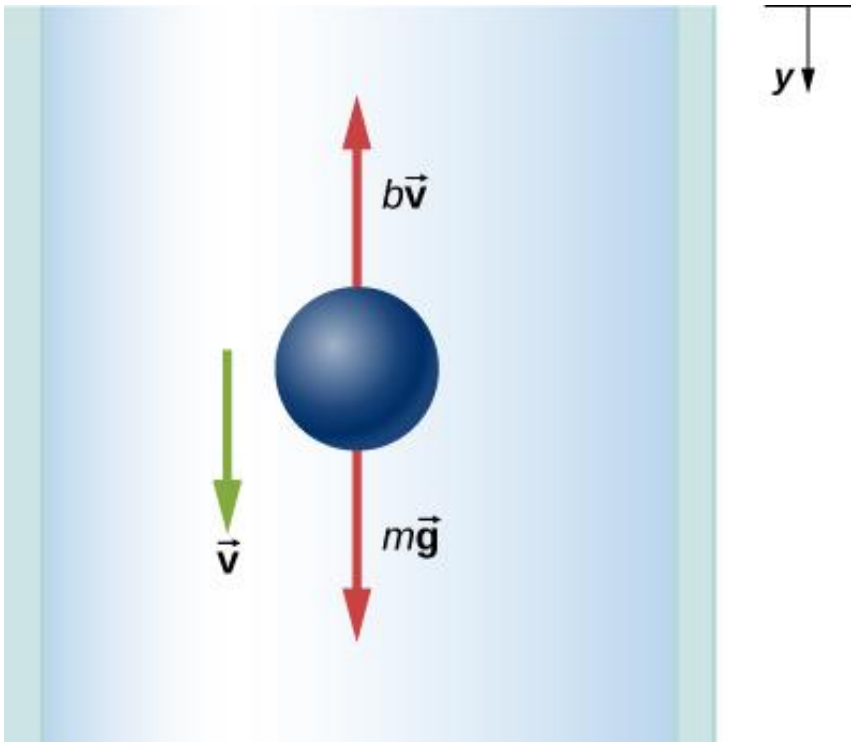
Body suits, such as this LZR Racer Suit, have been credited with aiding in many world records after their release in 2008. Smoother “skin” and more compression forces on a swimmer’s body provide at least 10% less drag. (credit: NASA/Kathy Barnstorff)

FIGURE 6.32

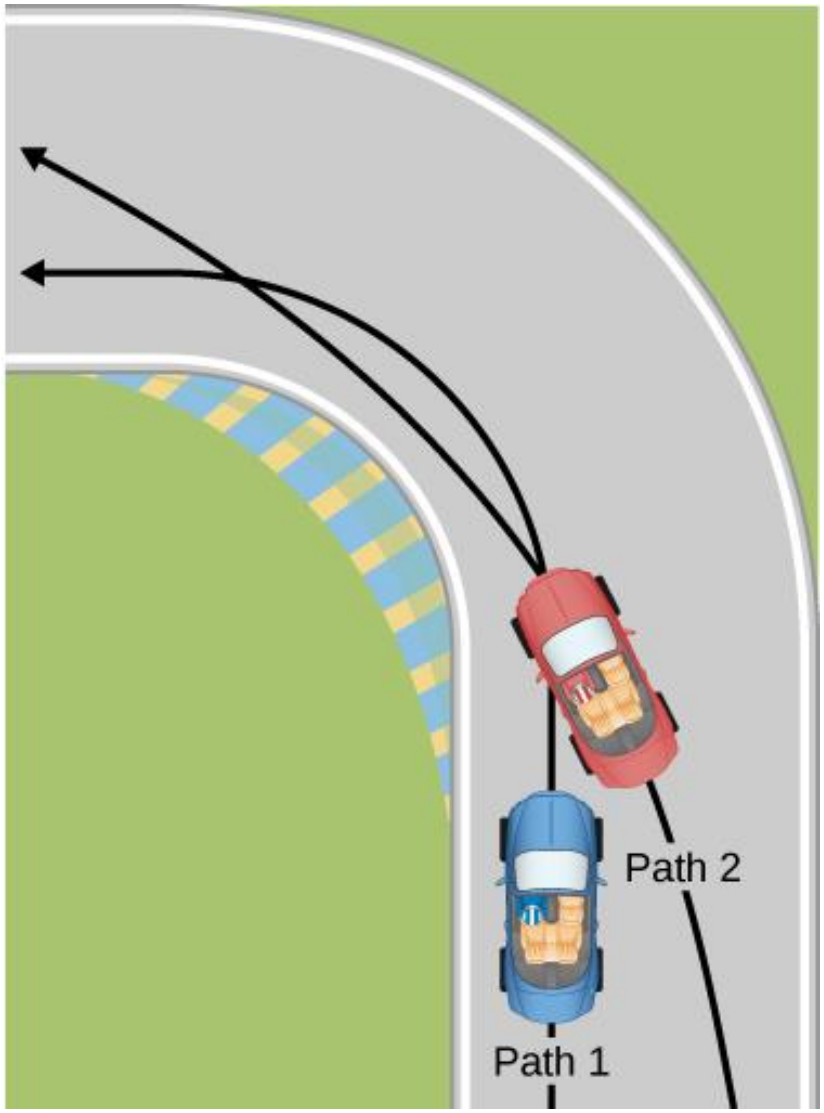
Geese fly in a V formation during their long migratory travels. This shape reduces drag and energy consumption for individual birds, and also allows them a better way to communicate. (credit: “Julo”/Wikimedia Commons)

FIGURE 6.33

Free-body diagram of an object falling through a resistive medium.

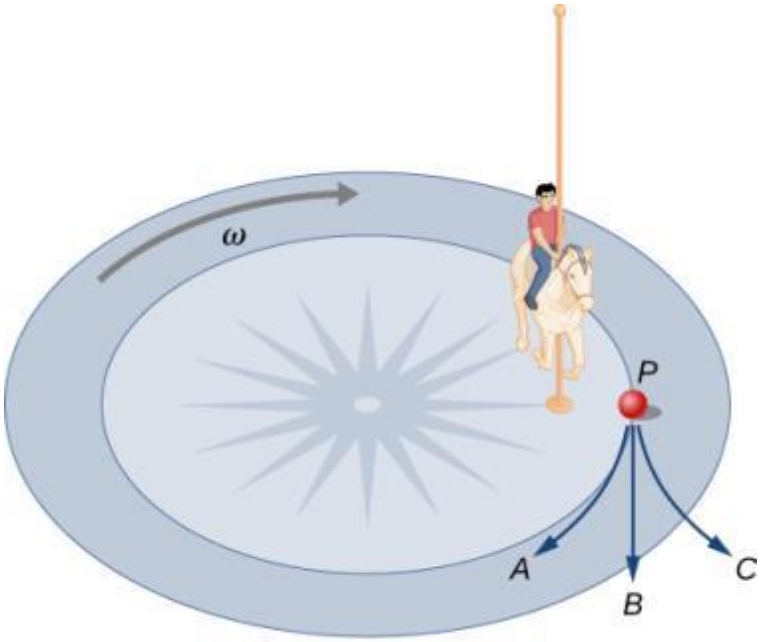


EXERCISE 9



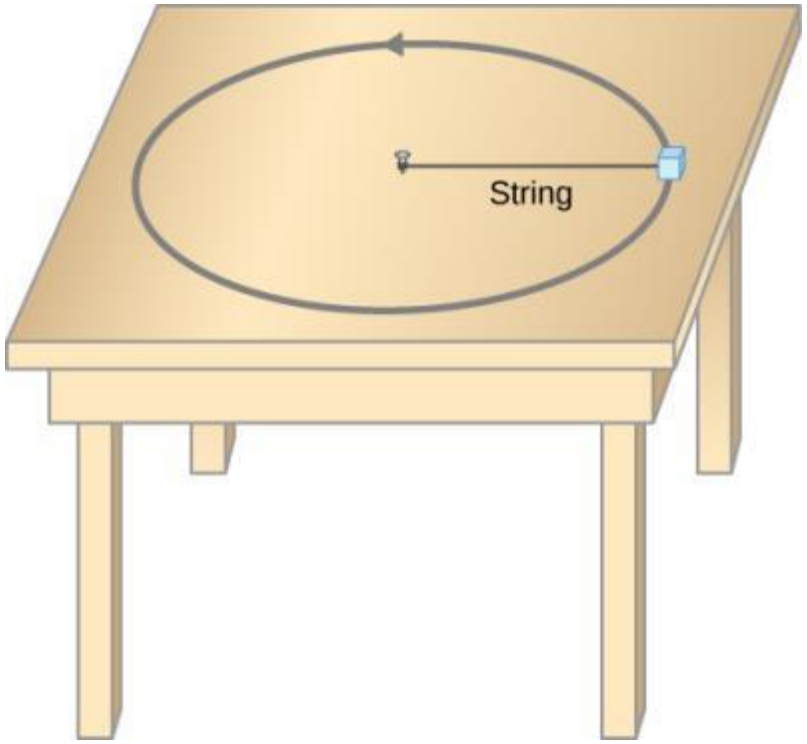
EXERCISE 11

EXERCISE 13

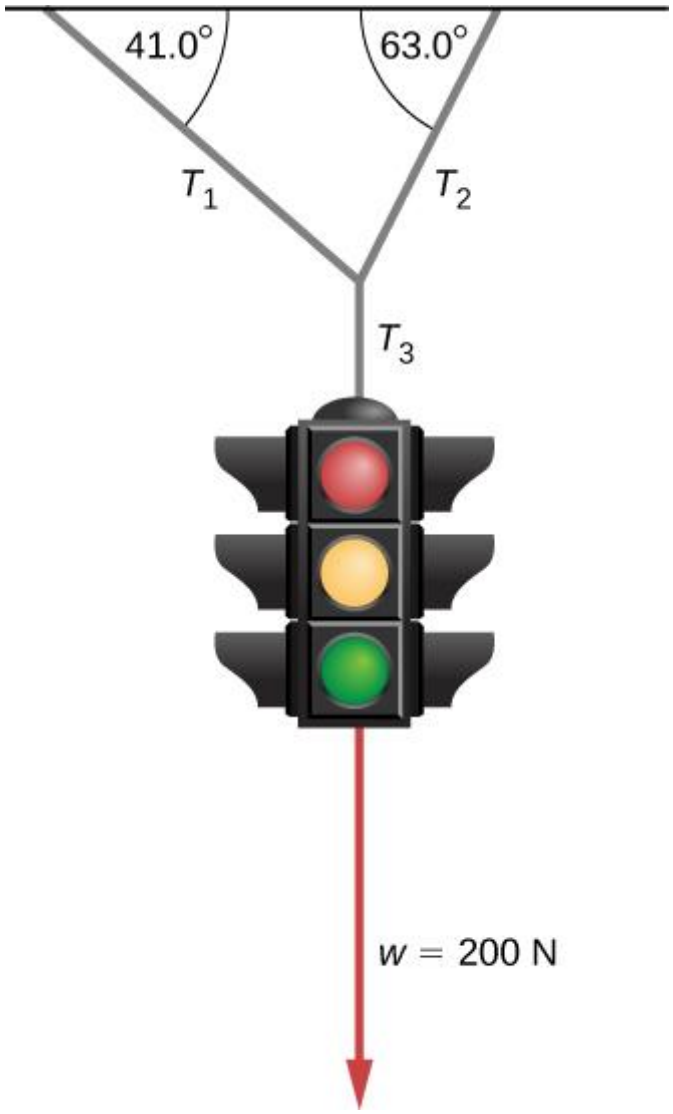


Merry-go-round's rotating frame of reference

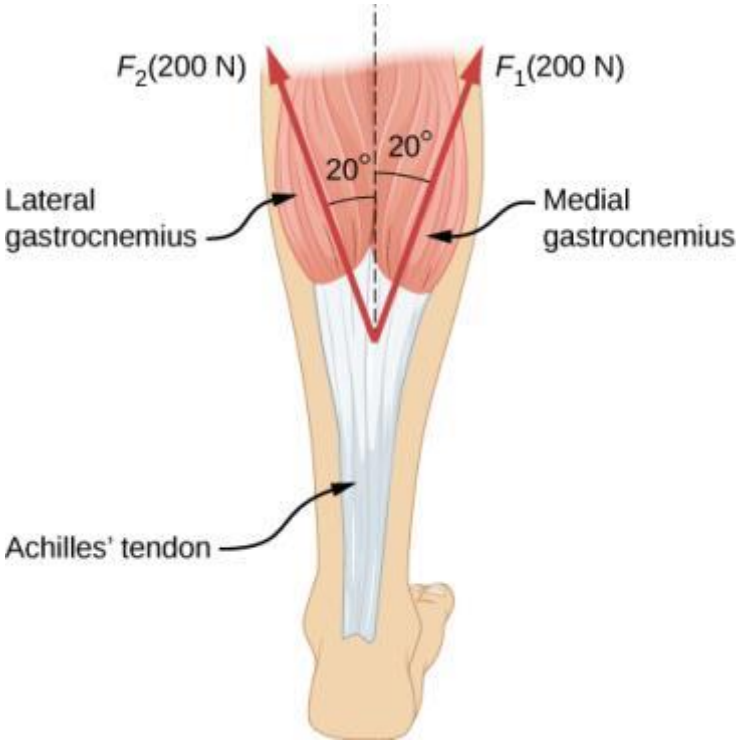
EXERCISE 15



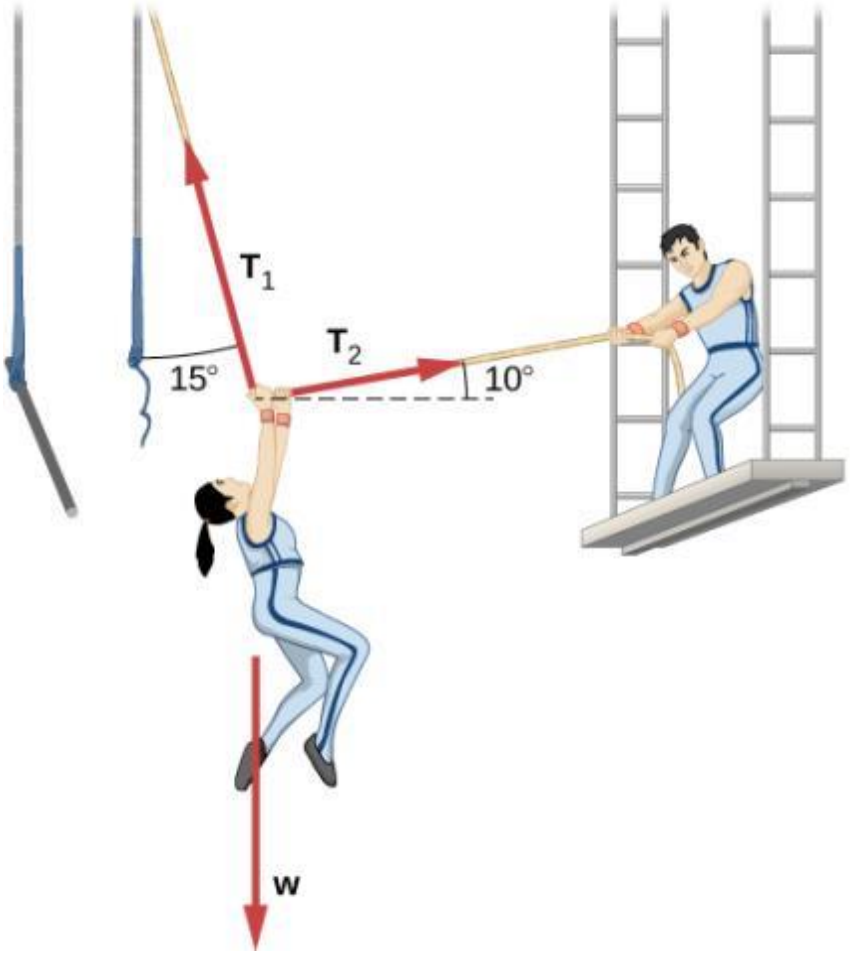
EXERCISE 26



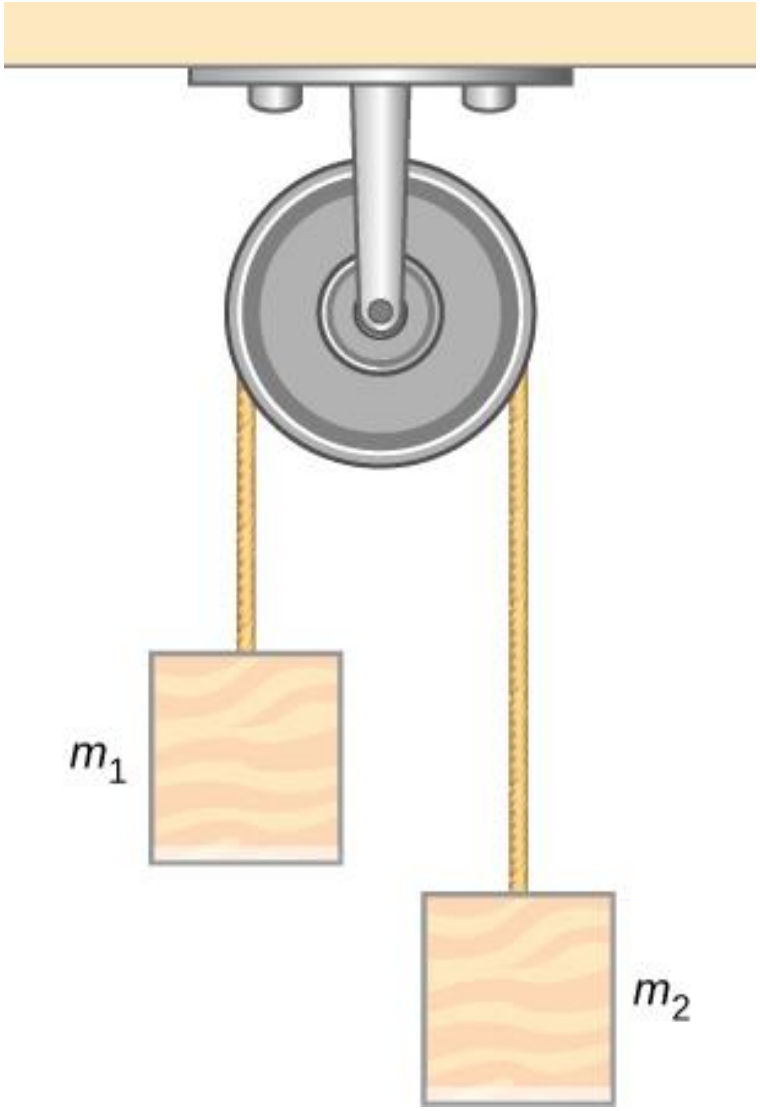
EXERCISE 29


F_2(200 N)
F_1(200 N)
20°
20°
Lateral gastrocnemius
Medial gastrocnemius
Achilles' tendon

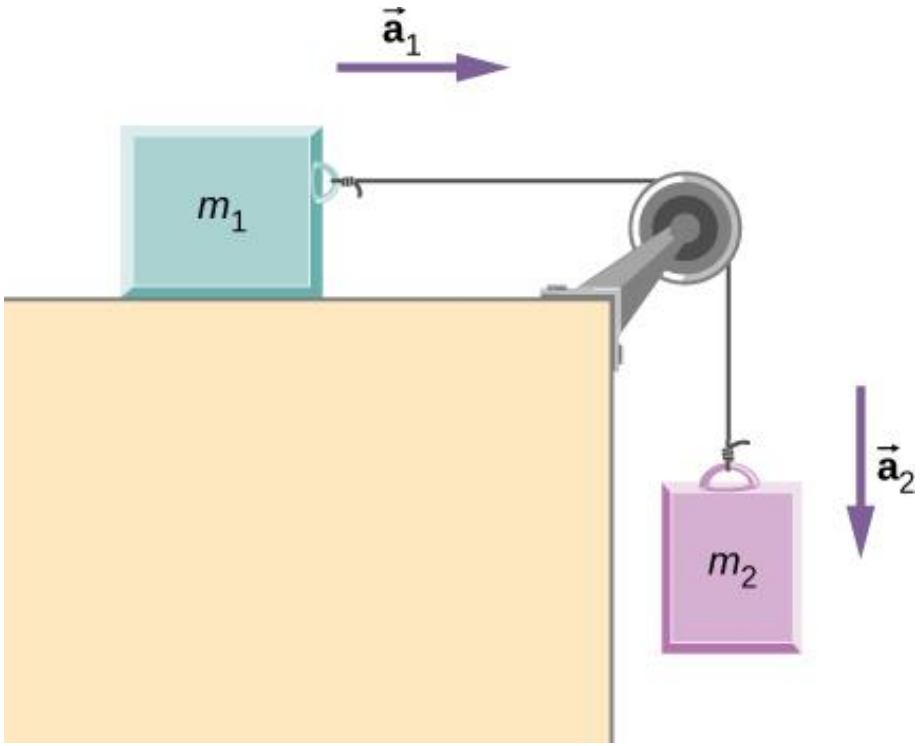
EXERCISE 30



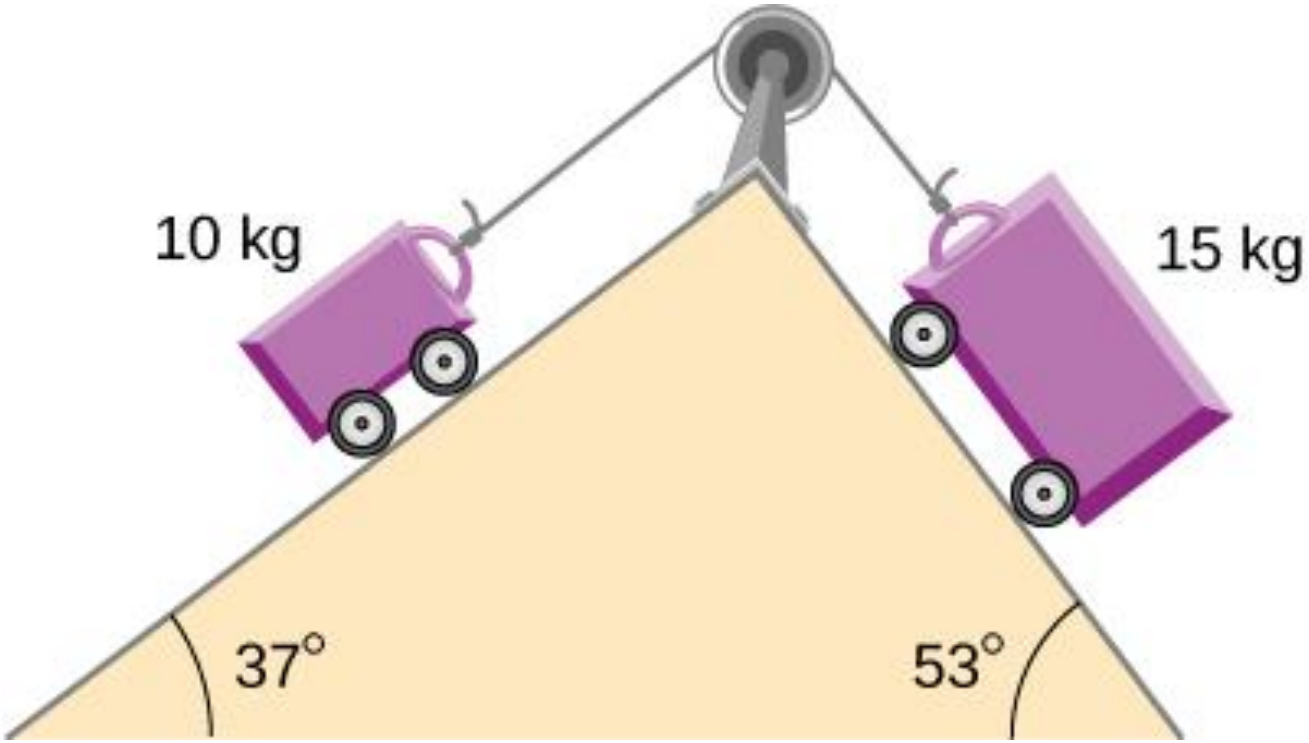
EXERCISE 42



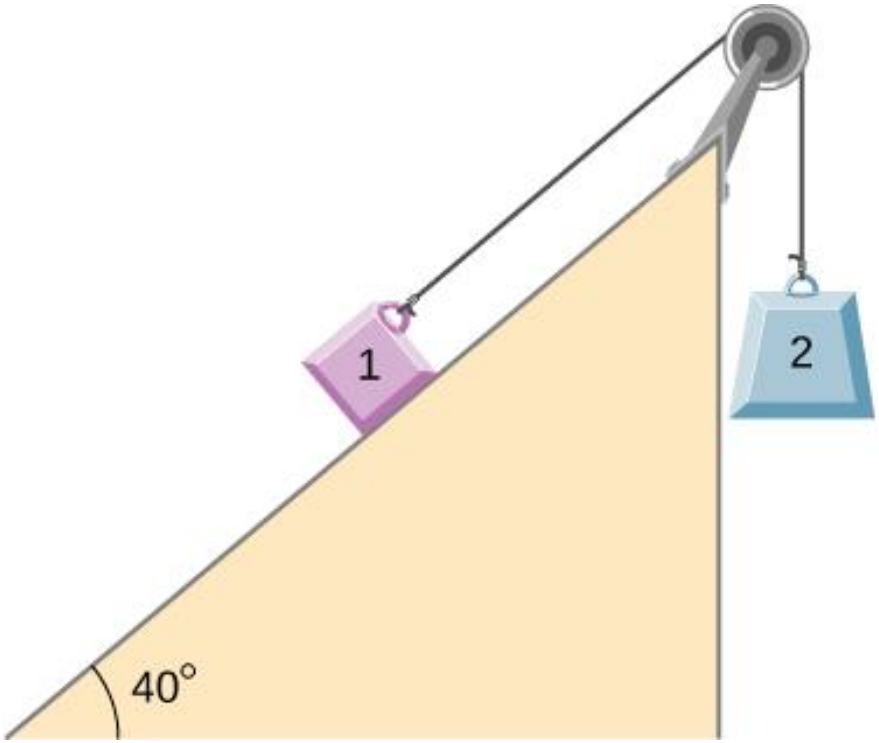
EXERCISE 43



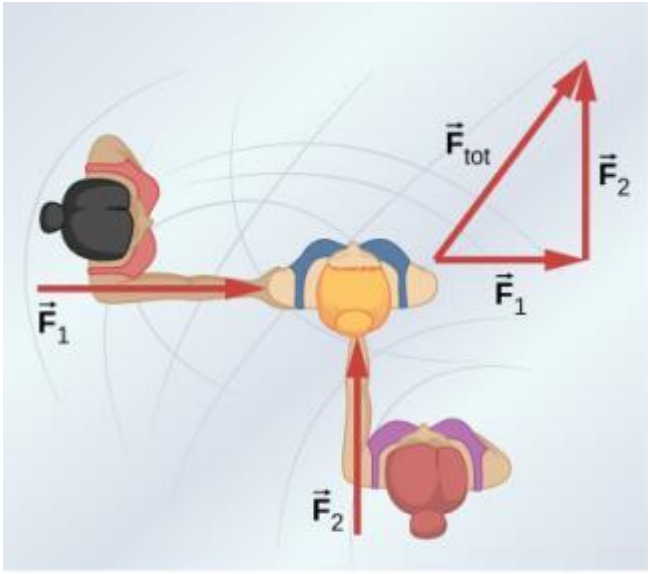
EXERCISE 44



EXERCISE 45

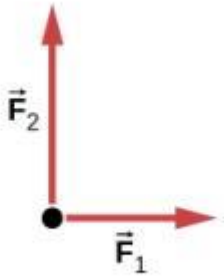


EXERCISE 51



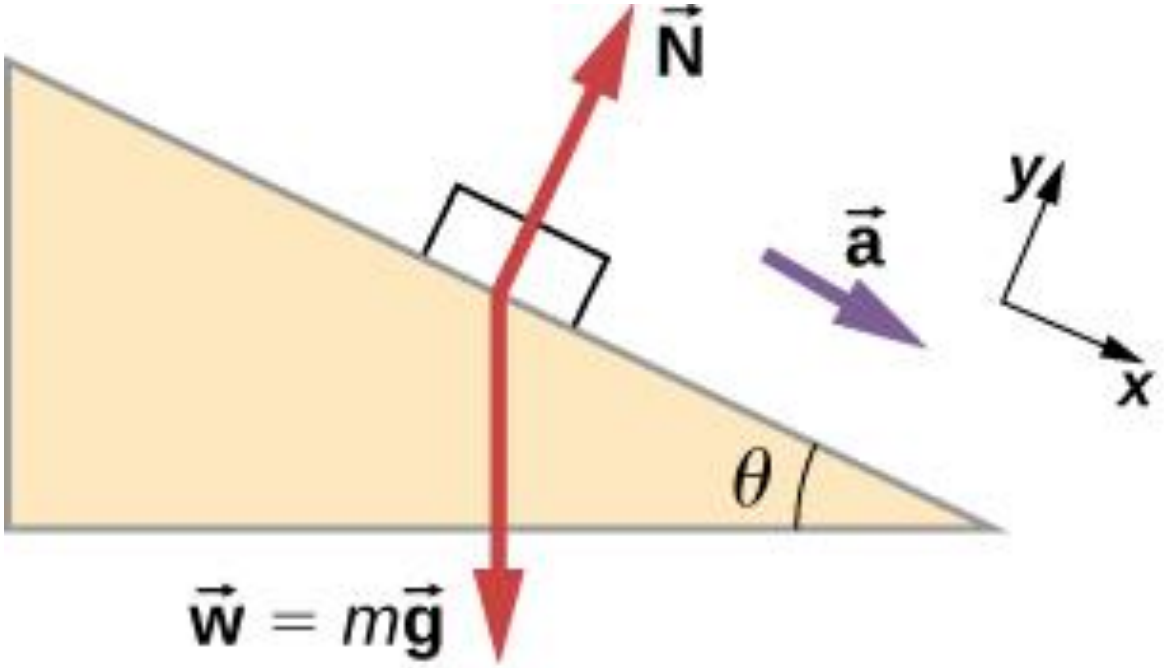
(a)

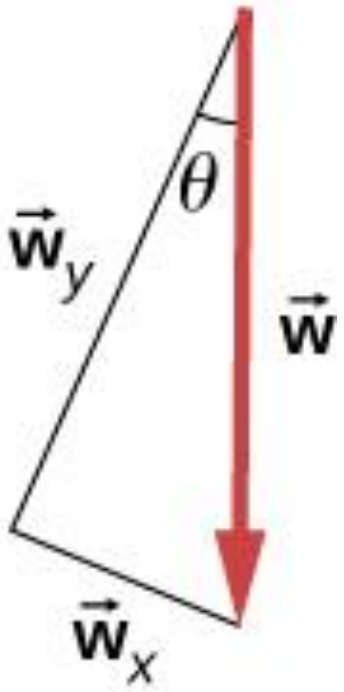
Free-body diagram



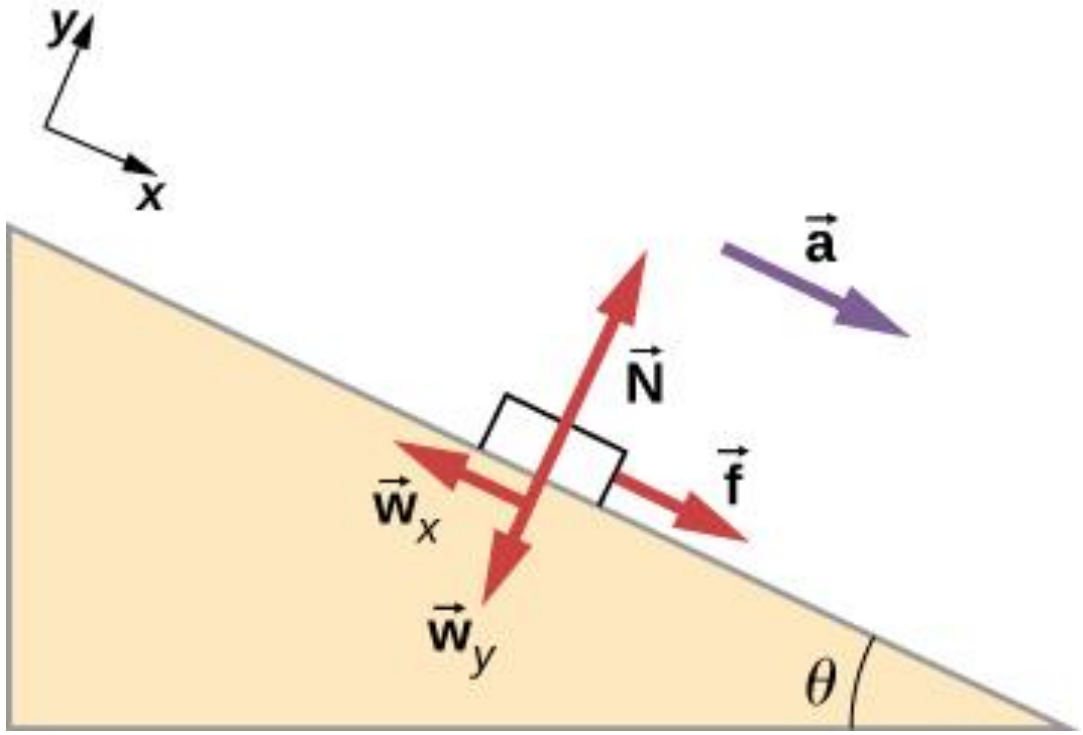
(b)

EXERCISE 52

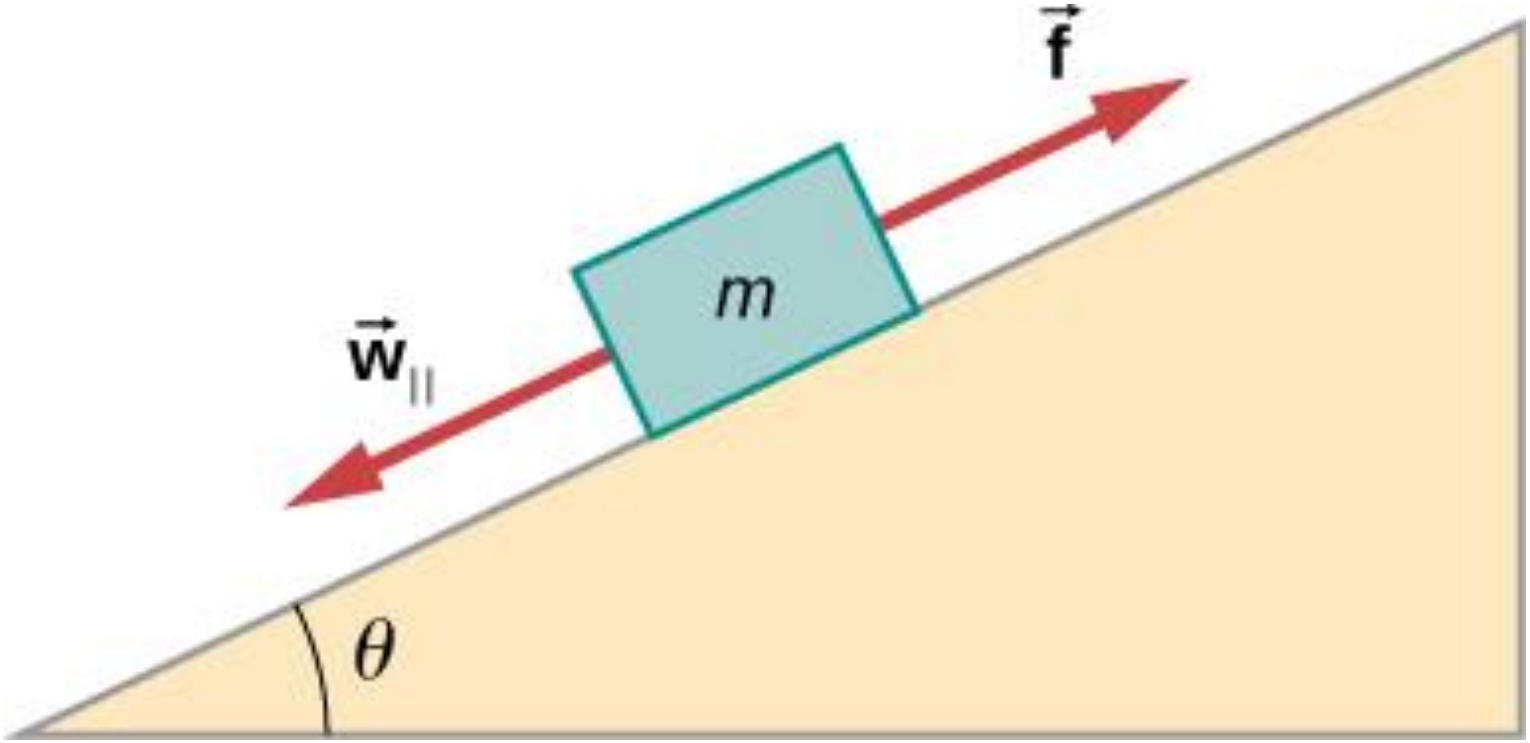




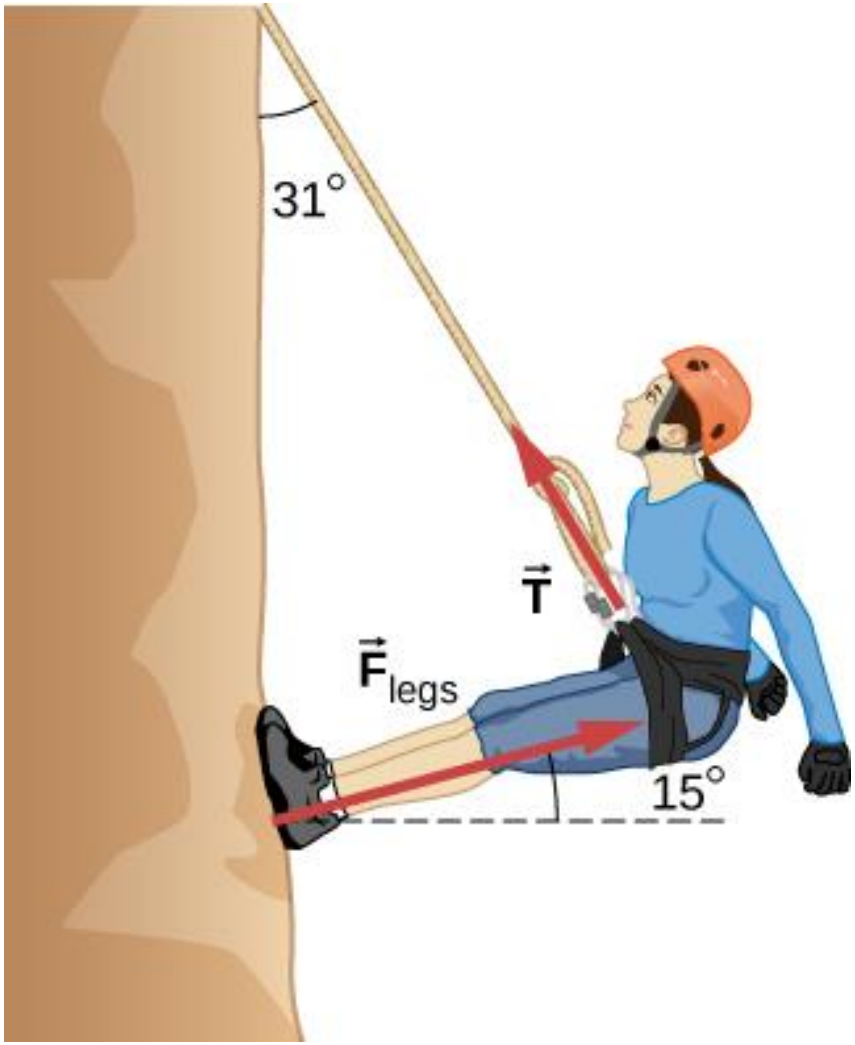
EXERCISE 53



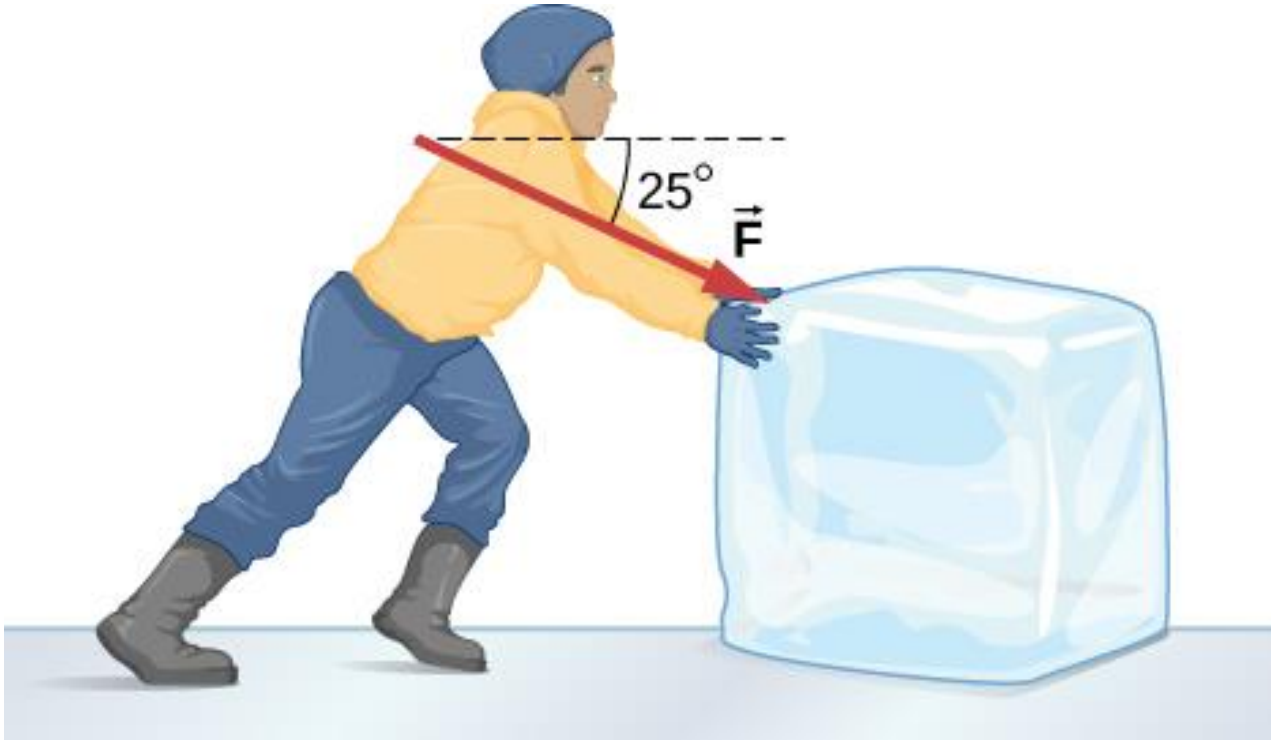
EXERCISE 56



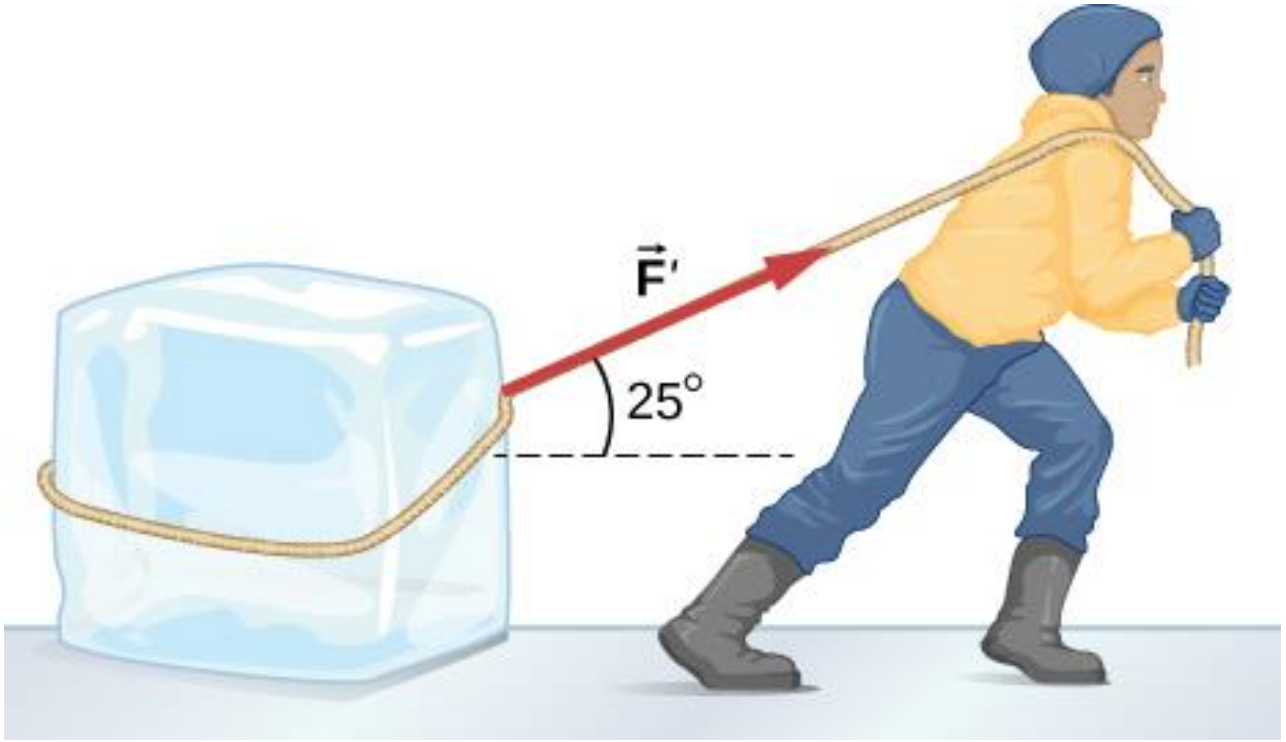
EXERCISE 61



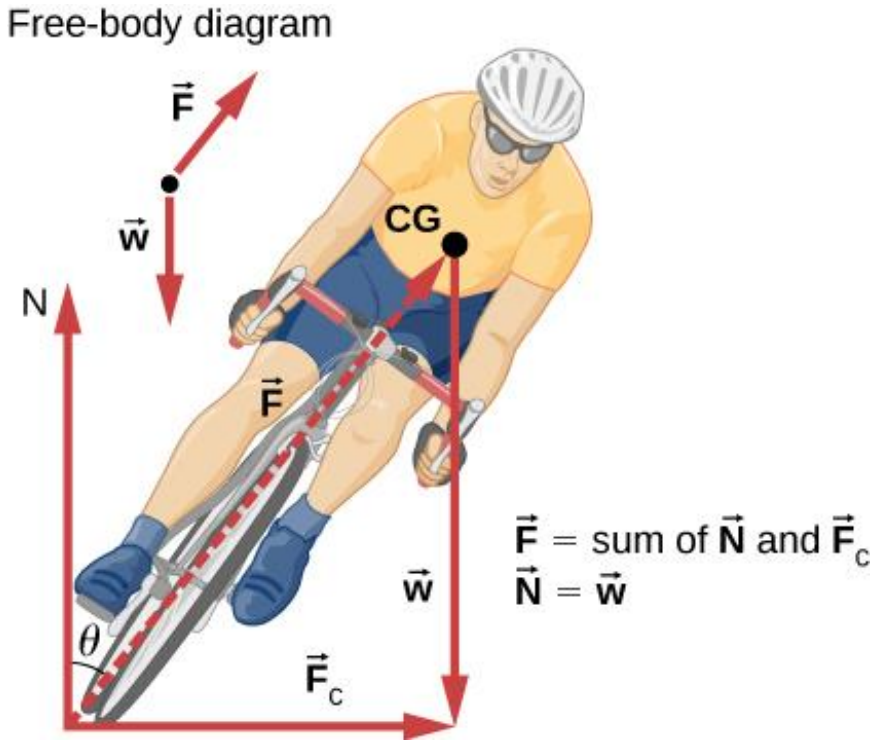
EXERCISE 62



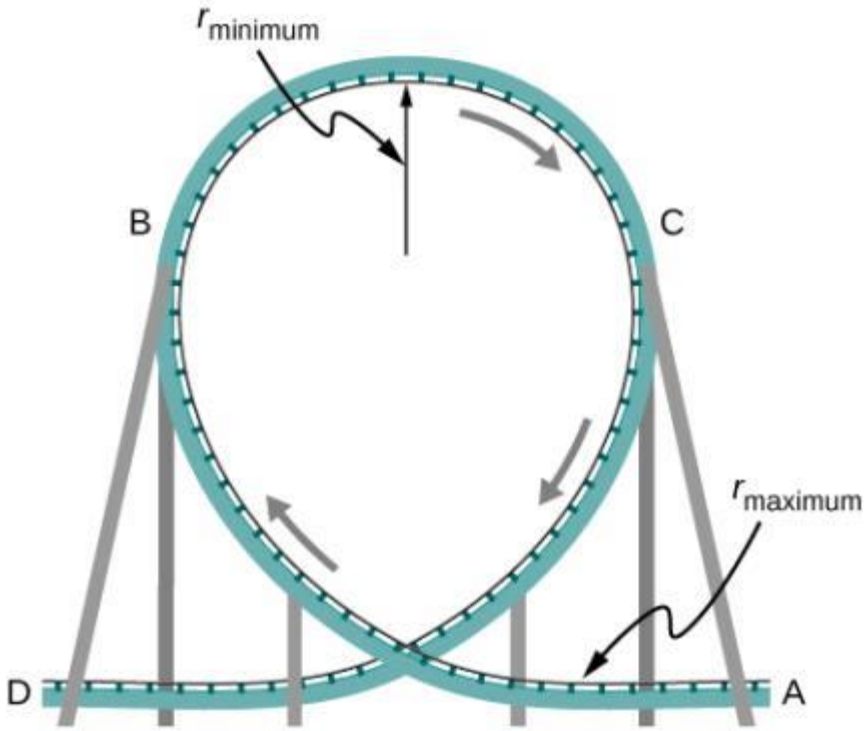
EXERCISE 63



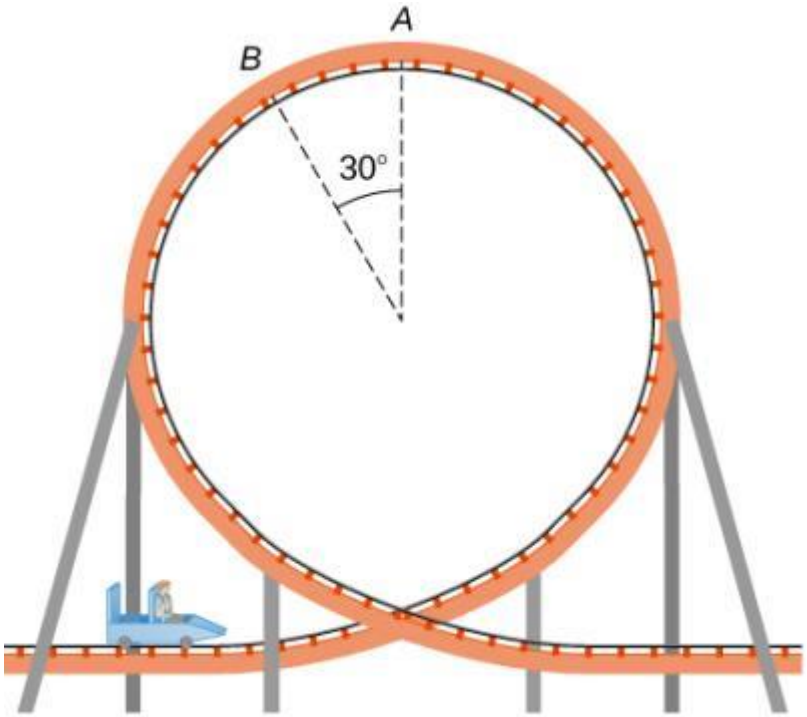
EXERCISE 70


Free-body diagram
$\vec{F}$
$\vec{w}$
N
CG
$\vec{F}$
$\vec{w}$
θ
$\vec{F}_c$
$\vec{F}$ = sum of $\vec{N}$ and $\vec{F}_c$
$\vec{N} = \vec{w}$

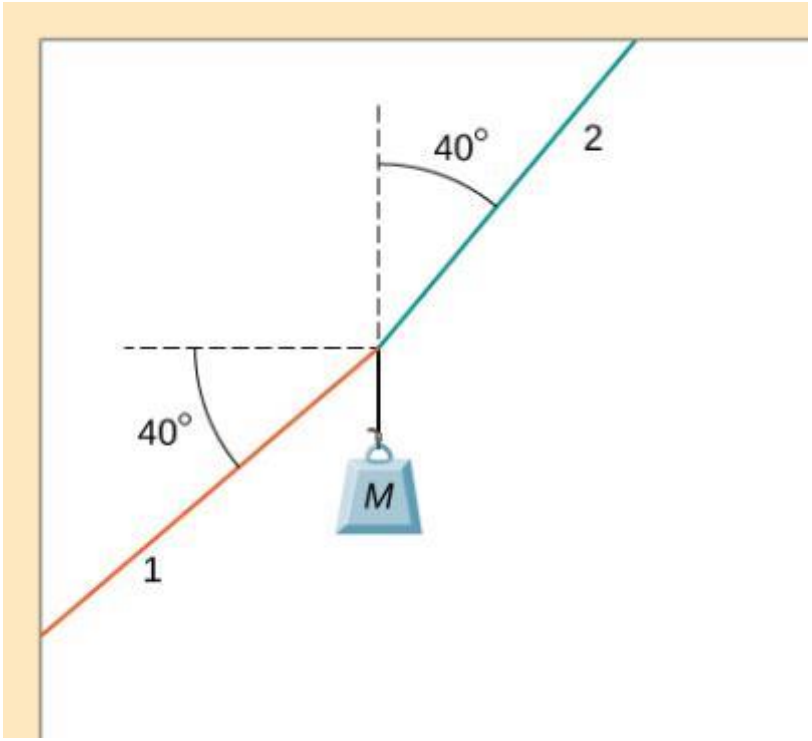
EXERCISE 72



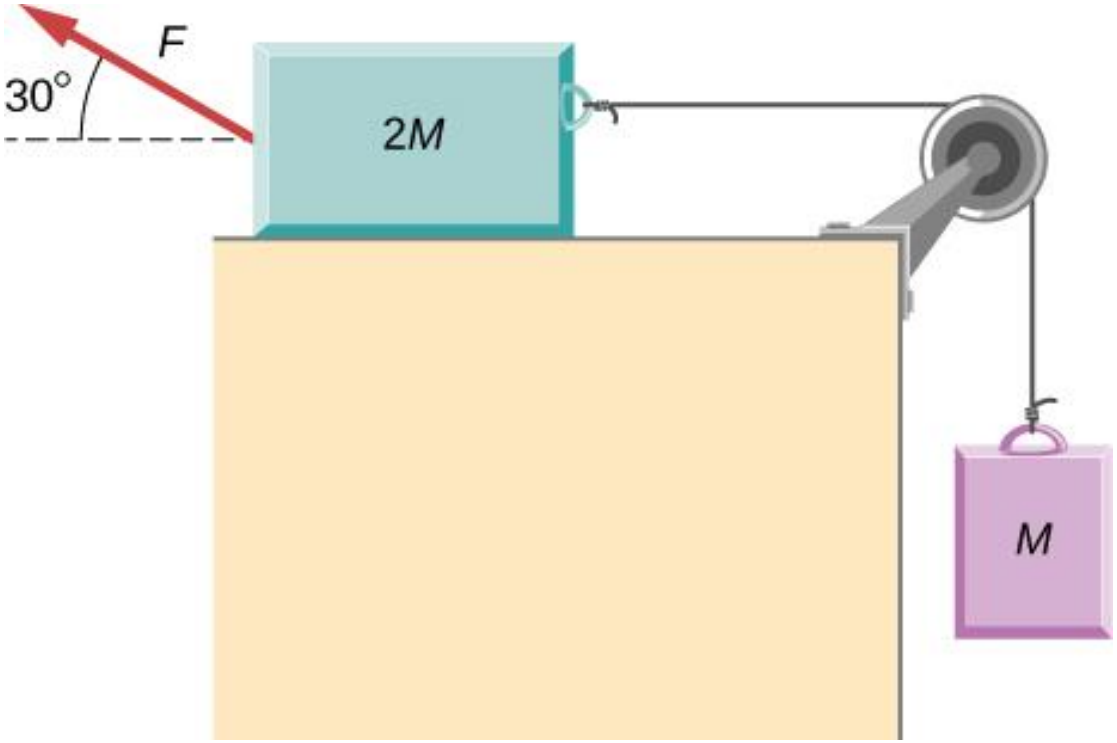
EXERCISE 73



EXERCISE 93

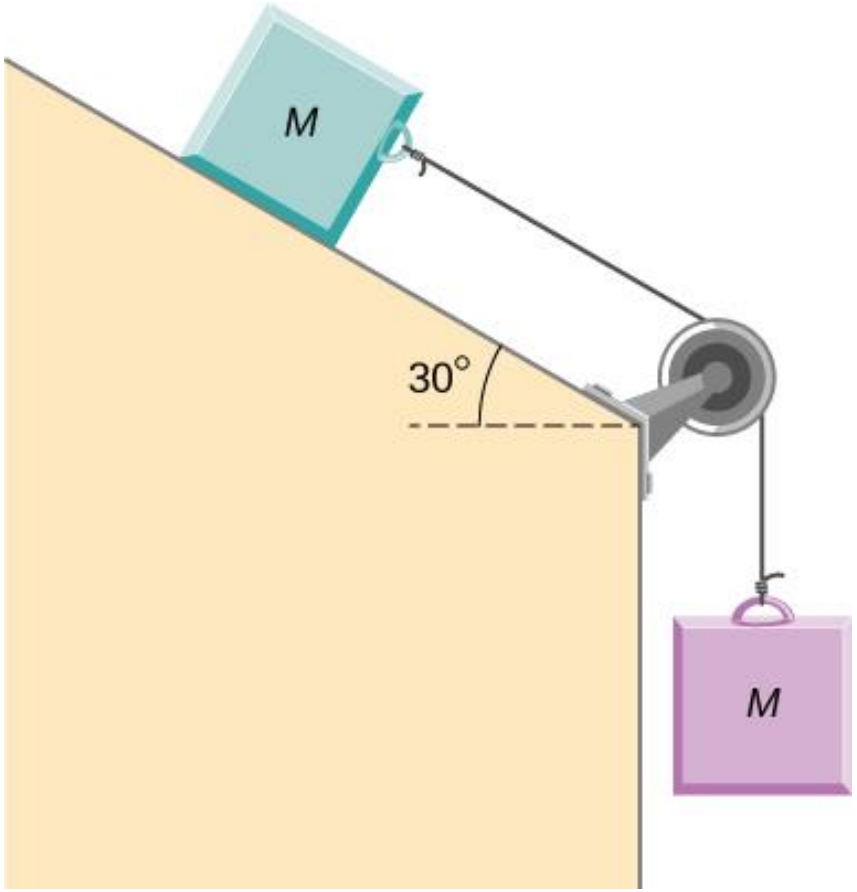


EXERCISE 94

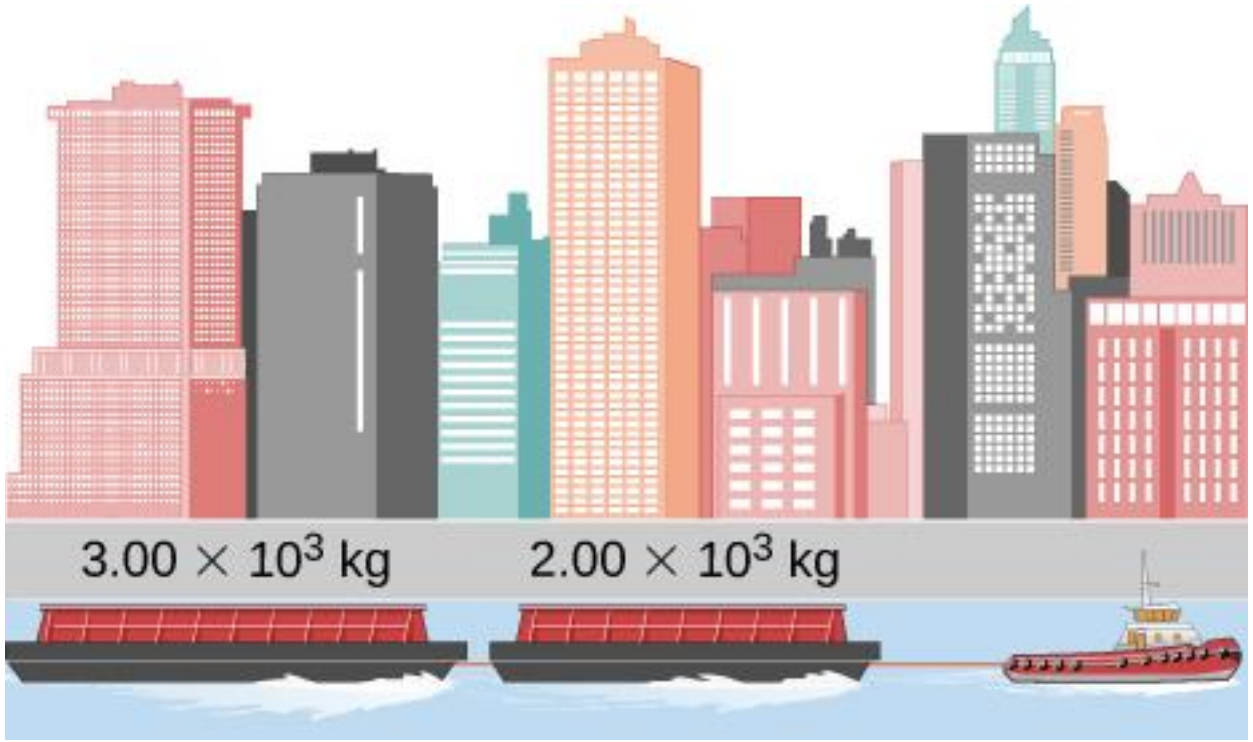


openstax™

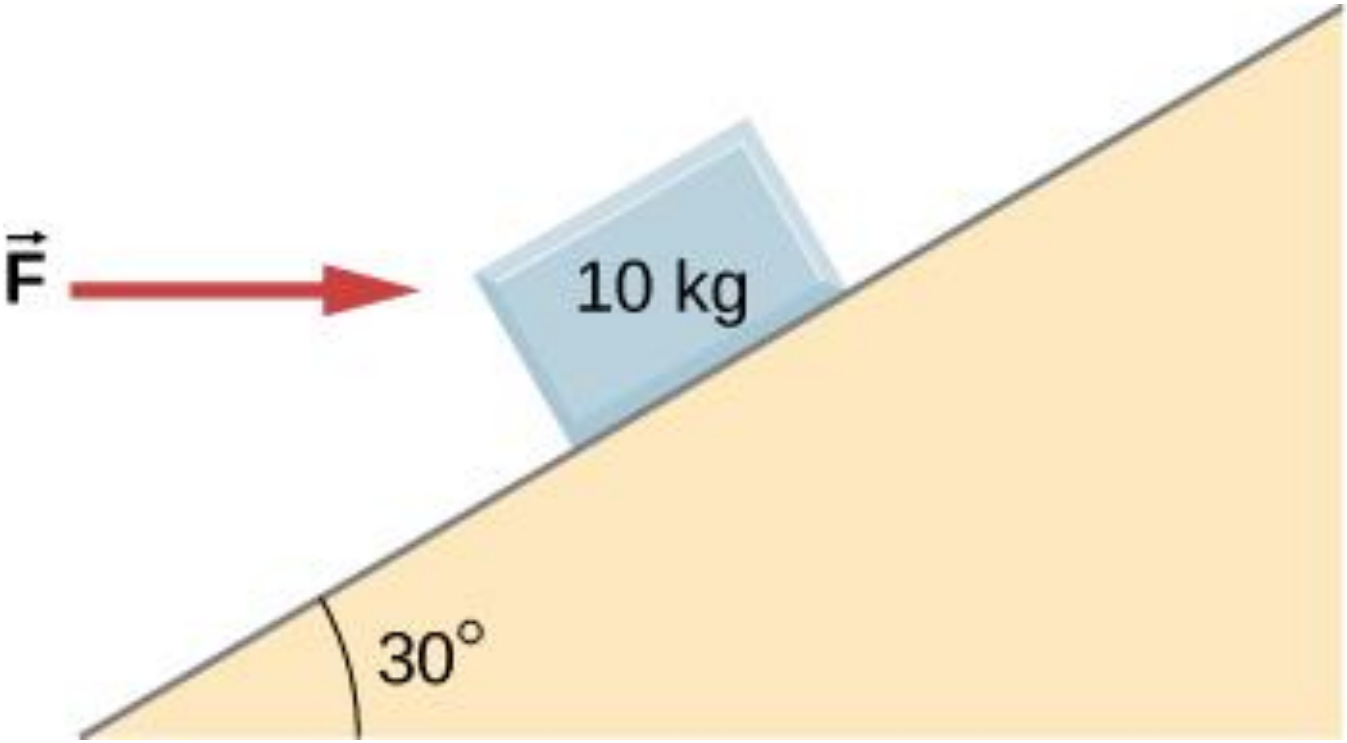
EXERCISE 95



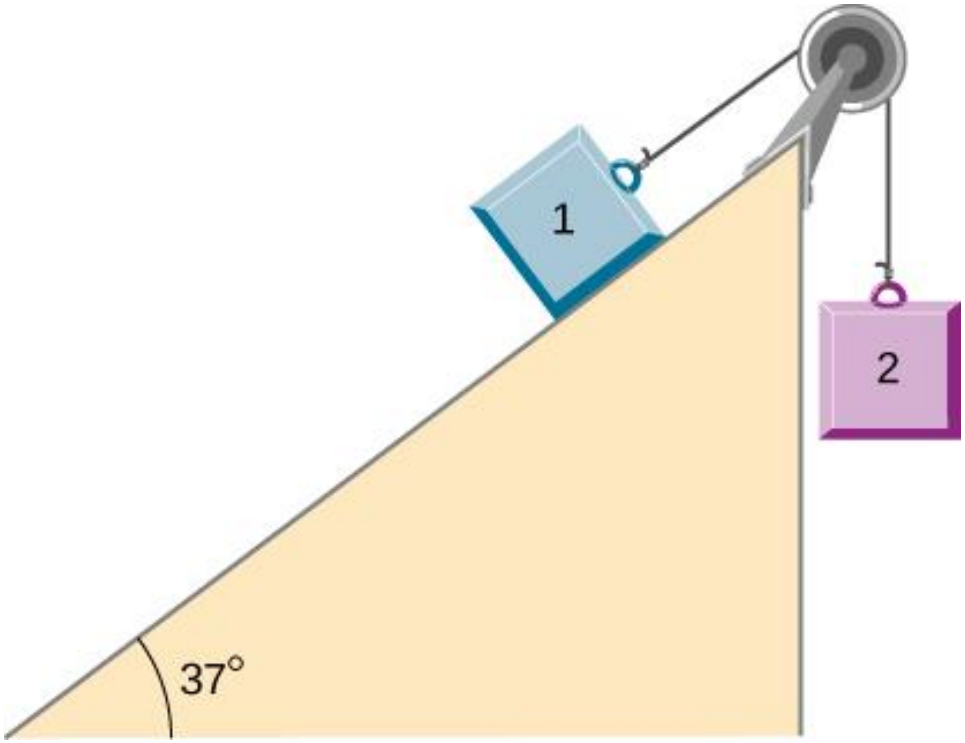
EXERCISE 99



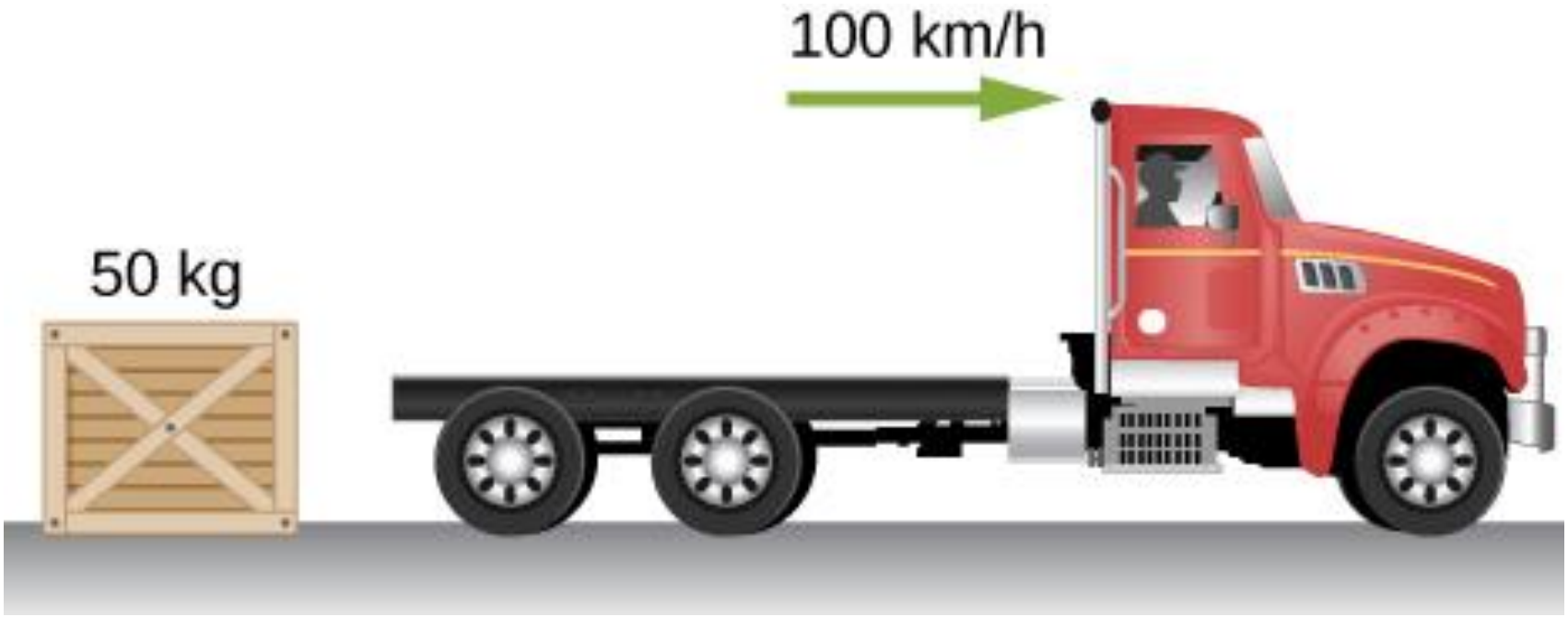
EXERCISE 108



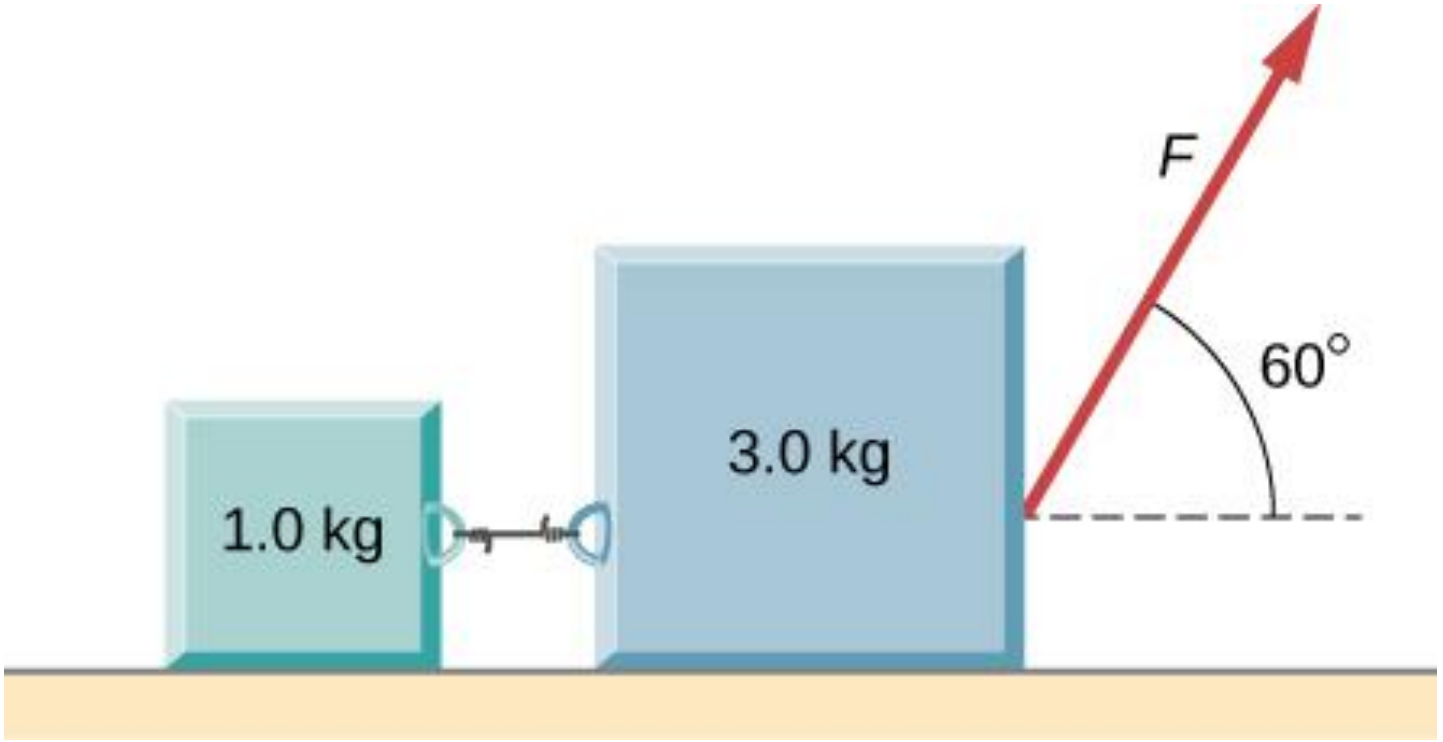
EXERCISE 109



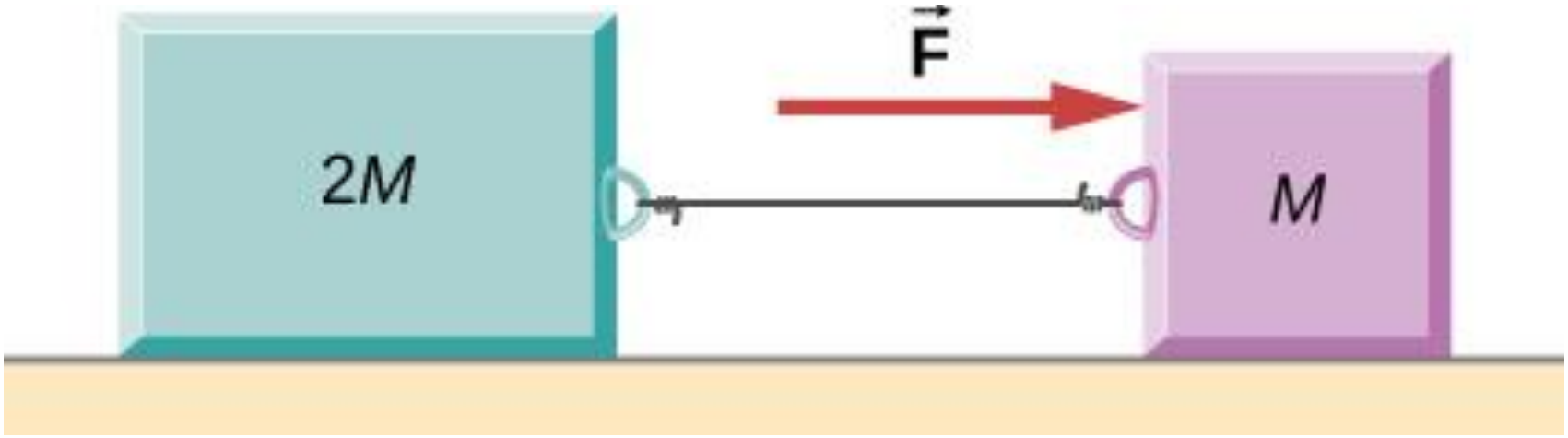
EXERCISE 113



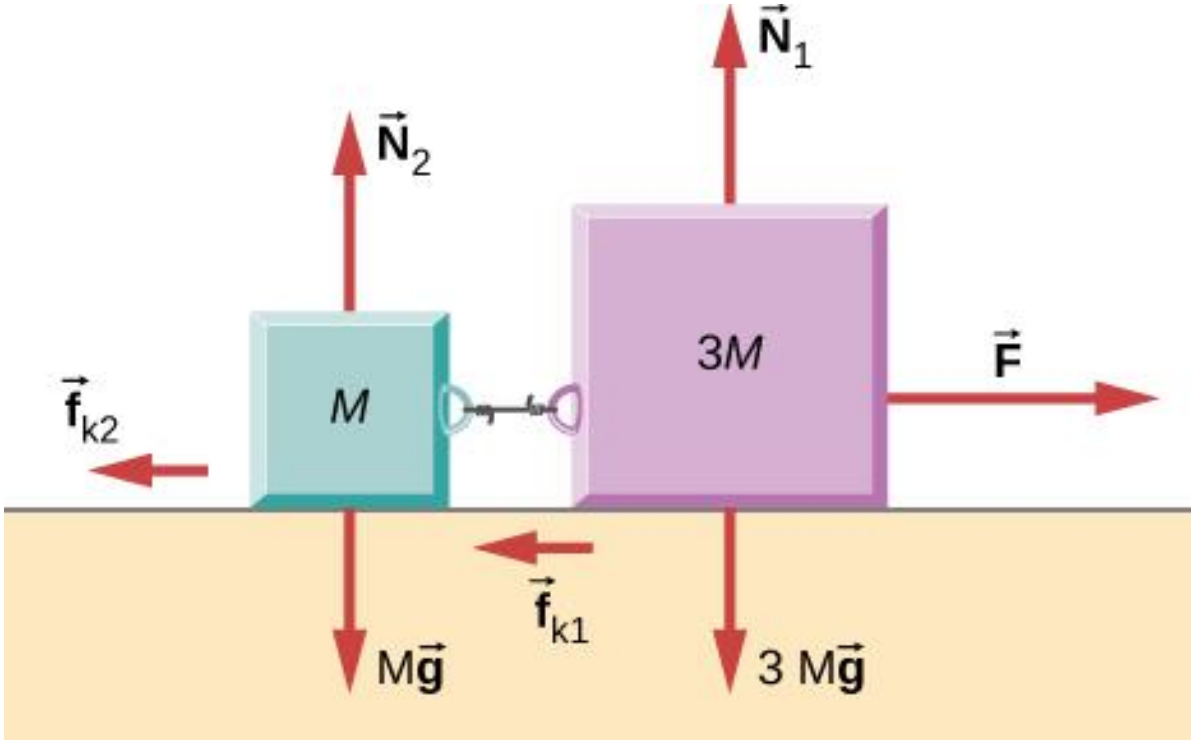
EXERCISE 123



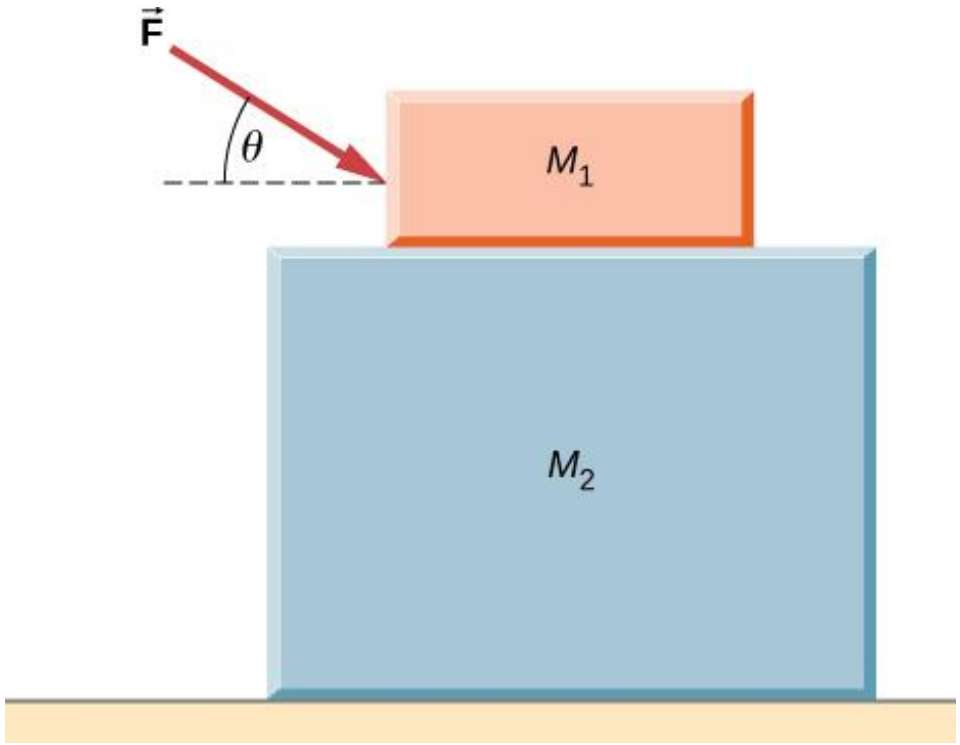
EXERCISE 124



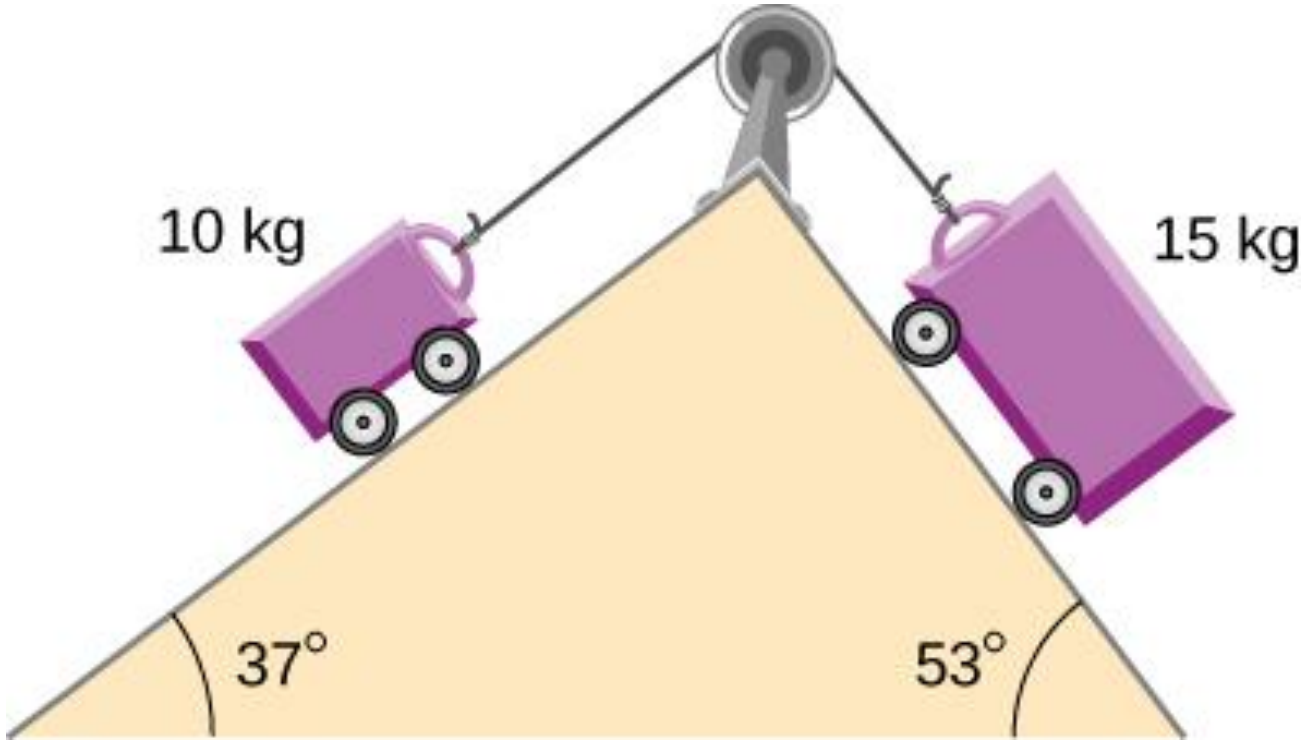
EXERCISE 125



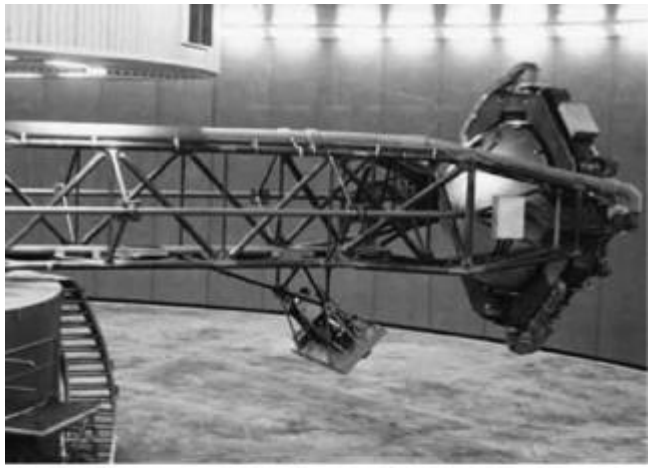
EXERCISE 126



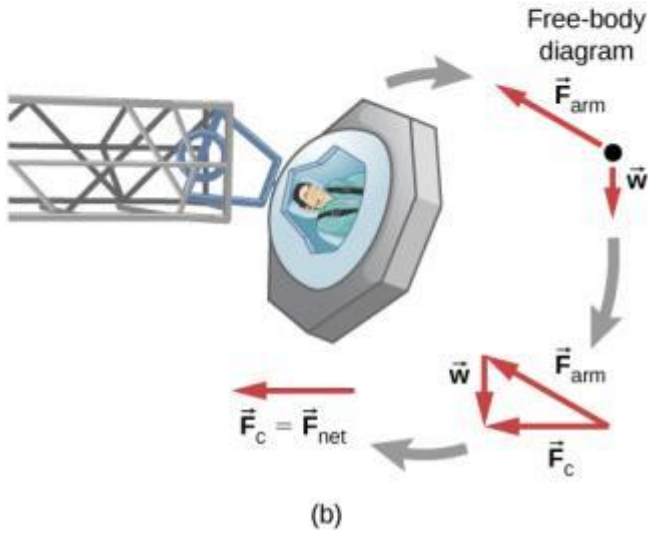
EXERCISE 128



EXERCISE 130



(a)



(b)

This OpenStax ancillary resource is © Rice University under a CC-BY 4.0 International license; it may be reproduced or modified but must be attributed to OpenStax, Rice University and any changes must be noted.