

UNIVERSITY PHYSICS

Chapter 2 VECTORS

PowerPoint Image Slideshow

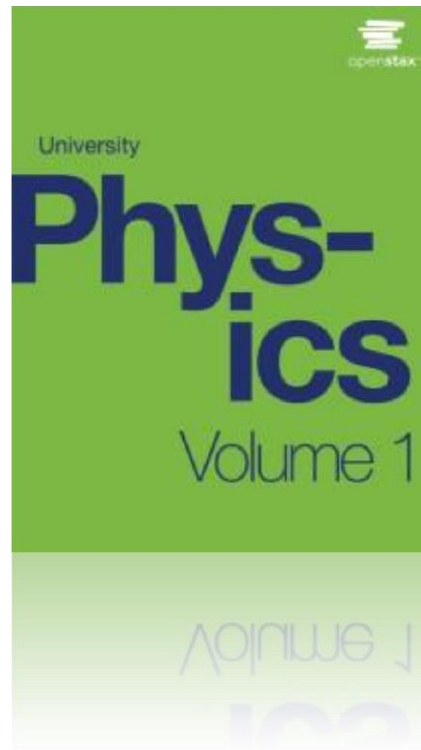
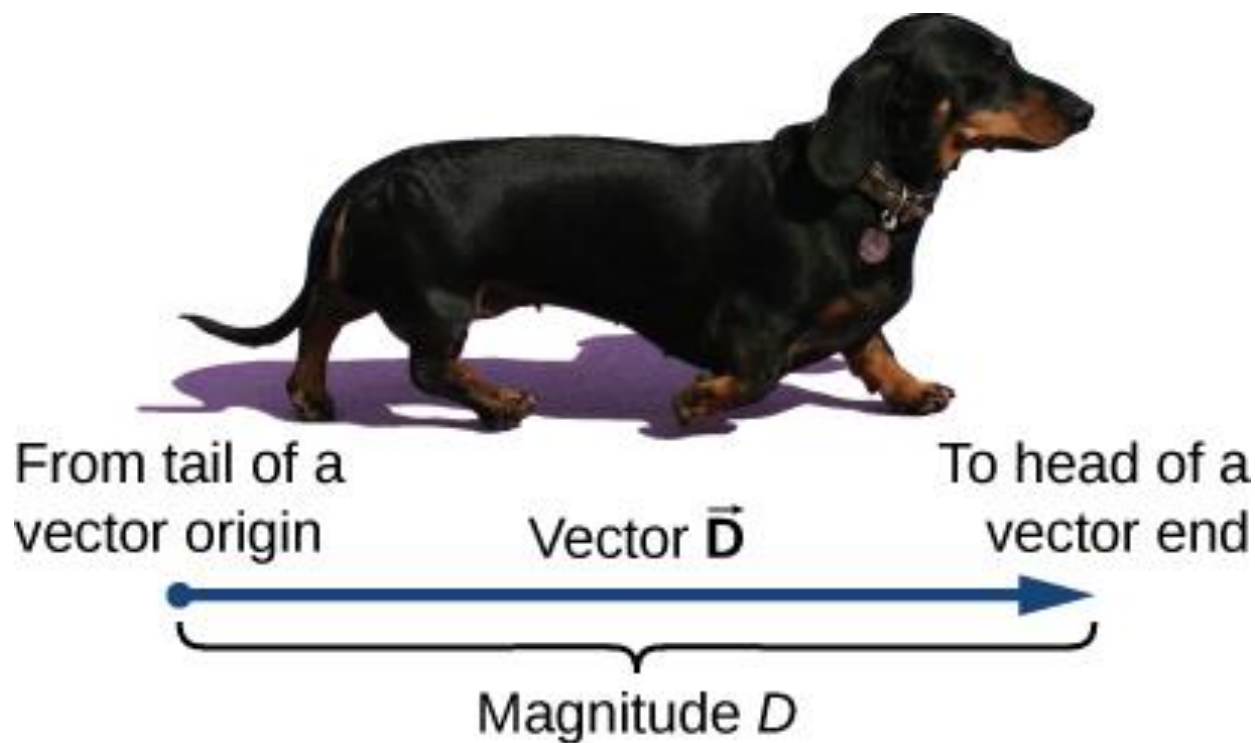


FIGURE 2.1



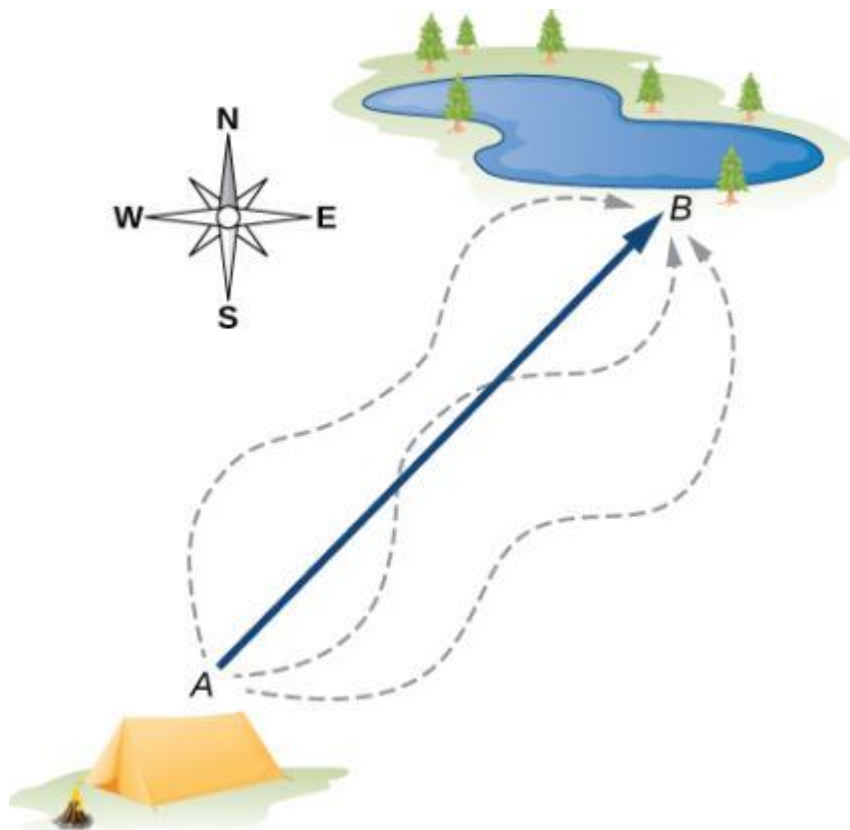
A signpost gives information about distances and directions to towns or to other locations relative to the location of the signpost. Distance is a scalar quantity. Knowing the distance alone is not enough to get to the town; we must also know the direction from the signpost to the town. The direction, together with the distance, is a vector quantity commonly called the displacement vector. A signpost, therefore, gives information about displacement vectors from the signpost to towns. (credit: modification of work by “studio tdes”/Flickr)

FIGURE 2.2



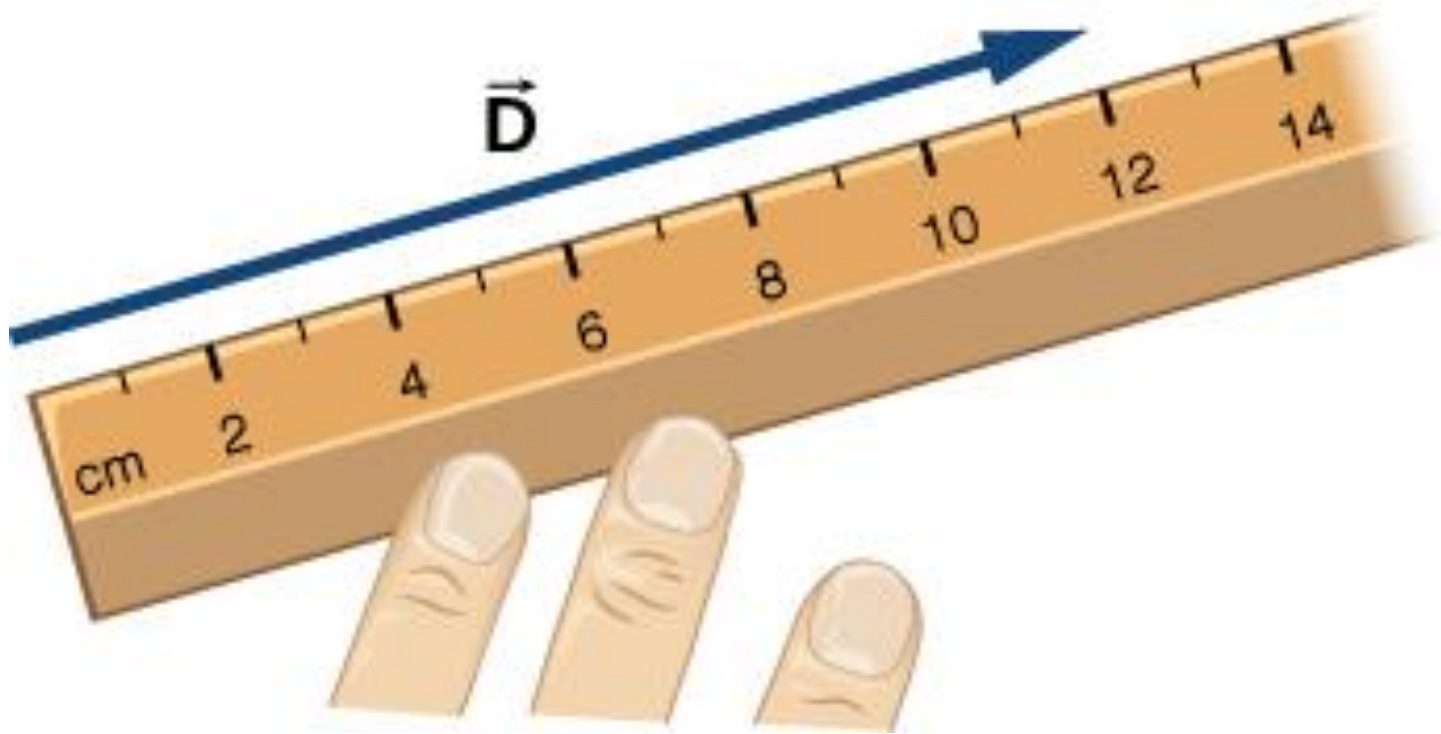
We draw a vector from the initial point or origin (called the “tail” of a vector) to the end or terminal point (called the “head” of a vector), marked by an arrowhead. Magnitude is the length of a vector and is always a positive scalar quantity. (credit: modification of work by Cate Sevilla)

FIGURE 2.3



The displacement vector from point A (the initial position at the campsite) to point B (the final position at the fishing hole) is indicated by an arrow with origin at point A and end at point B . The displacement is the same for any of the actual paths (dashed curves) that may be taken between points A and B .

FIGURE 2.4



A displacement \vec{D} of magnitude 6 km is drawn to scale as a vector of length 12 cm when the length of 2 cm represents 1 unit of displacement (which in this case is 1 km).

FIGURE 2.5

Various relations between two vectors \vec{A} and \vec{B} .

- (a) $\vec{A} \neq \vec{B}$ because $A \neq B$.
- (b) $\vec{A} \neq \vec{B}$ because they are not parallel and $A \neq B$.
- (c) $|\vec{A}| \neq |-\vec{A}|$ because they have different directions (even though $|\vec{A}| = |-\vec{A}| = A$).
- (d) $\vec{A} = \vec{B}$ because they are parallel and have identical magnitudes $A = B$.
- (e) $\vec{A} \neq \vec{B}$ because they have different directions (are not parallel); here, their directions differ by 90° —meaning, they are orthogonal.

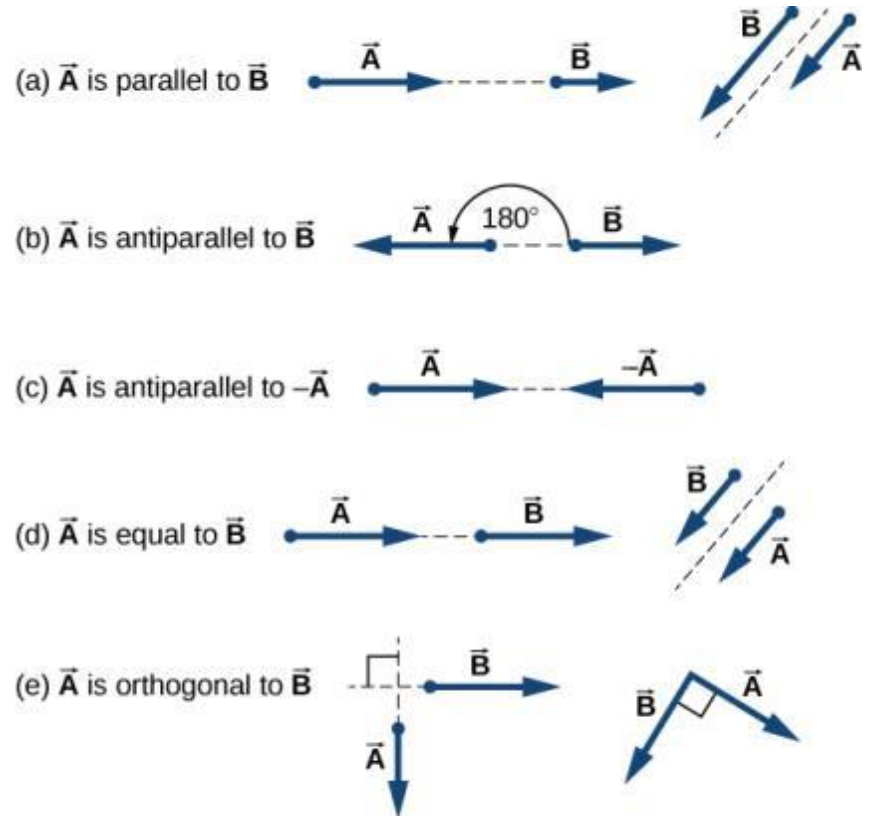
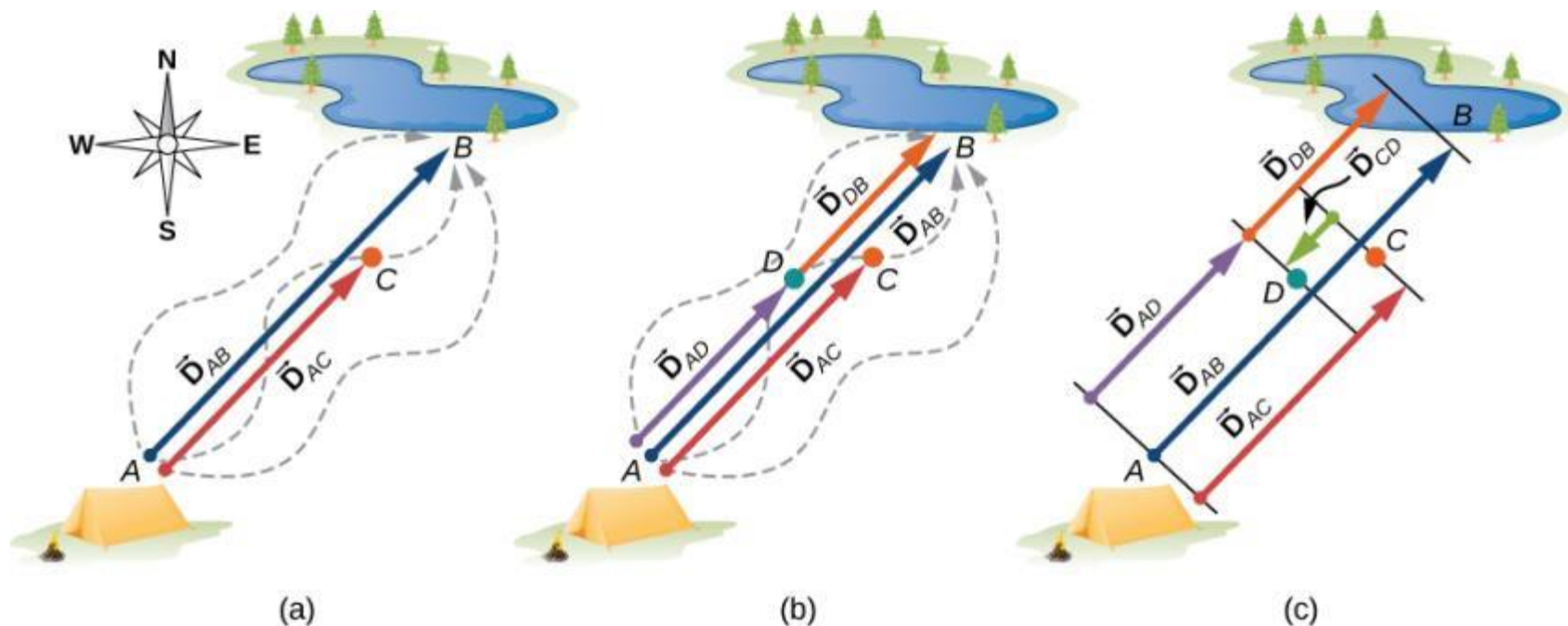


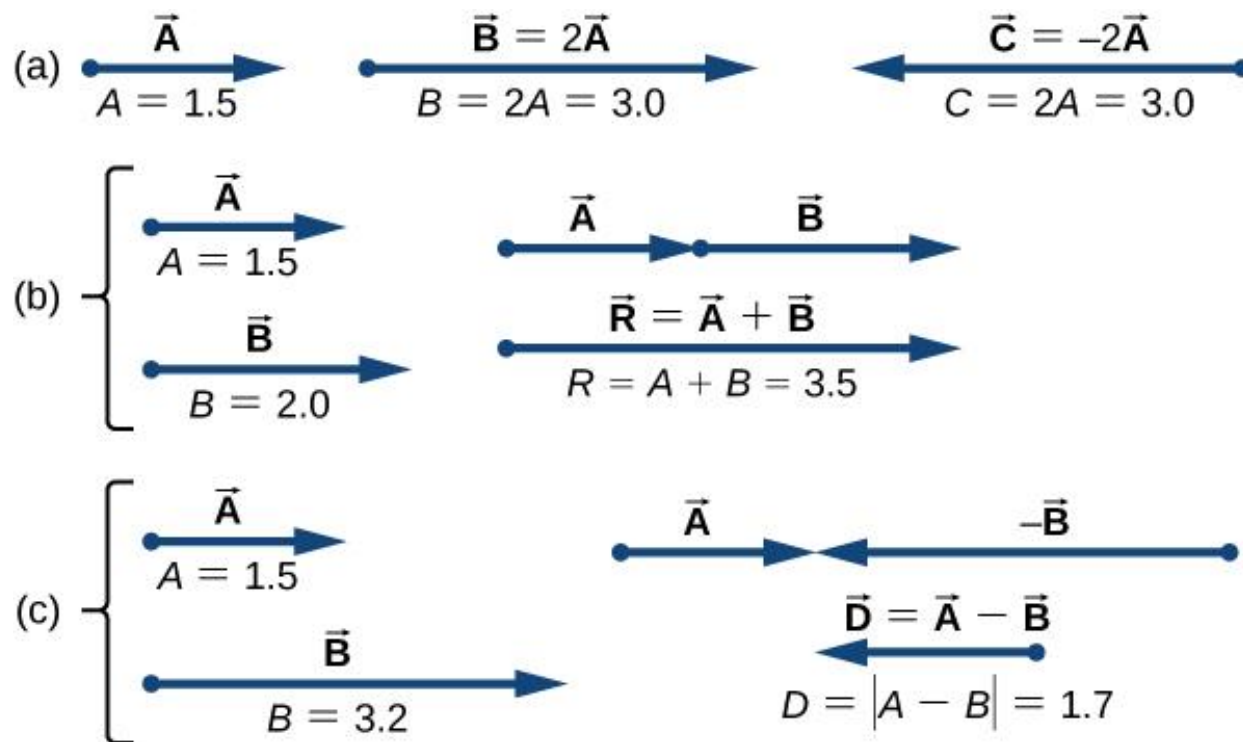
FIGURE 2.6



Displacement vectors for a fishing trip.

- (a) Stopping to rest at point C while walking from camp (point A) to the pond (point B).
- (b) Going back for the dropped tackle box (point D).
- (c) Finishing up at the fishing pond.

FIGURE 2.7



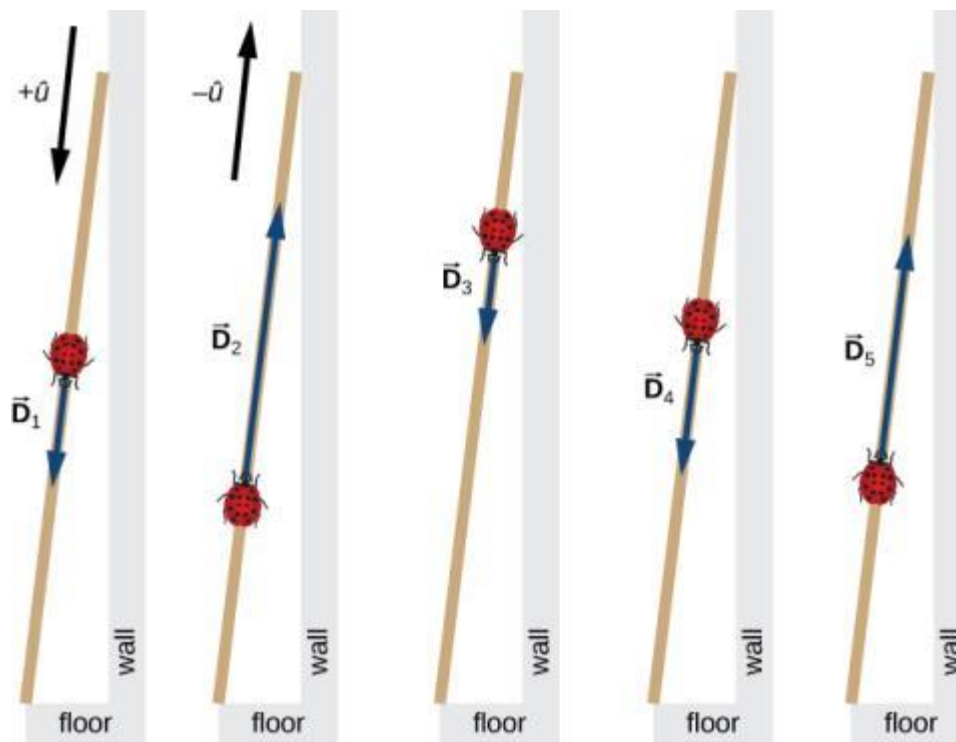
Algebra of vectors in one dimension.

(a) Multiplication by a scalar.

(b) Addition of two vectors (\vec{R} is called the *resultant* of vectors \vec{A} and \vec{B}).

(c) Subtraction of two vectors (\vec{D} is the difference of vectors \vec{A} and \vec{B}).

FIGURE 2.8



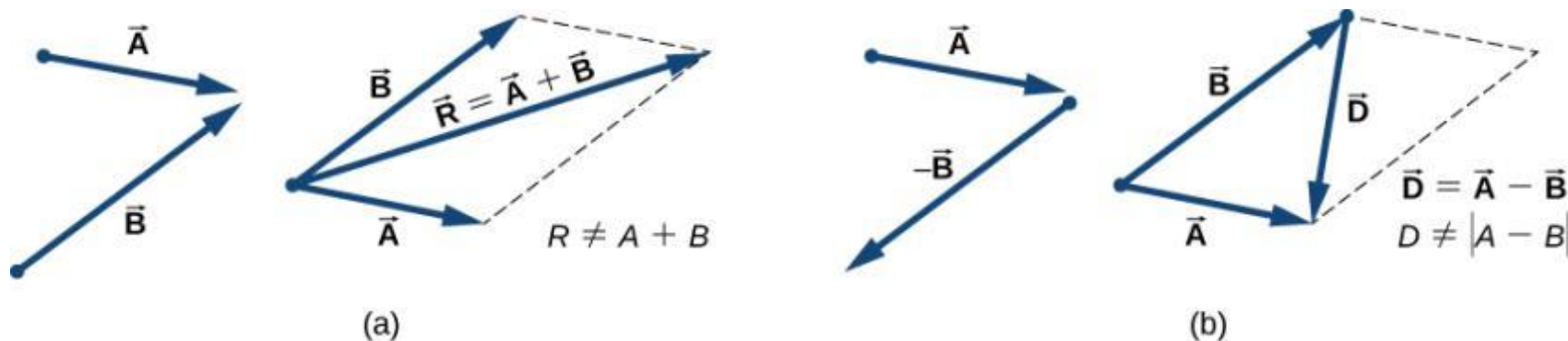
Five displacements of the ladybug. Note that in this schematic drawing, magnitudes of displacements are not drawn to scale. (credit: modification of work by “Persian Poet Gal”/Wikimedia Commons)

FIGURE 2.9



In navigation, the laws of geometry are used to draw resultant displacements on nautical maps.

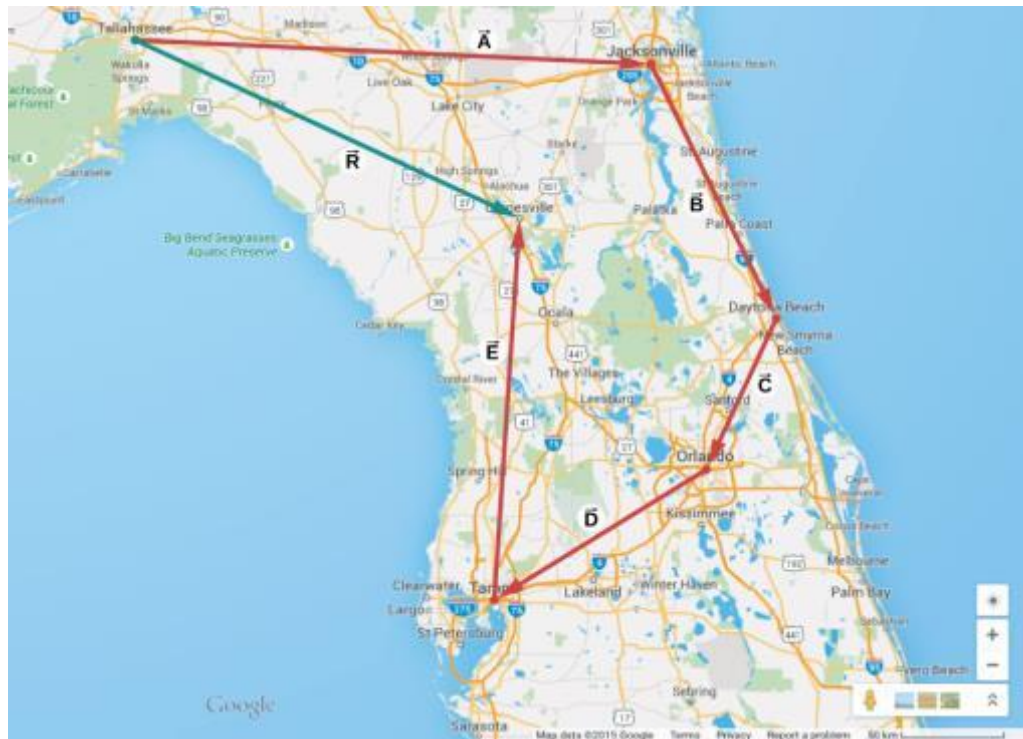
FIGURE 2.10



The parallelogram rule for the addition of two vectors. Make the parallel translation of each vector to a point where their origins (marked by the dot) coincide and construct a parallelogram with two sides on the vectors and the other two sides (indicated by dashed lines) parallel to the vectors.

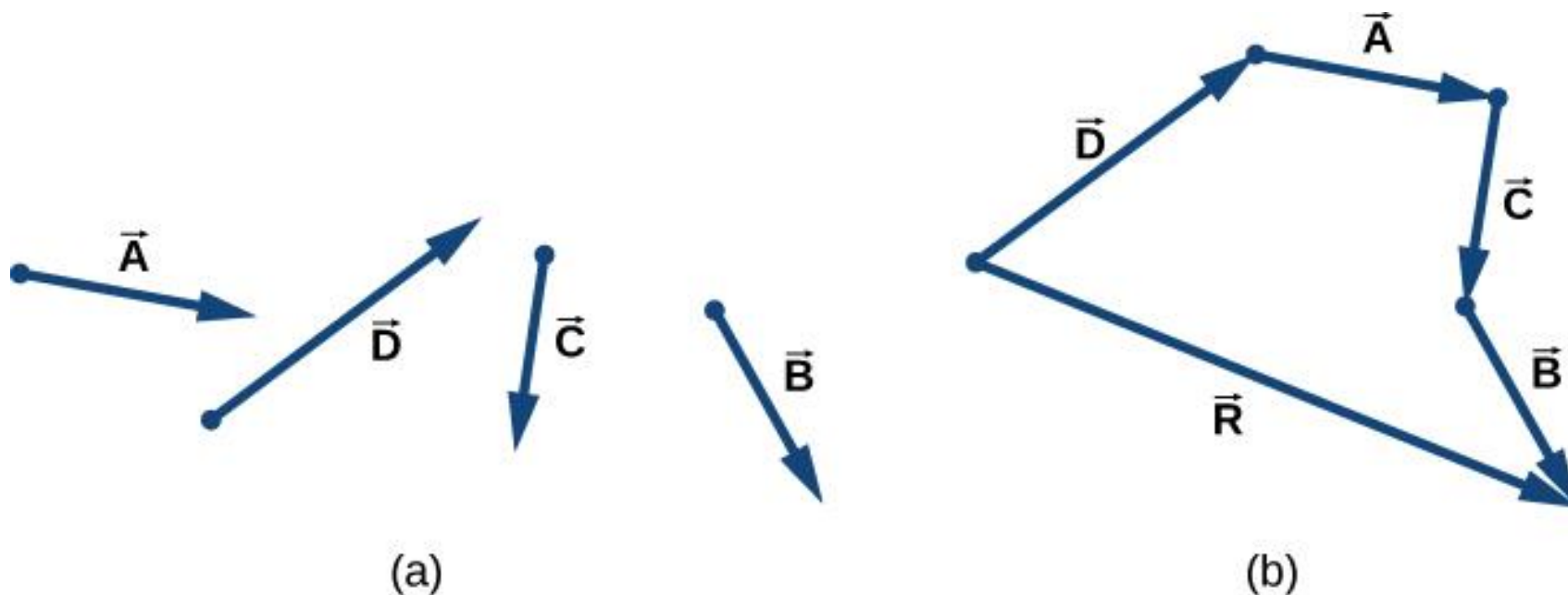
- (a) Draw the resultant vector \vec{R} along the diagonal of the parallelogram from the common point to the opposite corner. Length \vec{R} of the resultant vector is not equal to the sum of the magnitudes of the two vectors.
- (b) Draw the difference vector $\vec{D} = \vec{A} - \vec{B}$ along the diagonal connecting the ends of the vectors. Place the origin of vector \vec{D} at the end of vector \vec{B} and the end (arrowhead) of vector \vec{D} at the end of vector \vec{A} . Length D of the difference vector is not equal to the difference of magnitudes of the two vectors.

FIGURE 2.11



When we use the parallelogram rule four times, we obtain the resultant vector $\vec{R} = \vec{A} + \vec{B} + \vec{C} + \vec{D} + \vec{E}$, which is the green vector connecting Tallahassee with Gainesville.

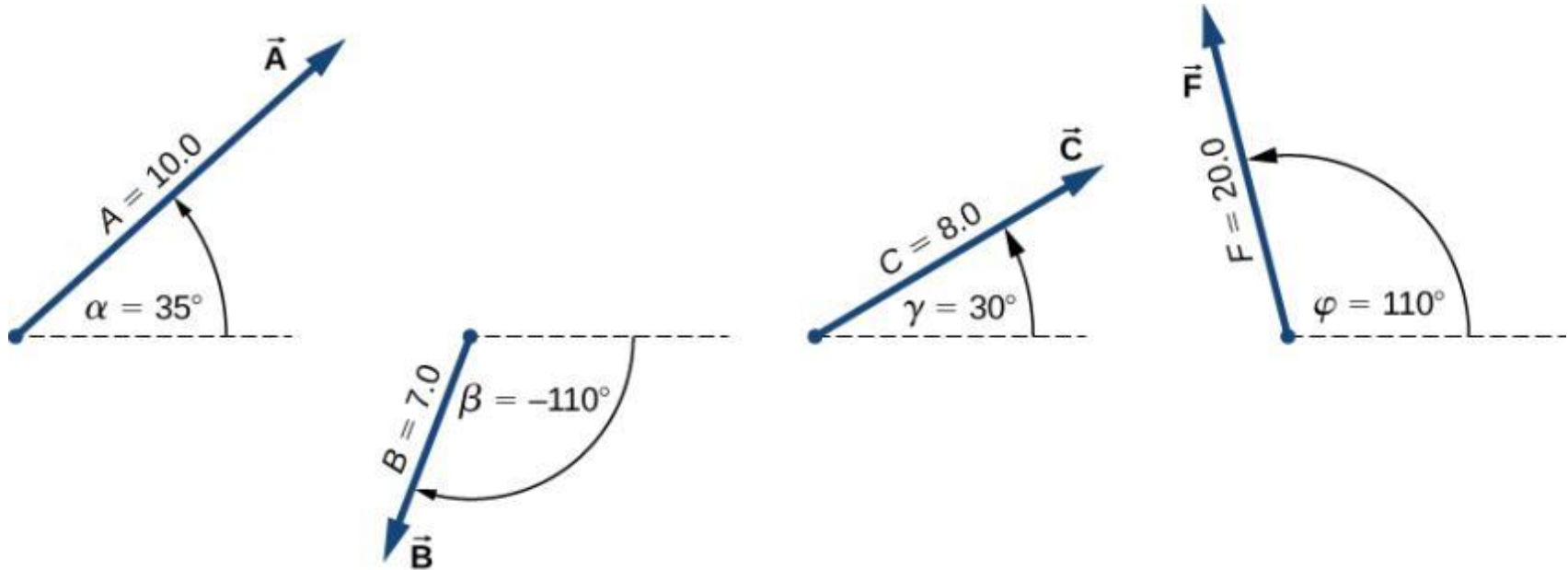
FIGURE 2.12



Tail-to-head method for drawing the resultant vector $\vec{R} = \vec{A} + \vec{B} + \vec{C} + \vec{D}$.

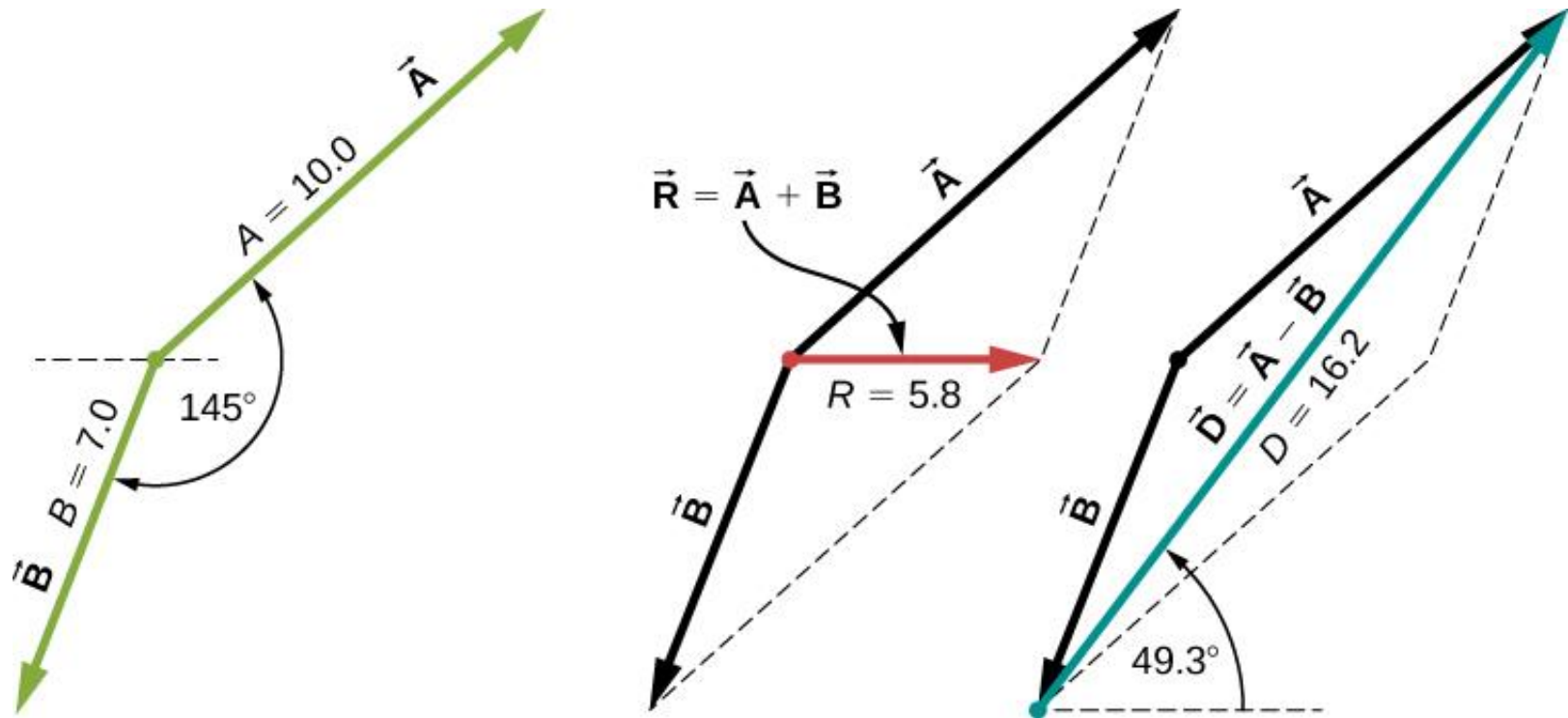
- (a) Four vectors of different magnitudes and directions.
- (b) Vectors in (a) are translated to new positions where the origin (“tail”) of one vector is at the end (“head”) of another vector. The resultant vector is drawn from the origin (“tail”) of the first vector to the end (“head”) of the last vector in this arrangement.

FIGURE 2.13



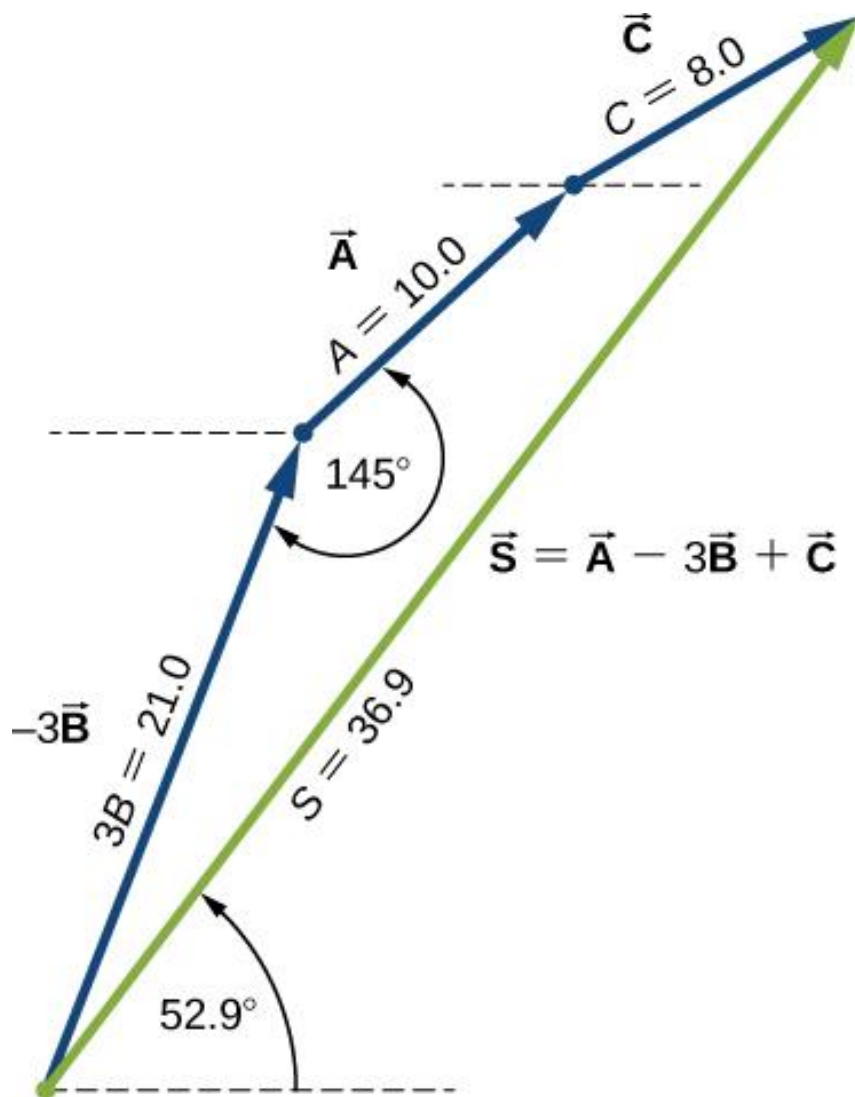
Vectors used in [Example 2.2](#) and in the Check Your Understanding feature that follows.

FIGURE 2.14



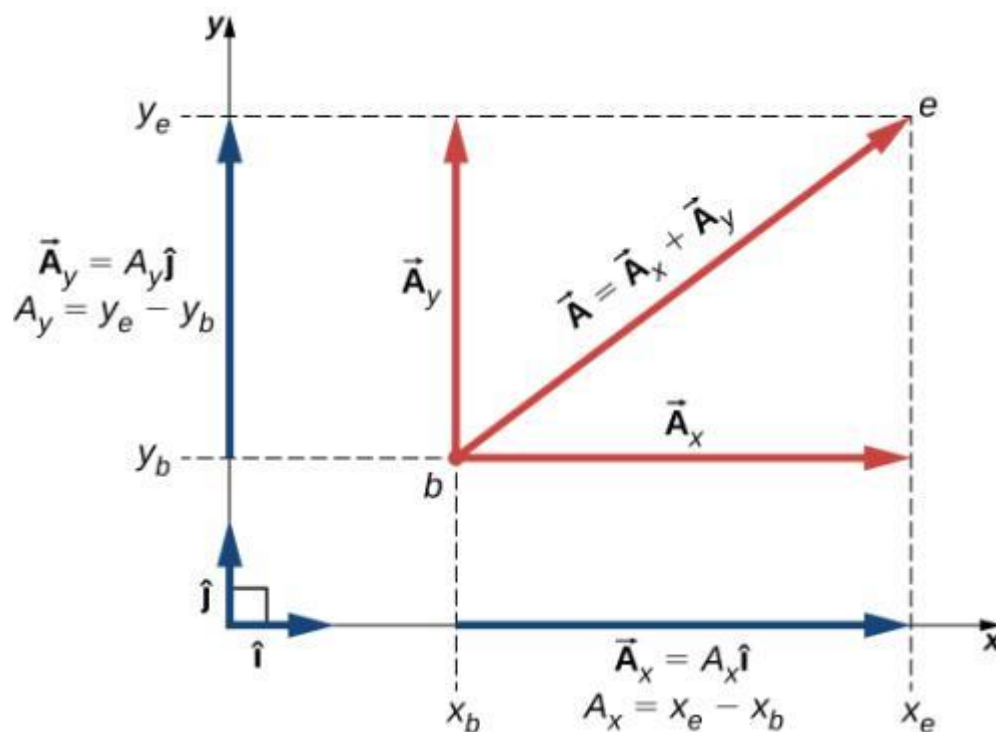
Using the parallelogram rule to solve (a) (finding the resultant, red) and (b) (finding the difference, blue).

FIGURE 2.15



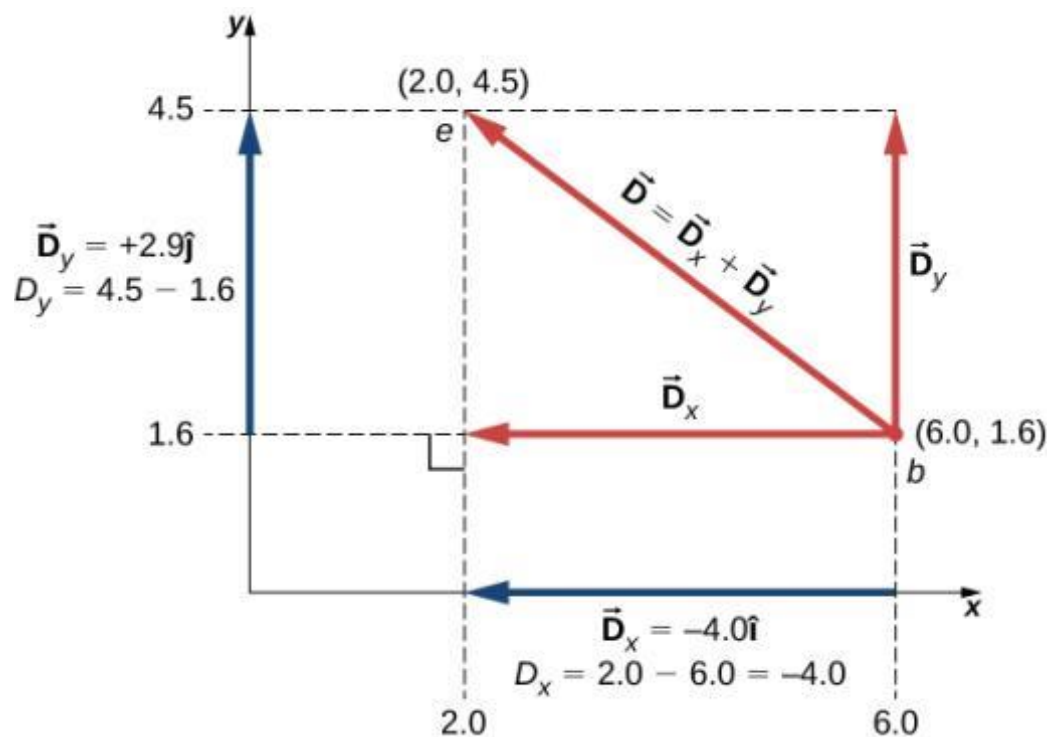
Using the tail-to-head method to solve (c)
(finding vector \vec{S} , green).

FIGURE 2.16



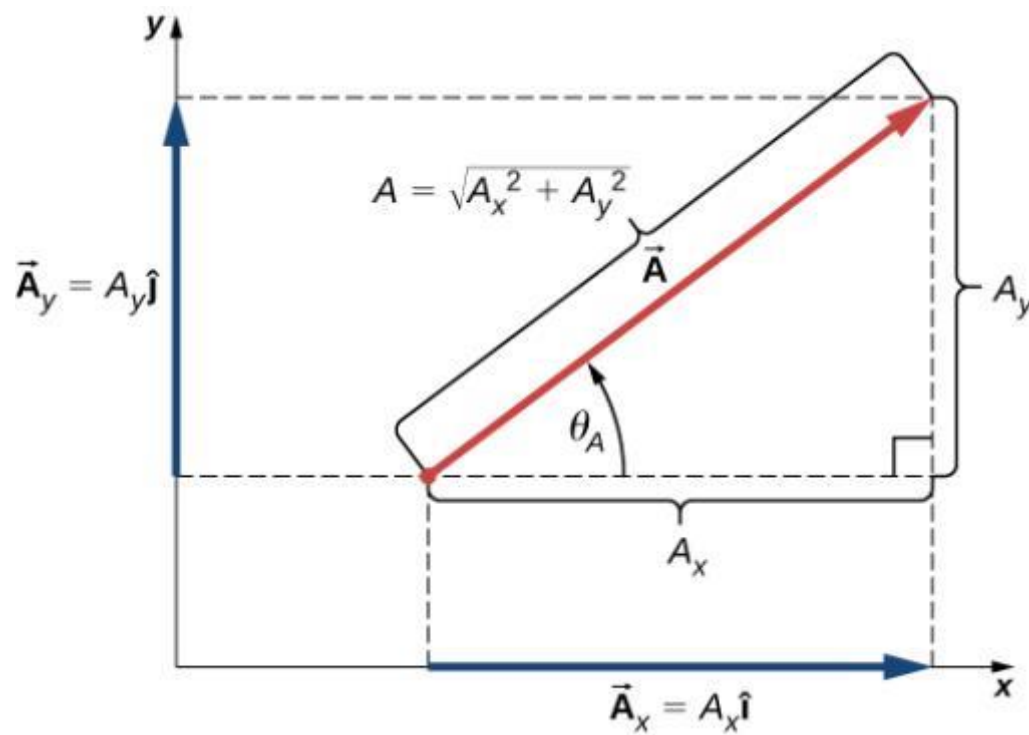
Vector \vec{A} in a plane in the Cartesian coordinate system is the vector sum of its vector x- and y-components. The x-vector component \vec{A}_x is the orthogonal projection of vector \vec{A} onto the x-axis. The y-vector component \vec{A}_y is the orthogonal projection of vector \vec{A} onto the y-axis. The numbers A_x and A_y that multiply the unit vectors are the scalar components of the vector.

FIGURE 2.17



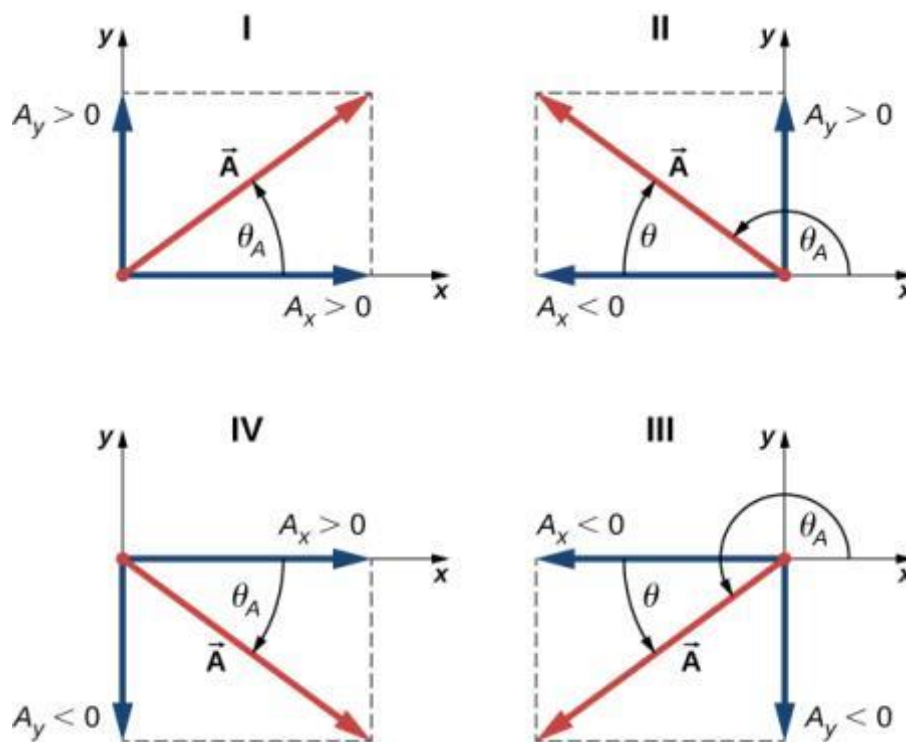
The graph of the displacement vector. The vector points from the origin point at b to the end point at e .

FIGURE 2.18



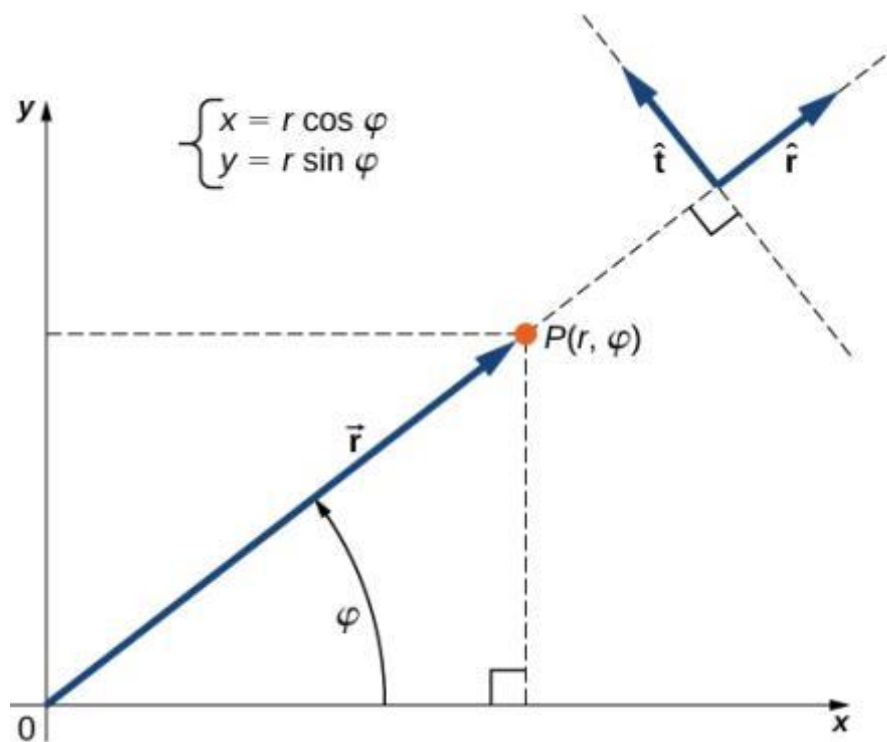
For vector \vec{A} , its magnitude A and its direction angle θ_A are related to the magnitudes of its scalar components because A , A_x , and A_y form a right triangle.

FIGURE 2.19



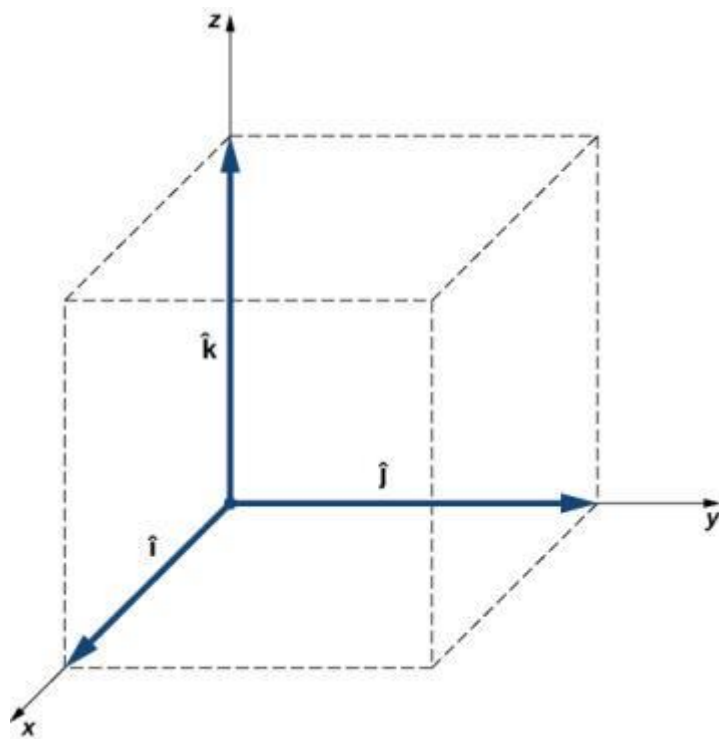
Scalar components of a vector may be positive or negative. Vectors in the first quadrant (I) have both scalar components positive and vectors in the third quadrant have both scalar components negative. For vectors in quadrants II and III, the direction angle of a vector is $\theta_A = \theta + 180^\circ$.

FIGURE 2.20



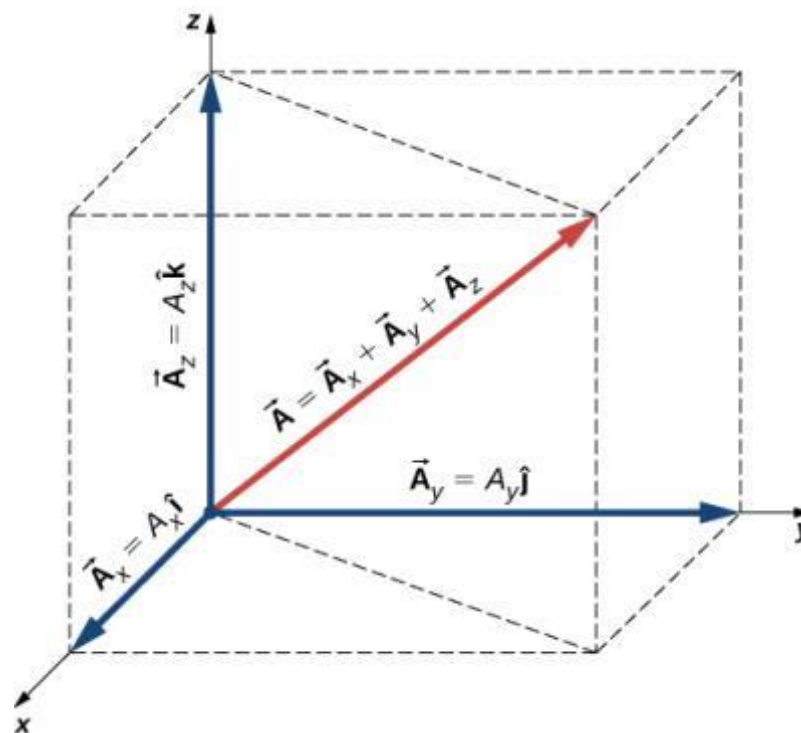
Using polar coordinates, the unit vector \hat{r} defines the positive direction along the radius r (radial direction) and, orthogonal to it, the unit vector \hat{t} defines the positive direction of rotation by the angle φ .

FIGURE 2.21



Three unit vectors define a Cartesian system in three-dimensional space. The order in which these unit vectors appear defines the orientation of the coordinate system. The order shown here defines the right-handed orientation.

FIGURE 2.22



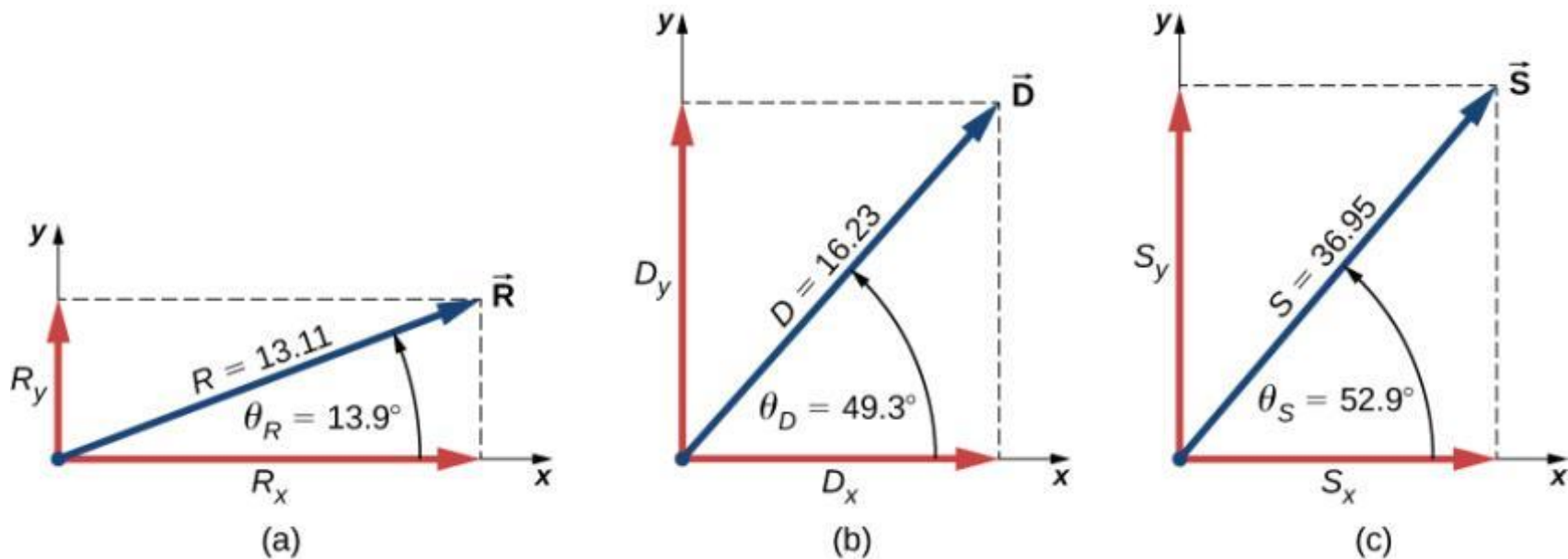
A vector in three-dimensional space is the vector sum of its three vector components.

FIGURE 2.23



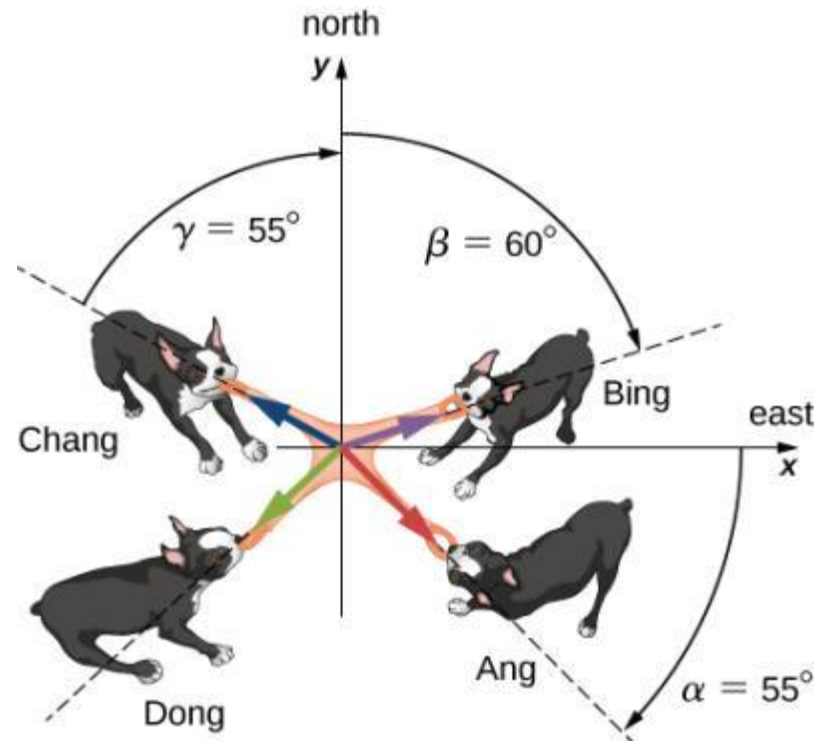
The drone IAI Heron in flight. (credit: SSgt Reynaldo Ramon, USAF)

FIGURE 2.24



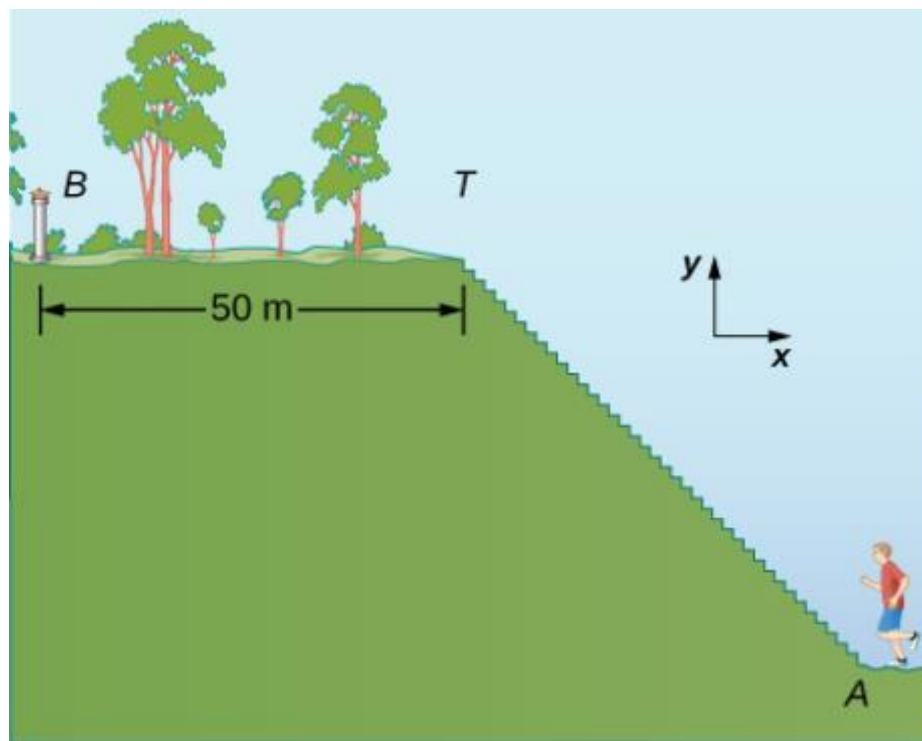
Graphical illustration of the solutions obtained analytically in [Example 2.9](#).

FIGURE 2.25



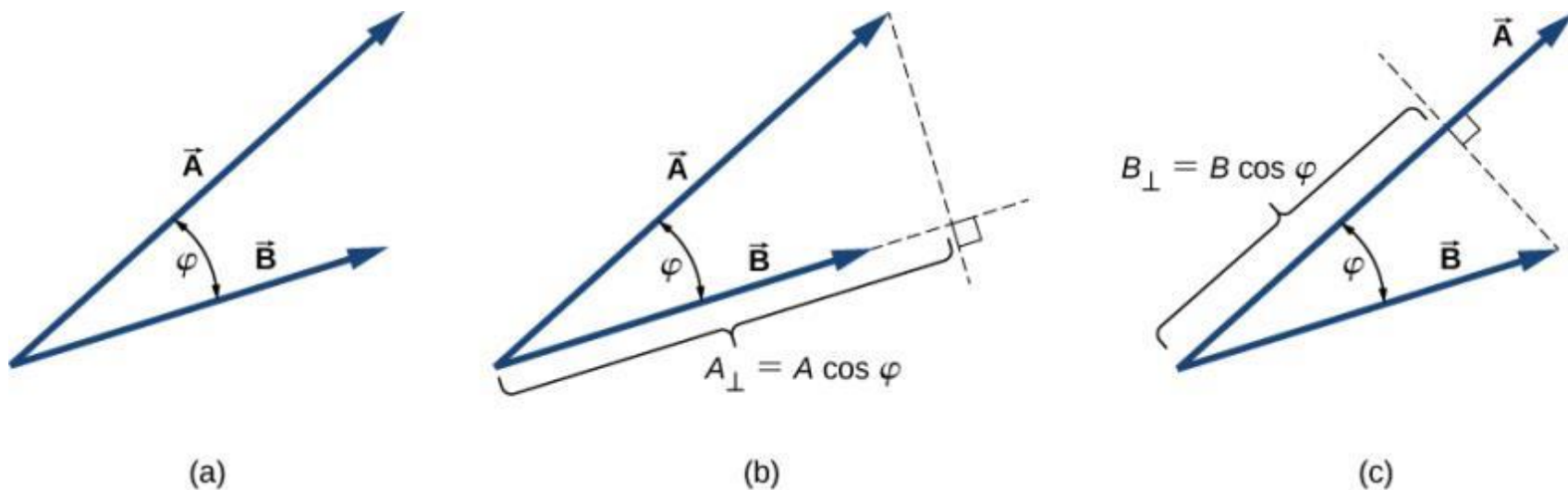
Four dogs play a tug-of-war game with a toy.

FIGURE 2.26



A jogger runs up a flight of steps.

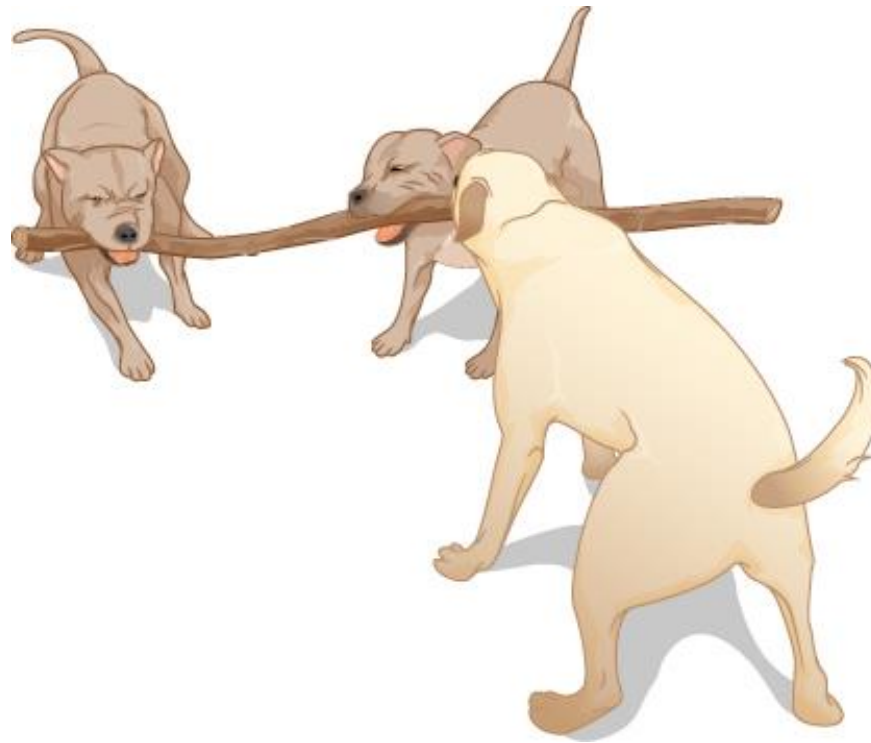
FIGURE 2.27



The scalar product of two vectors.

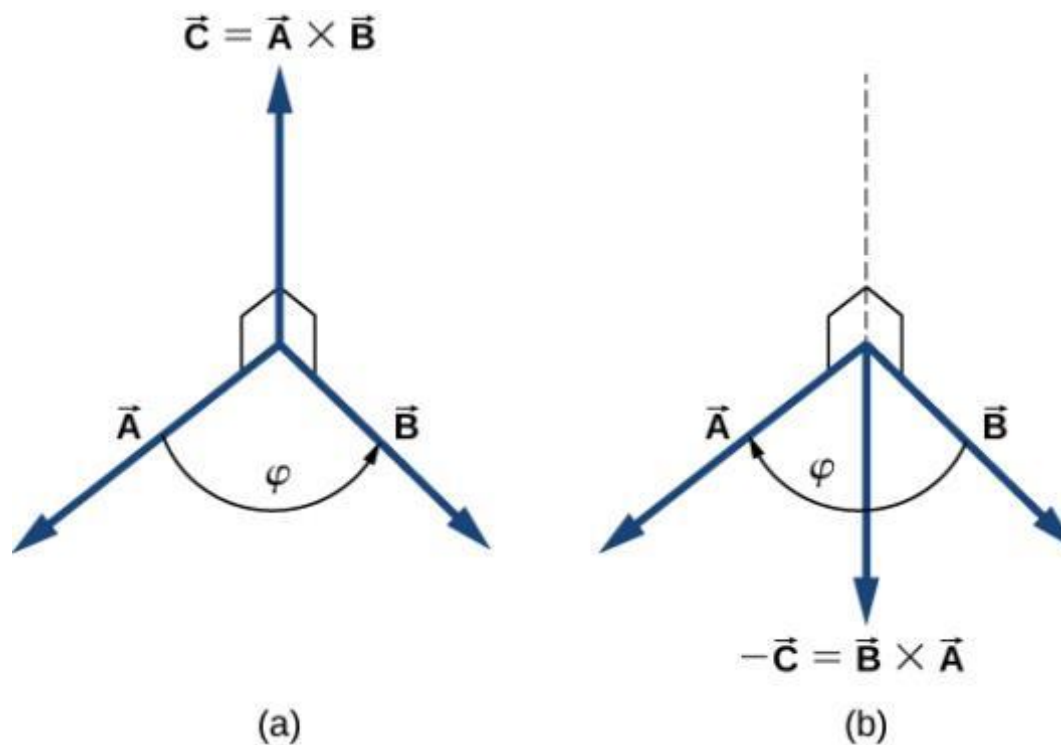
- (a) The angle between the two vectors.
- (b) The orthogonal projection A_{\perp} of vector \vec{A} onto the direction of vector \vec{B} .
- (c) The orthogonal projection B_{\perp} of vector \vec{B} onto the direction of vector \vec{A} .

FIGURE 2.28



Three dogs are playing with a stick.

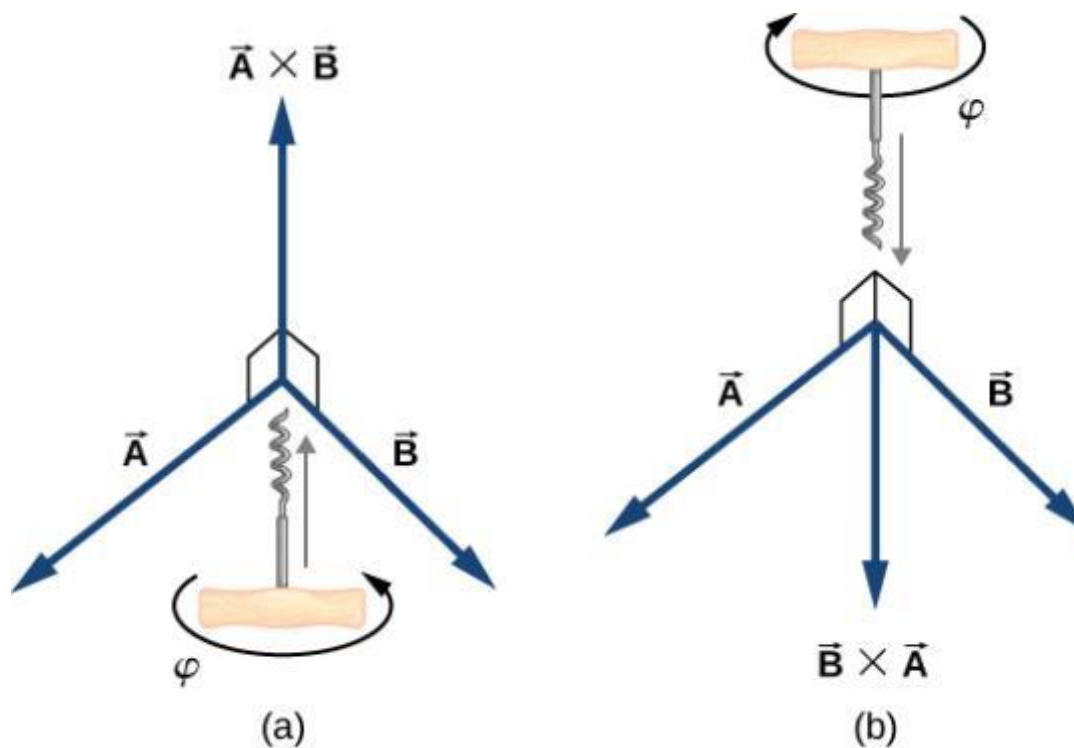
FIGURE 2.29



The vector product of two vectors is drawn in three-dimensional space.

- (a) The vector product $\vec{A} \times \vec{B}$ is a vector perpendicular to the plane that contains vectors \vec{A} and \vec{B} . Small squares drawn in perspective mark right angles between \vec{A} and \vec{C} , and between \vec{B} and \vec{C} so that if \vec{A} and \vec{B} lie on the floor, vector \vec{C} points vertically upward to the ceiling.
- (b) The vector product $\vec{B} \times \vec{A}$ is a vector antiparallel to vector $\vec{A} \times \vec{B}$.

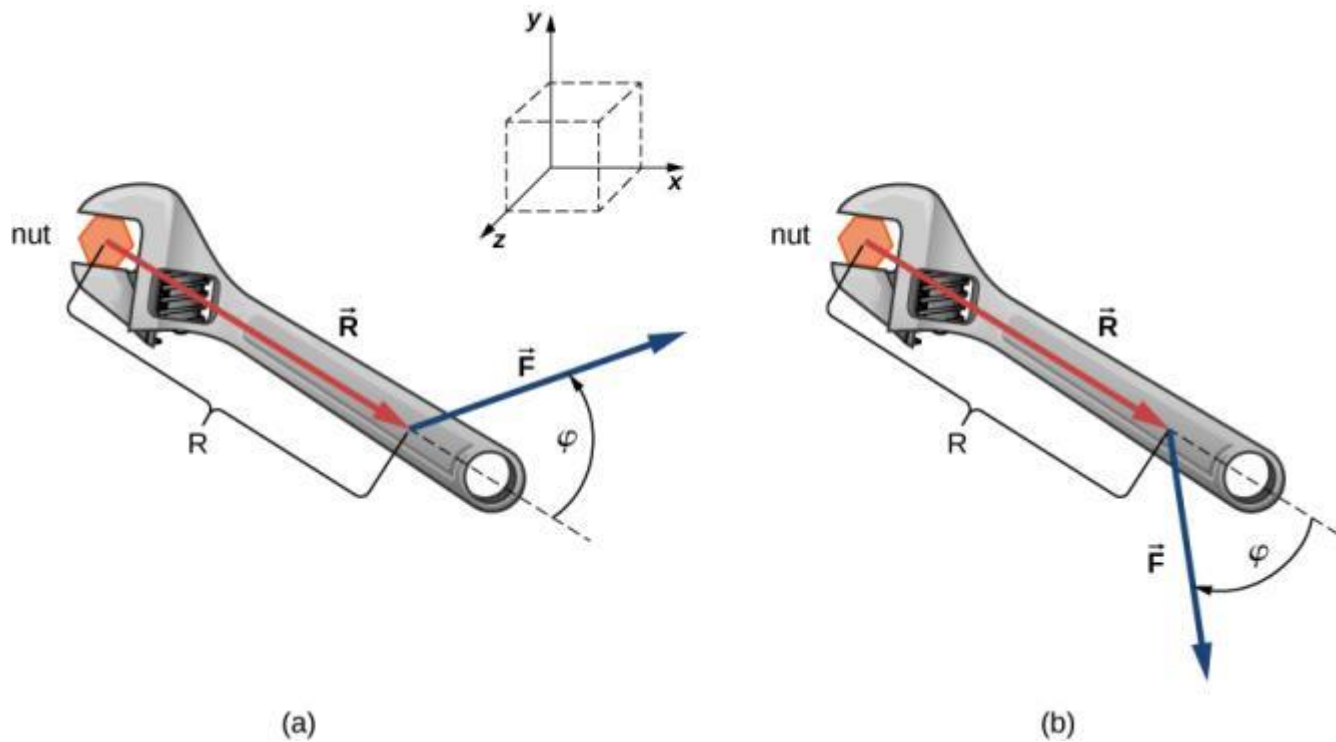
FIGURE 2.30



The corkscrew right-hand rule can be used to determine the direction of the cross product $\vec{A} \times \vec{B}$. Place a corkscrew in the direction perpendicular to the plane that contains vectors \vec{A} and \vec{B} , and turn it in the direction from the first to the second vector in the product. The direction of the cross product is given by the progression of the corkscrew.

- (a) Upward movement means the cross-product vector points up.
- (b) Downward movement means the cross-product vector points downward.

FIGURE 2.31

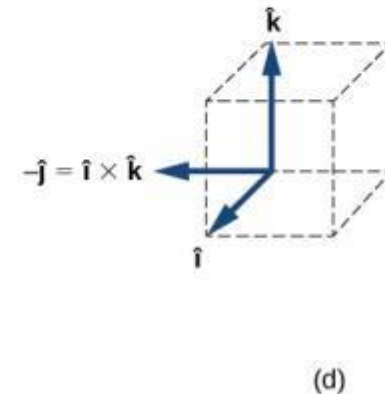
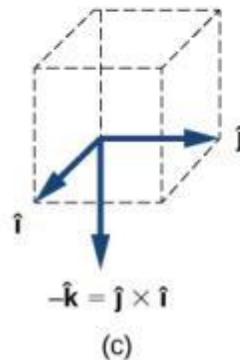
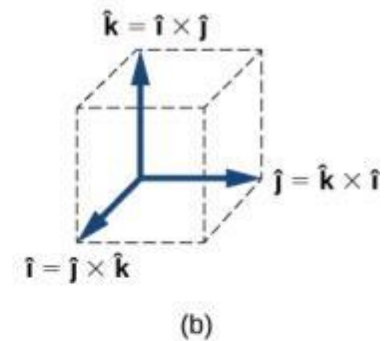
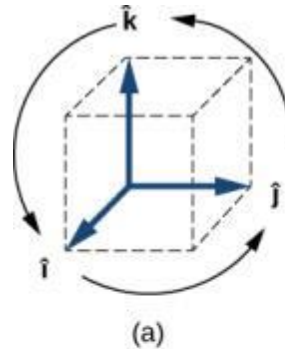


A wrench provides grip and mechanical advantage in applying torque to turn a nut.

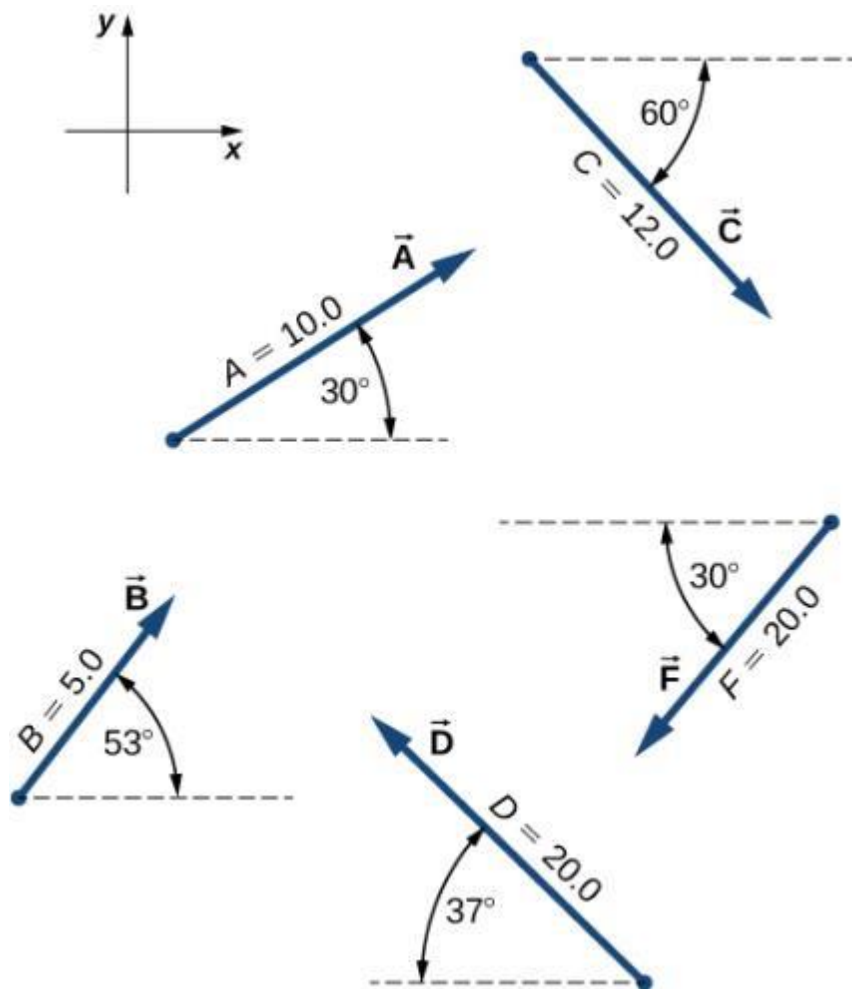
- (a) Turn counterclockwise to loosen the nut.
- (b) Turn clockwise to tighten the nut.

FIGURE 2.32

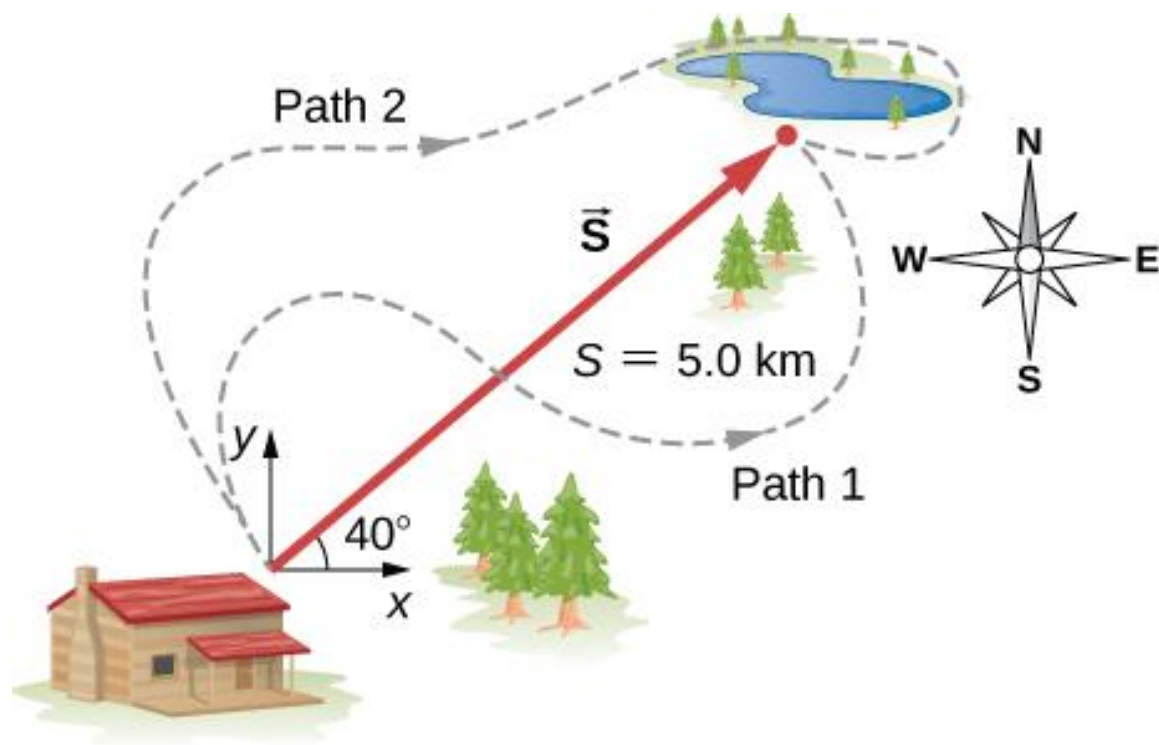
- (a) The diagram of the cyclic order of the unit vectors of the axes.
- (b) The only cross products where the unit vectors appear in the cyclic order. These products have the positive sign.
- (c) (d) Two examples of cross products where the unit vectors do not appear in the cyclic order. These products have the negative sign.



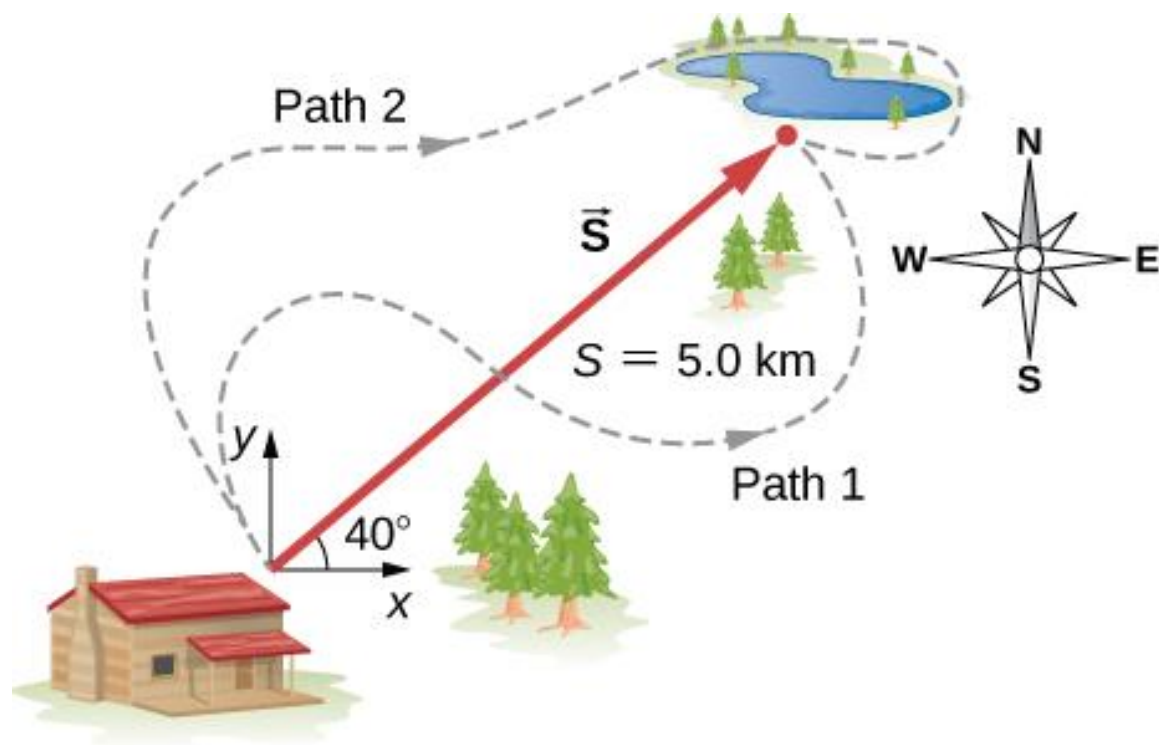
EXERCISE 28



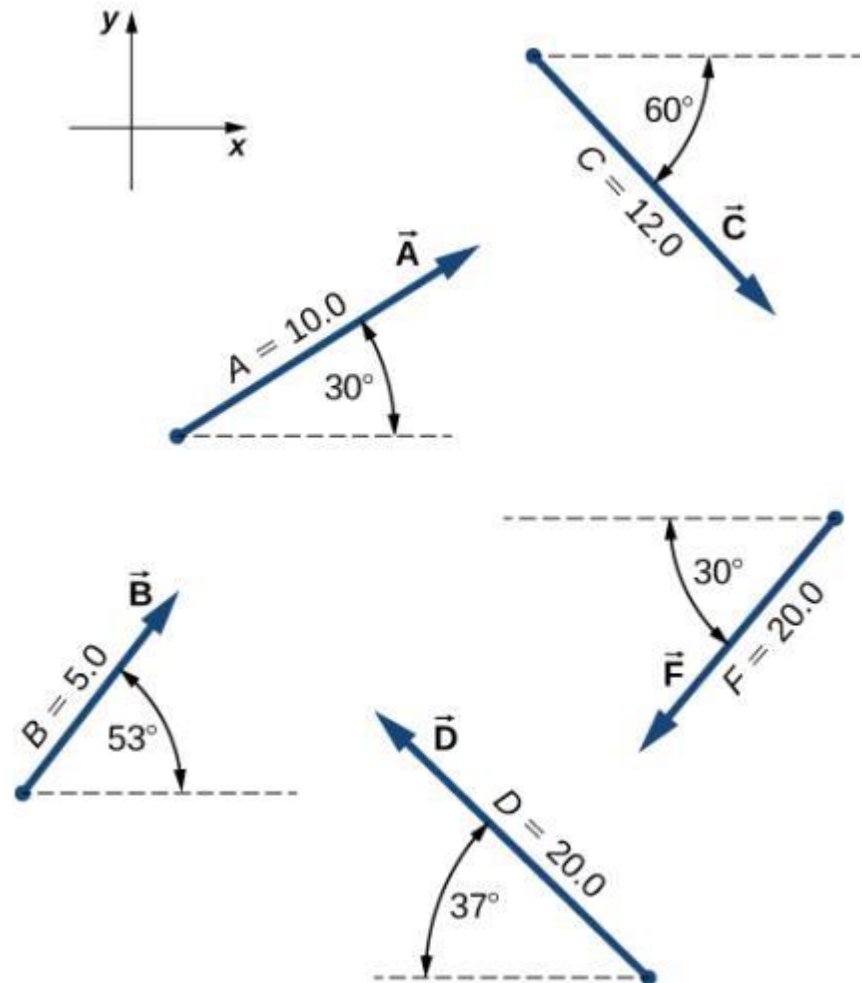
EXERCISE 33



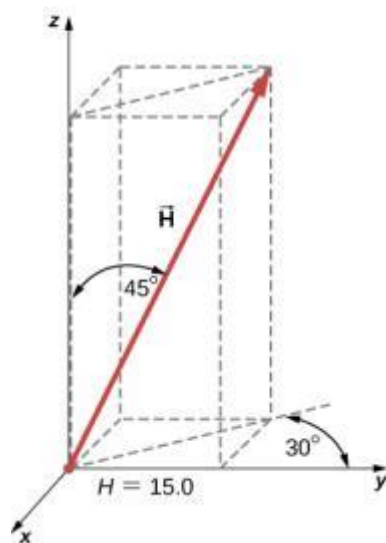
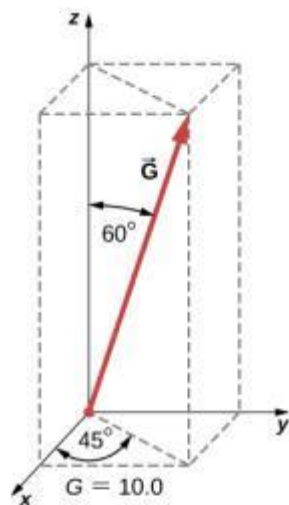
EXERCISE 41



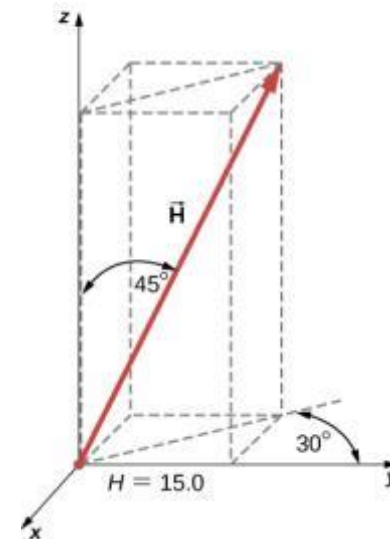
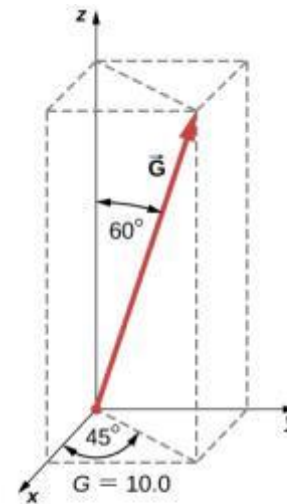
EXERCISE 62



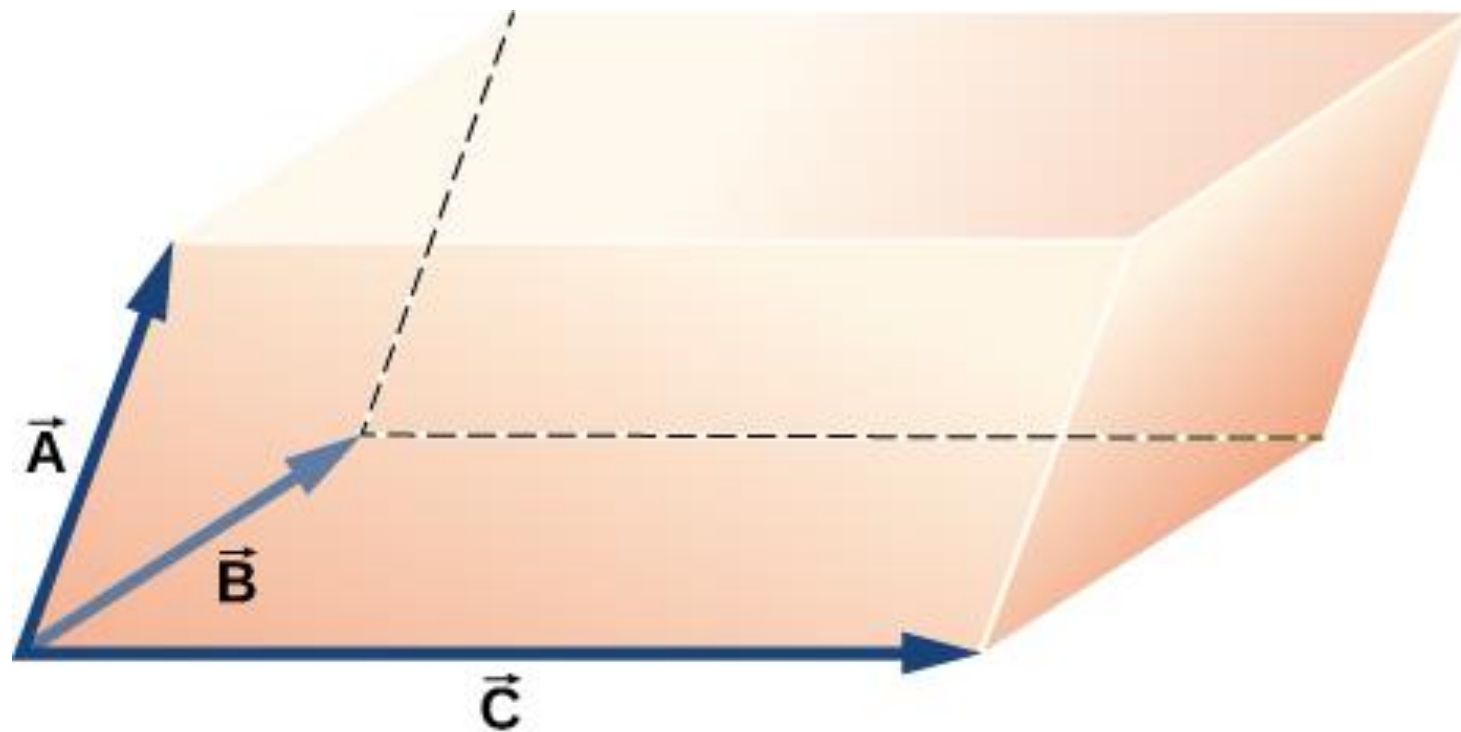
EXERCISE 82



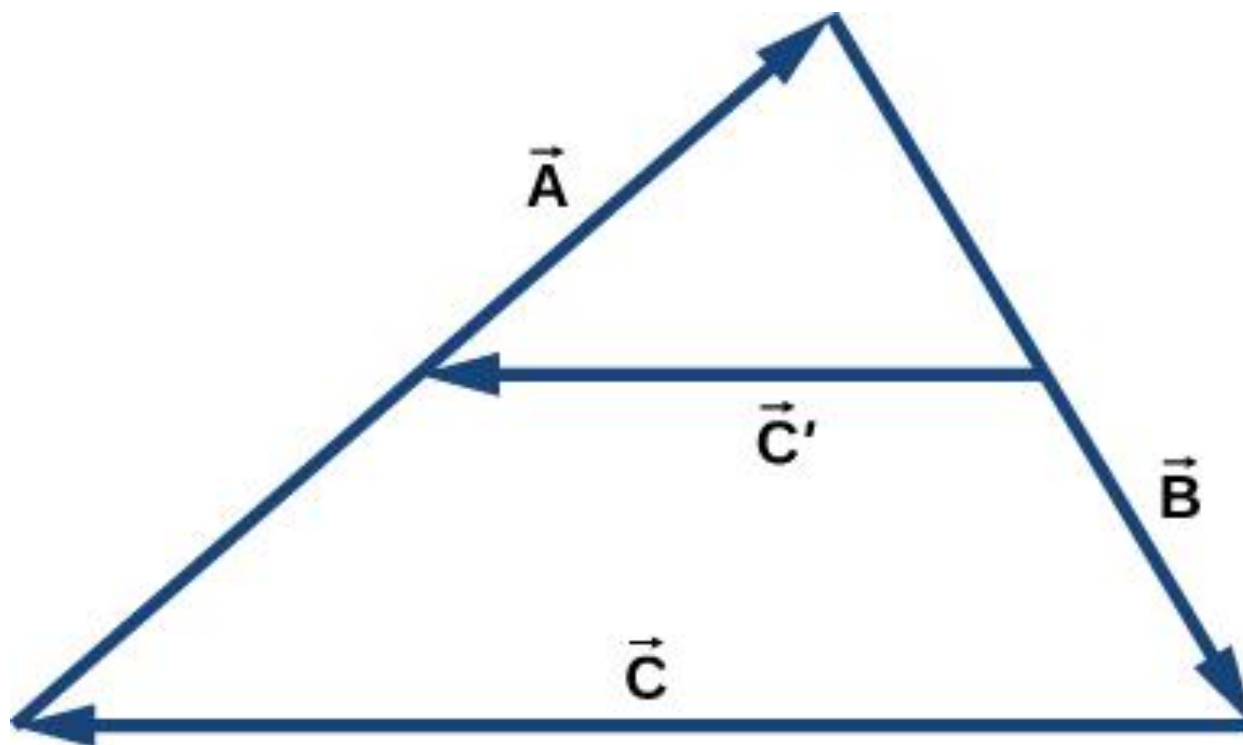
EXERCISE 86



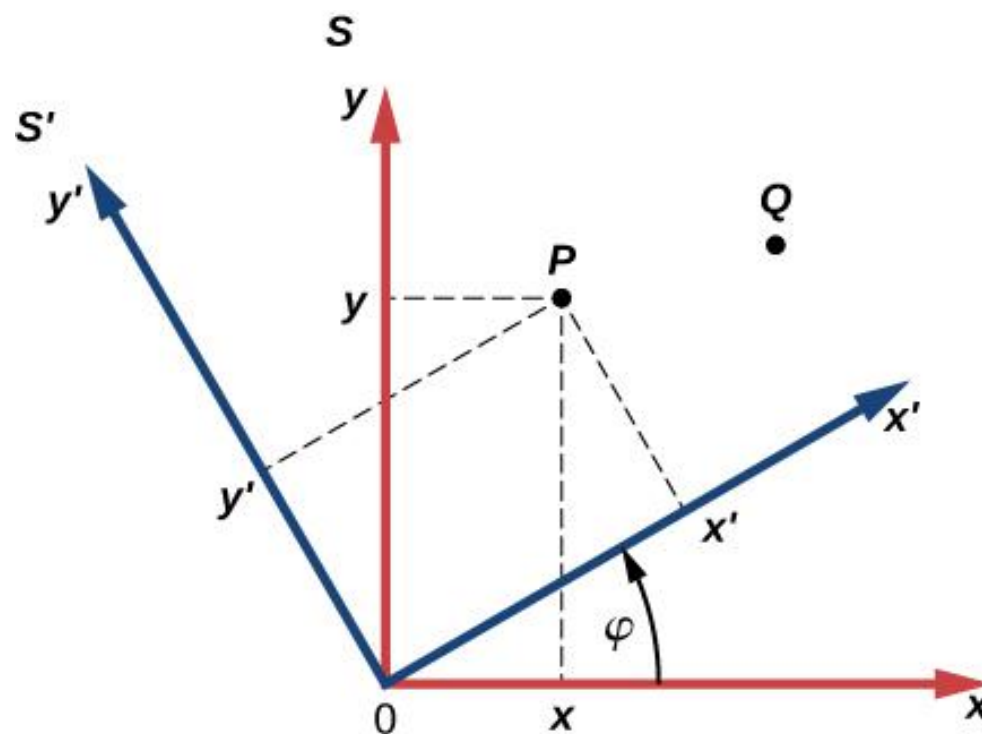
EXERCISE 87



EXERCISE 90



EXERCISE 91



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