

ENGINEERING MECHANICS BAA1113

Chapter 3: Equilibrium of a Particle (Static)

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Chapter Description

Aims

- To explain the Equilibrium Equation
- To explain the Free Body Diagram
- To apply the Equations of Equilibrium to solve particle equilibrium problems in Coplanar Force System (2-D & 3-D)
- Expected Outcomes
 - Able to solve the problems of a particle or rigid body in the mechanics applications by using Equilibrium Equation
- References
 - Russel C. Hibbeler. Engineering Mechanics: Statics & Dynamics, 14th Edition

Chapter Outline

- 3.1 Equilibrium Equation
- 3.2 Free Body Diagram
- 3.3 Coplanar Force Systems (2-D & 3-D)

3.4 Example



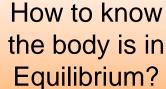
3.1 Equilibrium Equation

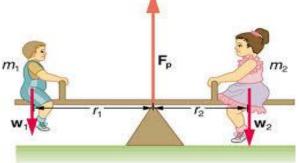
What is Equilibrium?



- Equilibrium means the forces are balanced but not necessarily equal
 - In physic, it means equal balance which the opposing forces or tendencies neutralize each other



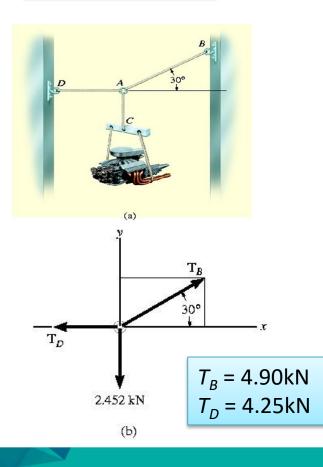




 A body at rest or in uniform motion (velocity) is in equilibrium

Condition for the Equilibrium of a Particle

How to know the body is in Equilibrium?



- Particle at equilibrium if
 - At rest
 - Moving at constant a constant velocity
- Newton's first law of motion

 $\sum \mathbf{F} = 0$

where $\sum \mathbf{F}$ is the vector sum of all the forces acting on the particle

+→
$$\sum \mathbf{F}_{x} = 0$$
; $T_{B} \cos 30^{\circ} - T_{D} = 0$
+↑ $\sum \mathbf{F}_{y} = 0$; $T_{B} \sin 30^{\circ} - 2.452 \text{kN} = 0$

Condition for the Equilibrium of a Particle

Newton's second law of motion

∑**F** = m**a**

 When the force fulfill Newton's first law of motion,

a = 0

therefore, the particle is moving in constant velocity or at rest

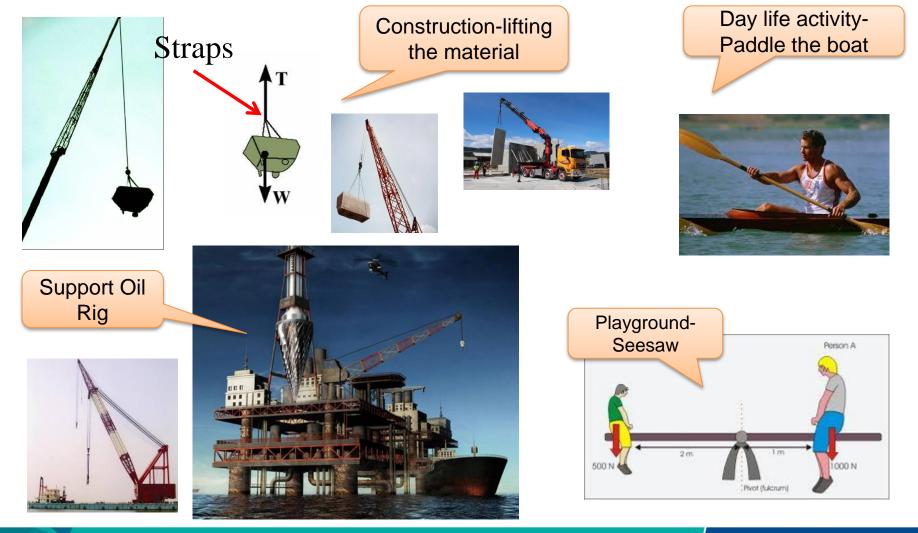


Static Equilibrium is when the body at rest

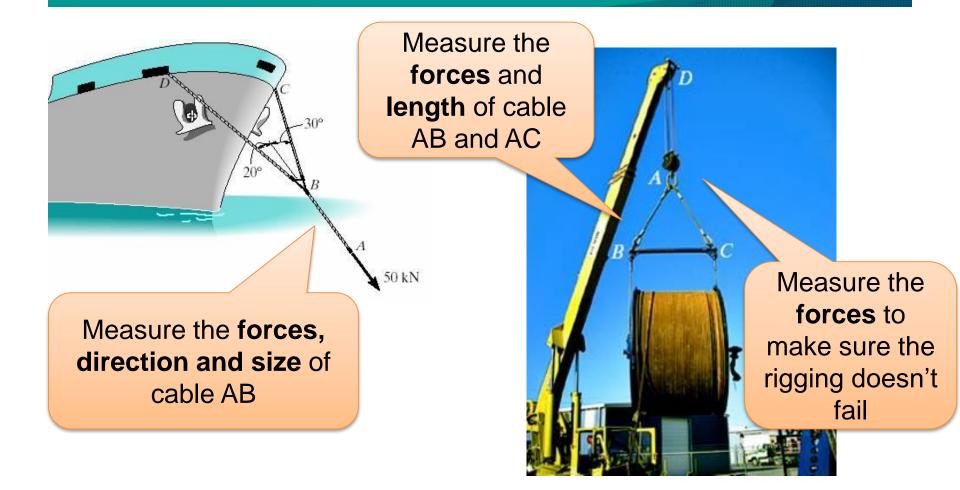


If the Dynamic Equilibrium, the body move and continue to move

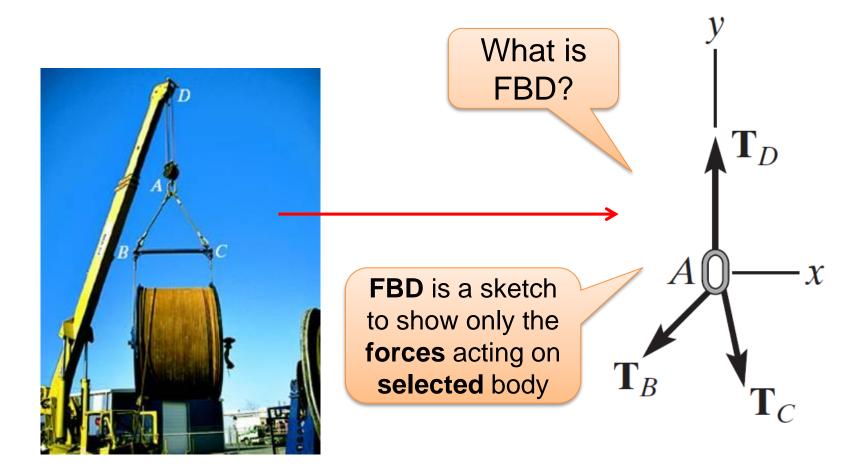
Application of Equilibrium Equation



Application of Equilibrium Equation



3.2 Free Body Diagram (FBD)

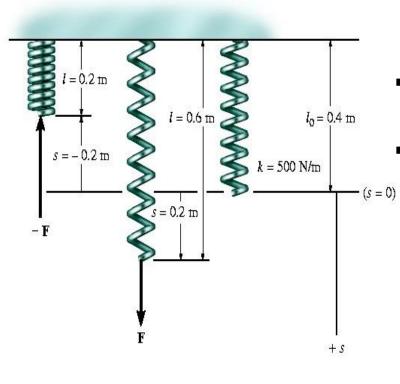


3.2 Free Body Diagram (FBD)

- Best representation of all the unknown forces (∑F) which acts on a body
- A sketch showing the particle "free" from the surroundings with all the forces acting on it
- Consider two common connections in this subject – Spring

- Cables and Pulleys

Spring



- Linear elastic spring: change in length is directly proportional to the force acting on it
- spring constant or stiffness k: defines the elasticity of the spring
- Magnitude of force when spring is elongated or compressed



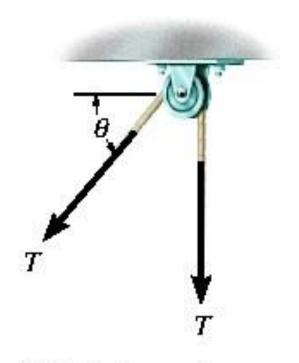
 where s is determined from the difference in spring's deformed length I and its undeformed length I_o

$$s = |-|_o$$
 $s = |-|_c$

- If s is positive, F "pull" onto the spring
- If **s** is negative, **F** "push" onto the spring

Cables and Pulley

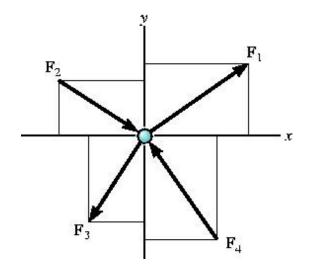
- Cables (or cords) are assumed to have negligible weight and they cannot stretch
- A cable only support tension or pulling force
- Tension always acts in the direction of the cable
- Tension force in a continuous cable must have a constant magnitude for equilibrium
- For any angle θ, the cable is subjected to a constant tension *T* throughout its length



Cable is in tension

With a frictionless pulley and cable $T_1 = T_2$.

3.3 Coplanar Systems 2-D



- A particle is subjected to coplanar forces in the x-y plane
- Resolve into i and j components for equilibrium

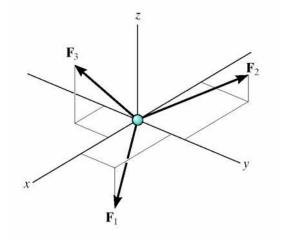
$$\sum \mathbf{F}_{x} = 0$$
$$\sum \mathbf{F}_{y} = 0$$

 Scalar equations of equilibrium require that the algebraic sum of the x and y components to equal o (zero)

Scalar Notation

- Sense of direction = an algebraic sign that corresponds to the arrowhead direction of the component along each axis
- For unknown magnitude, assume arrowhead sense of the force
- Since magnitude of the force is always positive, if the scalar is negative, the force is acting in the opposite direction

3.3 Coplanar Systems 3-D



- When a particle is in equilibrium, the vector sum of all the forces acting on it must be zero
 - $(\Sigma \mathbf{F} = \mathbf{0})$
 - This equation can be written in terms of its x, y and z components. This form is written as follows

$$(\Sigma F_x) \mathbf{i} + (\Sigma F_y) \mathbf{j} + (\Sigma F_z) \mathbf{k} = 0$$

This vector equation will be satisfied only when

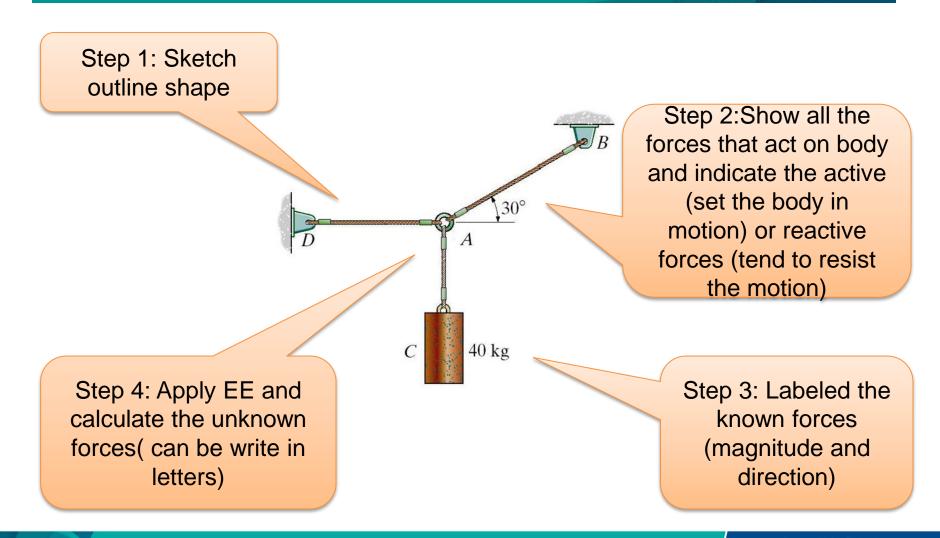
$$\Sigma F_{x} = 0$$

$$\Sigma F_{y} = 0$$

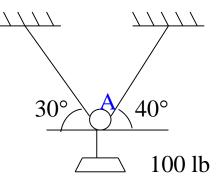
$$\Sigma F_{z} = 0$$

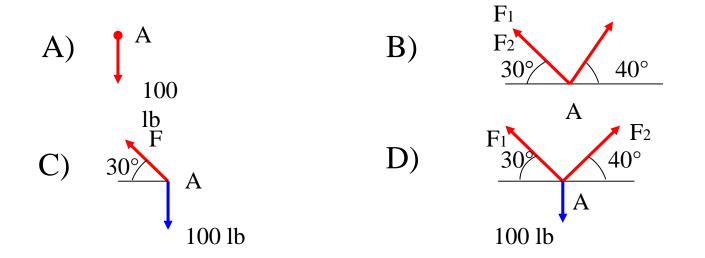
 These equations are the three scalar equations of equilibrium. They are valid for any point in equilibrium and allow you to solve for up to three unknowns.

Step to draw FBD



Select the correct FBD of Particle A







Using this FBD of Point C, the sum of forces in the x-direction (ΣF_{x}) is _____. 20 lb Use a sign convention of $+ \rightarrow$. A) $F_2 \sin 50^\circ - 20 = 0$ B) $F_2 \cos 50^\circ - 20 = 0$ C) $F_2 \sin 50^\circ - F_1 = 0$ D) $F_2 \cos 50^\circ + 20 = 0$

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 F_2

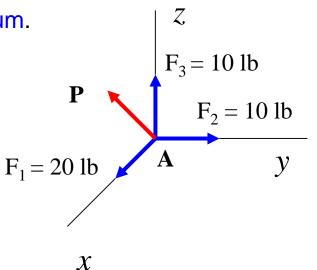
50°

F₁



Four forces act at point A and point A is in equilibrium. Select the correct force vector *P*.

- A) {-20 *i* + 10 *j* − 10 *k*}lb
- B) {-10 *i* − 20 *j* − 10 *k*} lb
- C) {+ 20 *i* − 10 *j* − 10 *k*}lb
- D) None of the above.

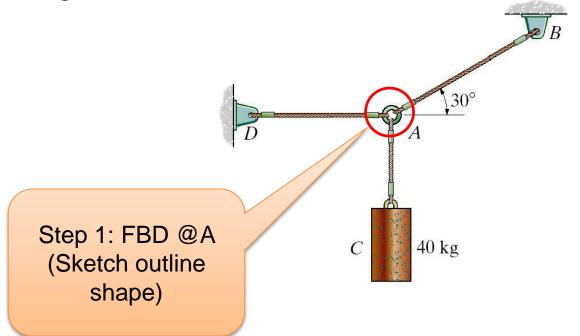


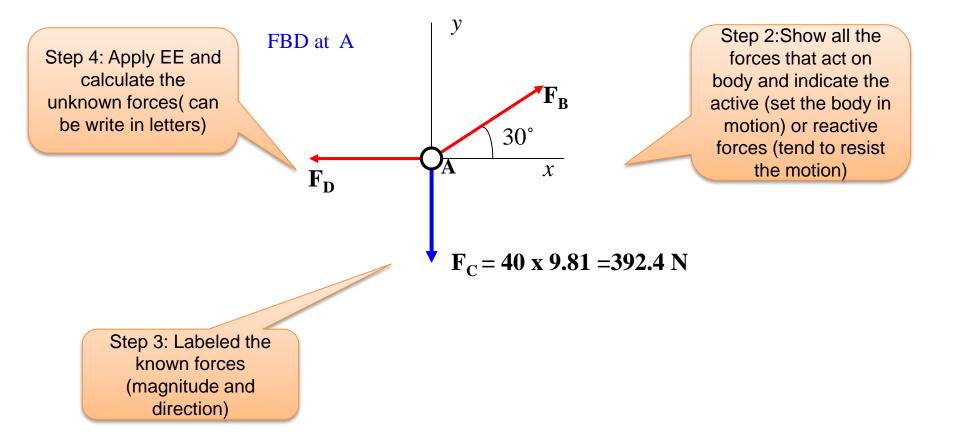
In 3-D, when you don't know the direction or the magnitude of a force, how many unknowns do you have corresponding to that force?

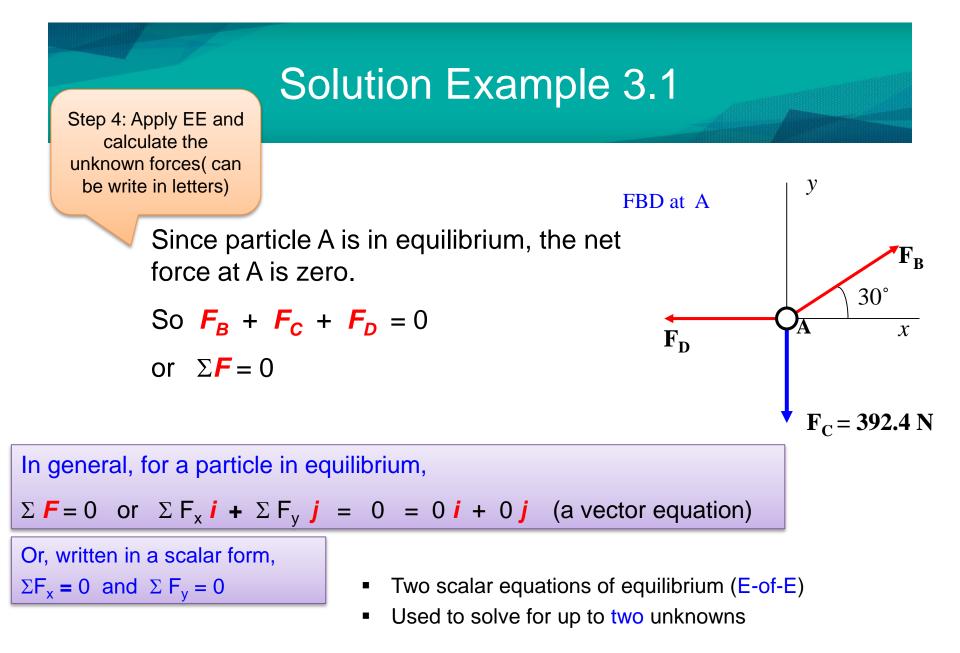
A) One B) Two C) Three D) Four

Example 3.1

This is an example of a 2-D or coplanar force system. If the whole assembly is in equilibrium, then particle A is also in equilibrium. Determine the tensions in the cables for a given weight of cylinder = 40kg







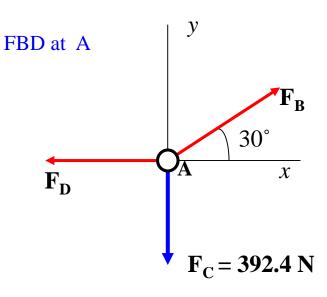
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Write the scalar E-of-E:

+ → Σ $F_x = F_B \cos 30^\circ - F_D = 0$ + ↑ Σ $F_v = F_B \sin 30^\circ - 392.4 \text{ N} = 0$

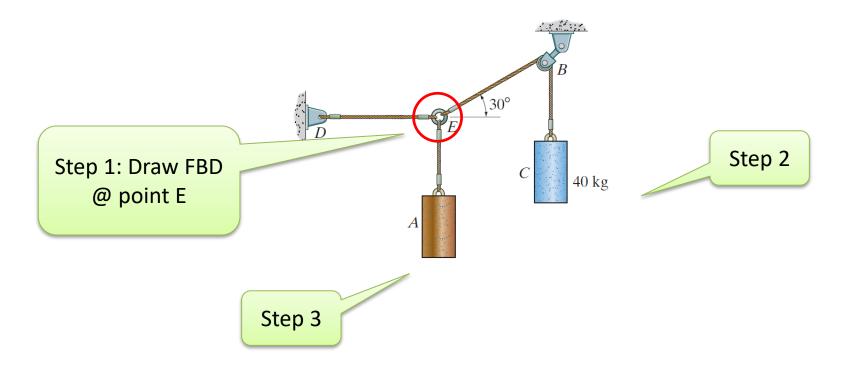
Solving the second equation, $F_B = 785 \text{ N} \rightarrow$

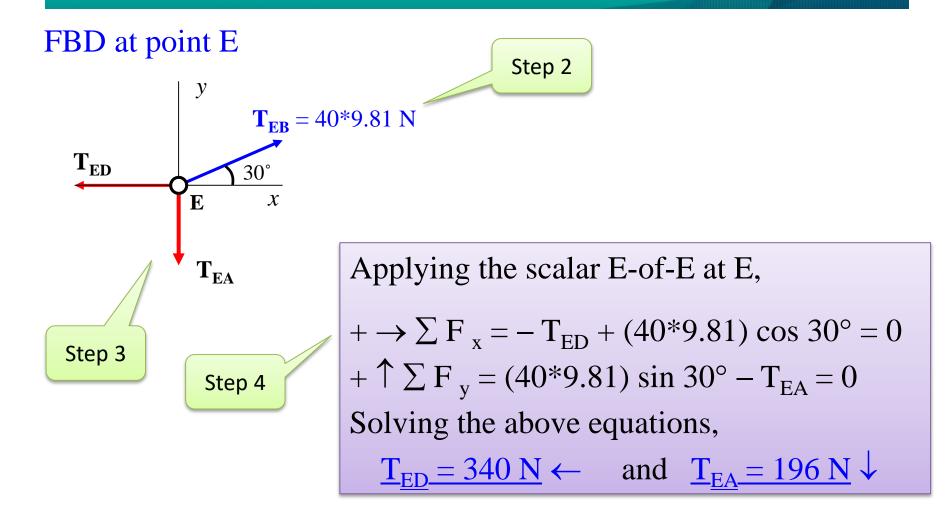
From the first equation, $\underline{F}_{D} = 680 \text{ N} \leftarrow$



Example 3.2

This is an example of a 2-D or coplanar force system. If the whole assembly is in equilibrium, then particle E is also in equilibrium. Determine the tensions in the cables DE,EA and EB for a given weight of cylinder = 40kg

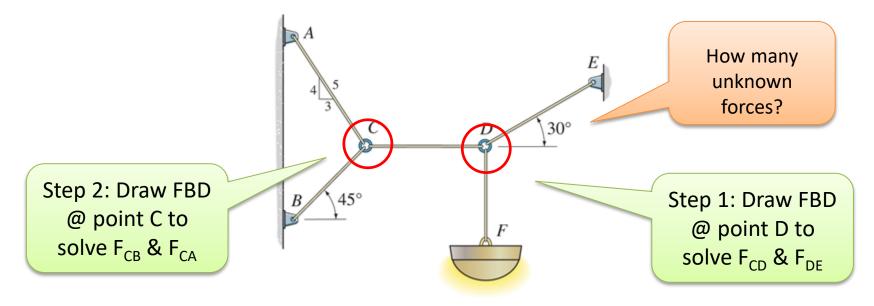


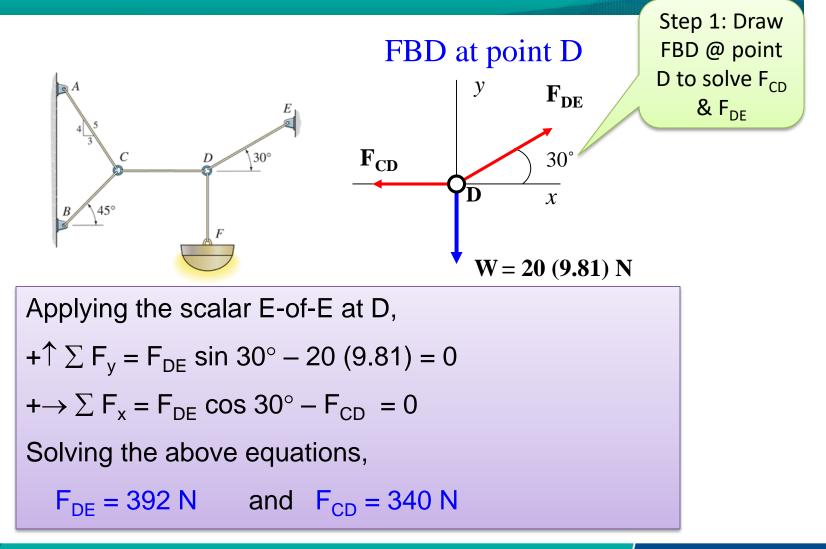


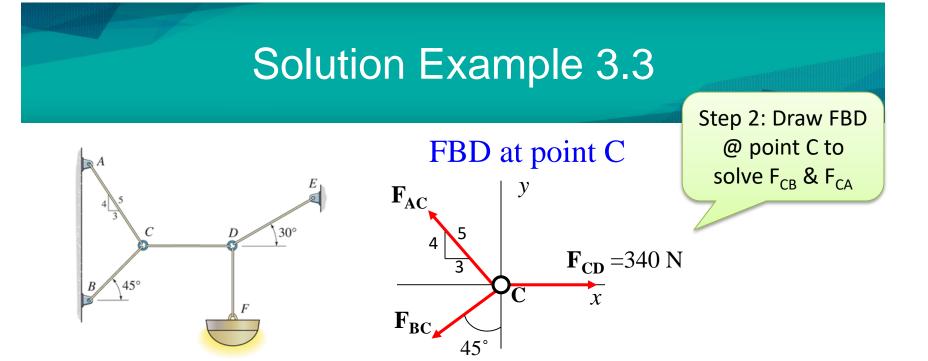
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Example 3.3

This is an example of a 2-D or coplanar force system. If the whole assembly is in equilibrium, then particle C and D are in equilibrium. Determine the force in each cables for a given weight of lamp = 20kg



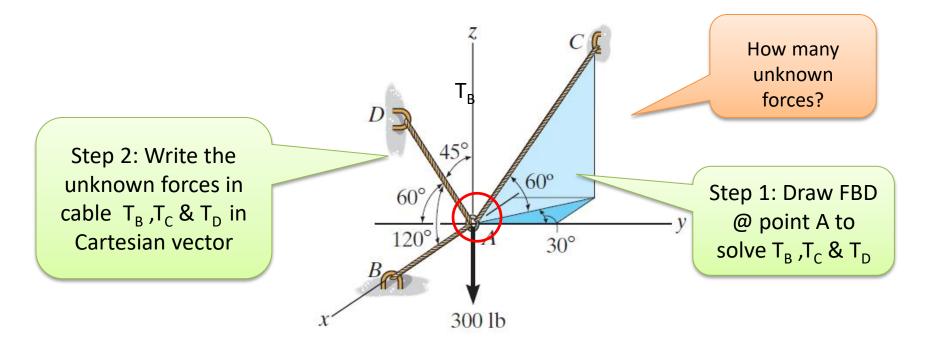




Applying the scalar E-of-E at C, $+ \rightarrow \sum F_x = 340 - F_{BC} \sin 45^\circ - F_{AC} (3/5) = 0$ $+ \uparrow \sum F_y = F_{AC} (4/5) - F_{BC} \cos 45^\circ = 0$ Solving the above equations, $\underline{F_{BC}} = 275 \text{ N} \swarrow \text{ and } \underline{F_{AC}} = 243 \text{ N}$

Example 3.4

This is an example of a 3-D or coplanar force system. If the whole assembly is in equilibrium, determine the tension developed in each cables

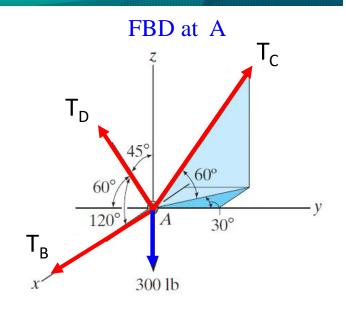


 $T_B = T_B i$ $T_C = -(T_C \cos 60^\circ) \sin 30^\circ i$ $+(T_C \cos 60^\circ) \cos 30^\circ j$ $+T_C \sin 60^\circ k$

$$T_{C} = T_{C} (-0.25 \, i + 0.433 \, j + 0.866 \, k)$$

$$T_{D} = T_{D} \cos 120^{\circ} i + T_{D} \cos 120^{\circ} j + T_{D} \cos 45^{\circ} k$$
$$T_{D} = T_{D} (-0.5 i - 0.5 j + 0.7071 k)$$

 $\boldsymbol{W} = -300 \, \boldsymbol{k}$



Applying equilibrium equations:

 $\Sigma F_{R} = 0 = T_{B} i$ + T_C (- 0.25 i +0.433 j + 0.866 k) + T_D (- 0.5 i - 0.5 j + 0.7071 k) - 300 k

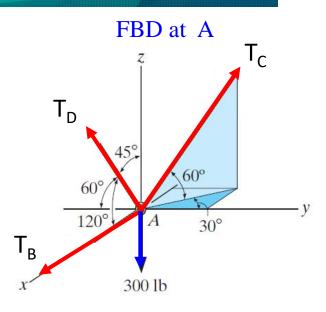
Equating the respective *i*, *j*, *k* components to zero,

$$\Sigma F_{x} = T_{B} - 0.25 T_{C} - 0.5 T_{D} = 0$$
 (1)

$$\Sigma F_{y} = 0.433 T_{C} - 0.5 T_{D} = 0$$
 (2)

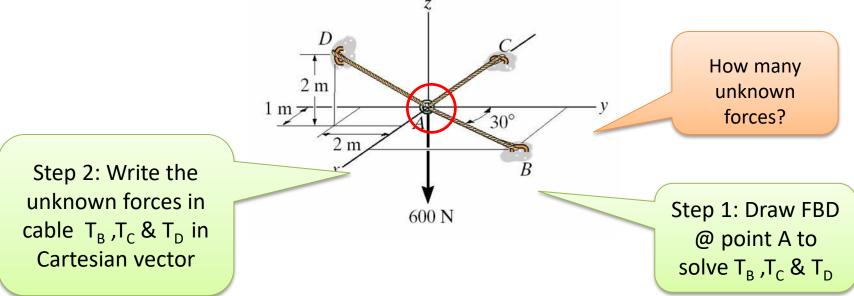
 $\Sigma F_z = 0.866 T_C + 0.7071 T_D - 300 = 0$ (3)

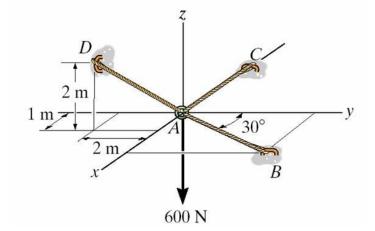
Using (2) and (3), $T_C = 203$ lb, $T_D = 176$ lb Substituting T_C and T_D into (1), $T_B = 139$ lb

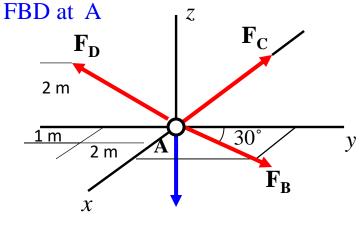


Example 3.5

This is an example of a 3-D or coplanar force system. If the whole assembly is in equilibrium, determine the tension developed in each cables







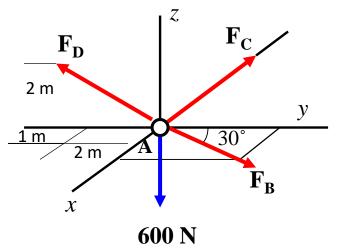
600 N

 $F_{B} = F_{B} (\sin 30^{\circ} i + \cos 30^{\circ} j) N$ = {0.5 F_B i + 0.866 F_B j} N $F_{C} = -F_{C} i N$

$$F_{D} = F_{D} (r_{AD}/r_{AD})$$

= $F_{D} \{ (1 \ i - 2 \ j + 2 \ k) \ l (1^{2} + 2^{2} + 2^{2})^{\frac{1}{2}} \} N$
= $\{ 0.333 \ F_{D} \ i - 0.667 \ F_{D} \ j + 0.667 \ F_{D} \ k \} N$

Now equate the respective *i*, *j*, and *k* components to zero $\sum F_x = 0.5 F_B - F_C + 0.333 F_D = 0$ $\sum F_y = 0.866 F_B - 0.667 F_D = 0$ $\sum F_z = 0.667 F_D - 600 = 0$



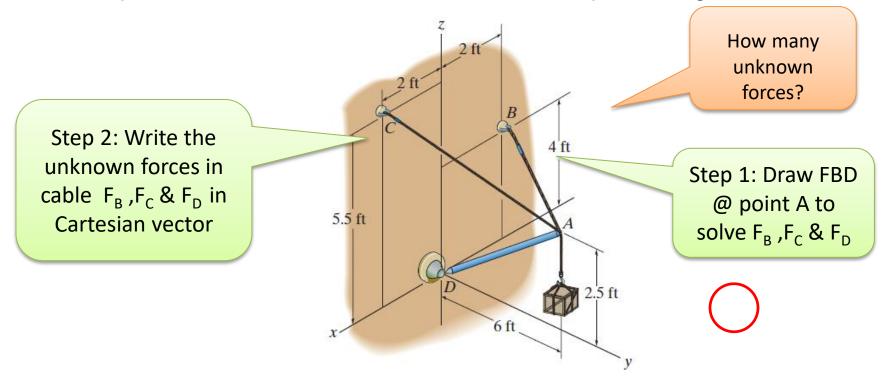
Solving the three simultaneous equations yields

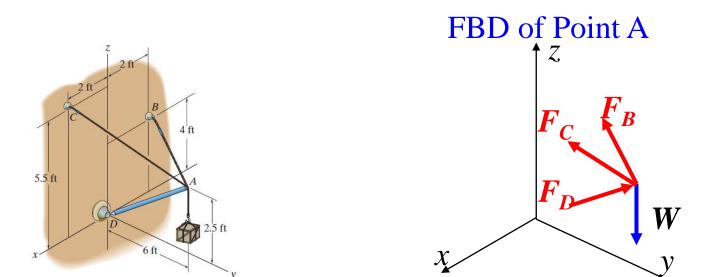
 F_{C} = 646 N (since it is positive, it is as assumed, e.g., in tension) F_{D} = 900 N

 $F_{B} = 693 N$

Example 3.6

This is an example of a 3-D or coplanar force system. If the whole assembly is in equilibrium, and supported by two cables and strut AD. Given 400 lb crate, determine the magnitude of the tension developed in each cables and the force developed along strut ADs





W = weight of crate = -400 k lb $F_B = F_B(r_{AB}/r_{AB}) = F_B\{(-4 \text{ i} - 12 \text{ j} + 3 \text{ k}) / (13)\} \text{ lb}$ $F_C = F_C(r_{AC}/r_{AC}) = F_C\{(2 \text{ i} - 6 \text{ j} + 3 \text{ k}) / (7)\} \text{ lb}$ $F_D = F_D(r_{AD}/r_{AD}) = F_D\{(12 \text{ j} + 5 \text{ k}) / (13)\} \text{ lb}$

The particle A is in equilibrium, hence

FB + FC + FD + W = 0

Now equate the respective i, j, k components to zero (i.e., apply the three scalar equations of equilibrium).

$$\sum Fx = -(4/13) FB + (2/7) FC = 0$$
(1)

$$\Sigma Fy = -(12/13) FB - (6/7) FC + (12/13) FD = 0$$
 (2)

 $\Sigma Fz = (3 / 13) FB + (3 / 7) FC + (5 / 13) FD - 400 = 0$ (3)

Solving the three simultaneous equations gives the forces

- FB = 274 Ib
- FC = 295 lb
- FD = 547 lb

Conclusion of The Chapter 3

- Conclusions
 - The Equilibrium and FBD have been identified
 - The Equilibrium Equation have been implemented to solve a particle problems in Coplanar Forces Systems





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