

BMM3553 Mechanical Vibrations

Chapter 1: Introduction to Vibrations

by

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Chapter Description

- **Expected Outcomes**

Students will be able to:

- Understand the basic concepts of vibration
- Identify the different types of motion
- Identify the different types of vibration
- Identify the Degree of Freedom.



- **References**

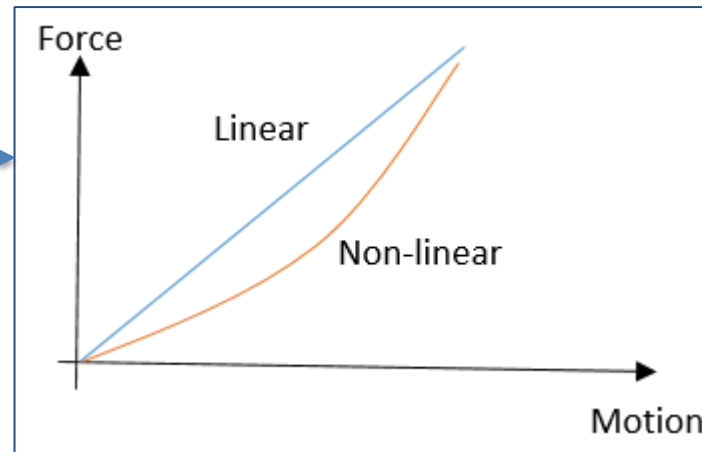
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Introduction

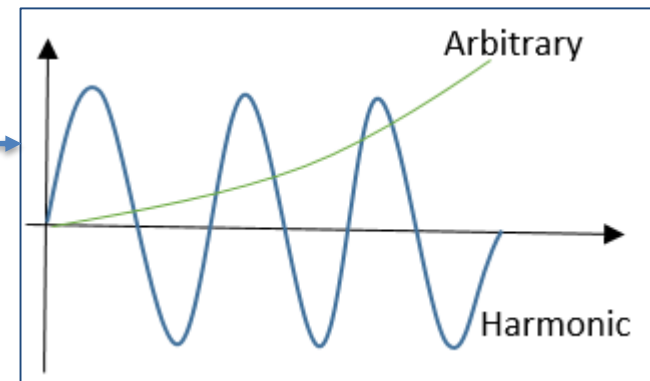
| | No Forces | Forces |
|-----------|-------------------|-----------------|
| No Motion | Who Care? | Statics |
| Motion | Kinematics | Dynamics |

Dynamics

Linear
Non-Linear



Arbitrary motion
Harmonic motion



- Mechanical Vibration
- Acoustics

Building on the Past

Dynamics and Kinematics

Strength of Materials

Thermodynamics

Differential Equations

Basic Concepts of Vibration

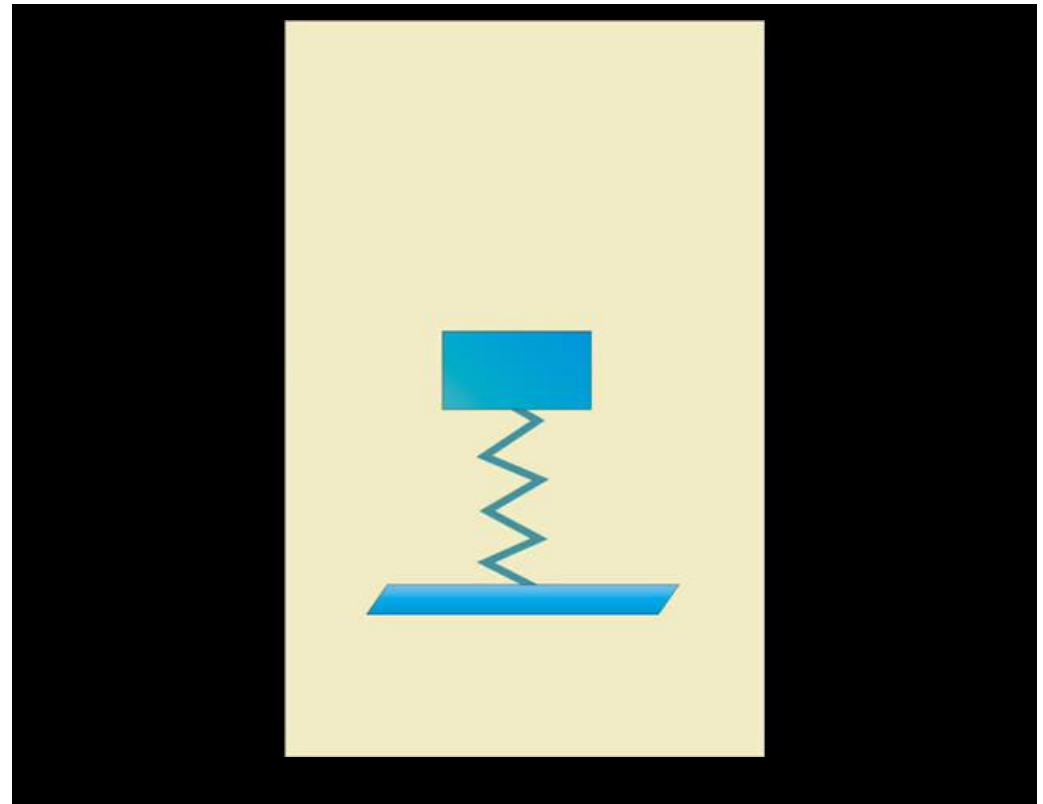
- ❑ Inherent in the study of vibration is **oscillation**.
- ❑ **Electric circuits** can have **oscillatory voltages** or currents but these are **not called vibratory systems** and their study is not called vibration.
- ❑ **Air pressure** oscillation is called sound but the study of sound is called **acoustics not vibration**.
- ❑ **Vibration** is usually used to describe the **motion of mechanical objects** that **oscillates** or have the **potential to oscillate**

Basic Concepts of Vibration

- ❑ Vibration is repetition of any motion after a period of time
- ❑ Vibration System consists of those elements:
 - 1) mass or inertia
 - 2) spring or elasticity
 - 3) damper
- ❑ Involves transfer of potential energy to kinetic energy and vice versa

Why is sine function often associated with vibration?

- The decomposed rotating force vector is sinusoidal
- The natural or free motion of an elastic body about equilibrium position is sinusoidal
- Combined they create a sinusoidal motion commonly known as **VIBRATION**



Rotating force vector becomes sinusoidal force in the vertical direction

$$= F \sin \omega t$$

Classification of Vibration

By Motion:

Simple Harmonic Motion

The simplest form of vibration.

Exact position is predictable from the equation of motion.

Mathematical description:

$$x(t) = A \sin(\omega t + \theta)$$

Simple Harmonic Motion

$$x(t) = A \sin(\omega t + \theta)$$

Terms:

$x(t)$ - instantaneous displacement (m)

A - maximum amplitude (m)

ω - angular velocity (Radians/Second)

θ - phase angle (Radians)

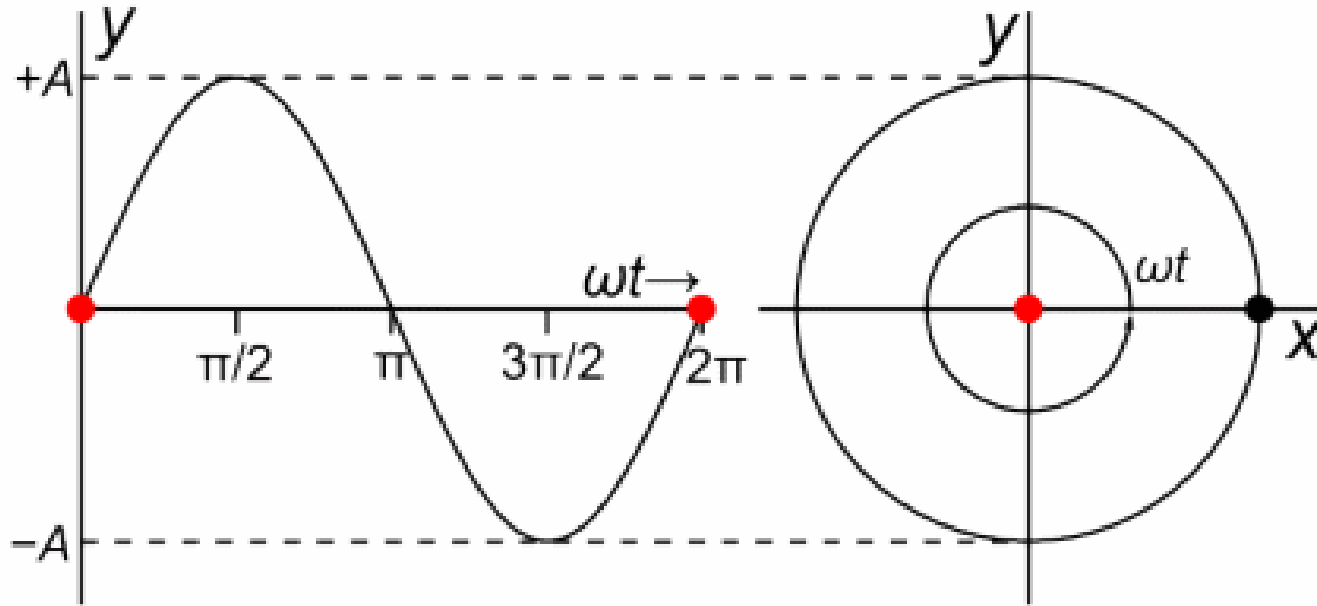
f = frequency, $\omega = 2\pi f$

T = cycle/period, $T = 1 / f$

Natural frequency, characteristic frequency, fundamental frequency, resonance frequency, normal frequency



Simple Harmonic Motion



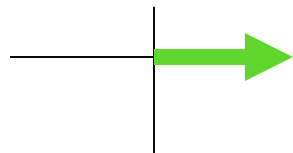
Graphical description of simple harmonic motion

Image source: https://commons.wikimedia.org/wiki/File:Simple_harmonic_motion_animation_1.gif

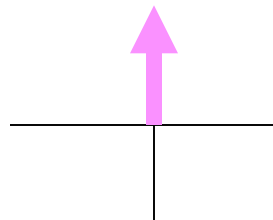


Simple Harmonic Motion

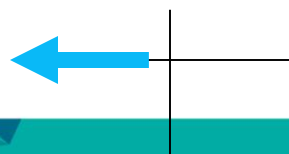
- **Vibration Parameters:
Displacement, Velocity
and Acceleration**



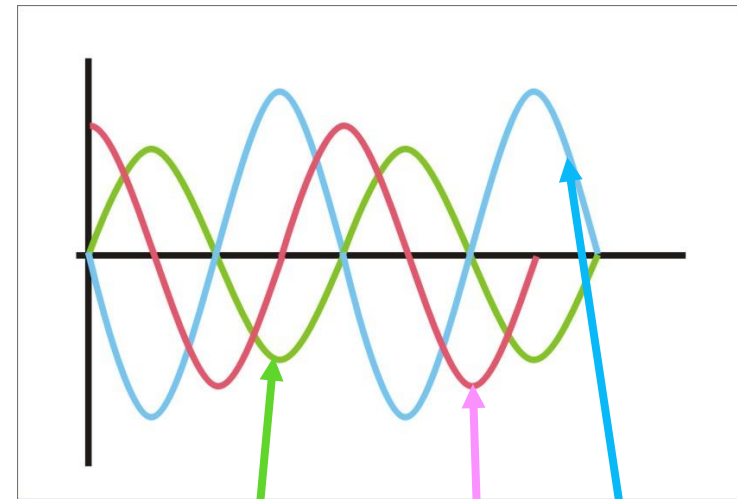
Displacement



Velocity



Acceleration



$$x = A \sin \omega t$$

$$\dot{x} = \omega A \cos \omega t$$

$$\ddot{x} = -\omega^2 A \sin \omega t = -\omega^2 x$$

Periodic Motion

- ❑ Motion repeats itself in equal time periods. Includes harmonics motion, pulses, etc.

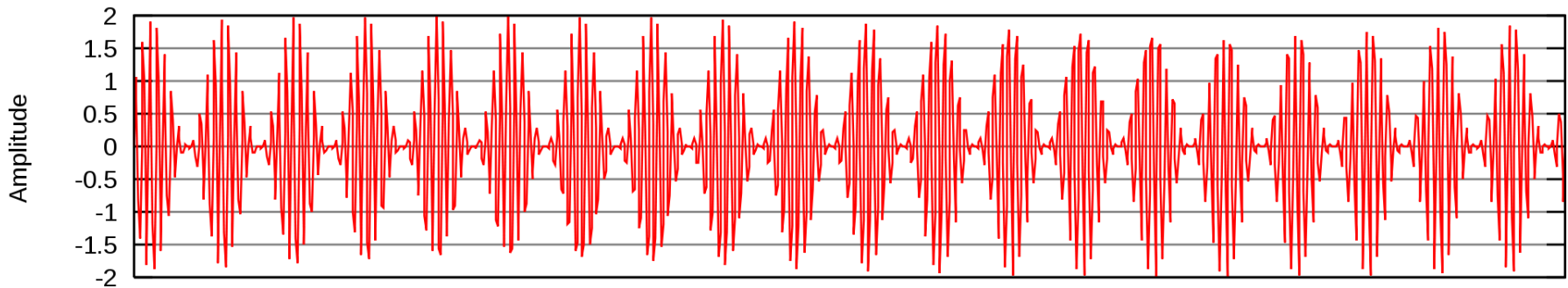
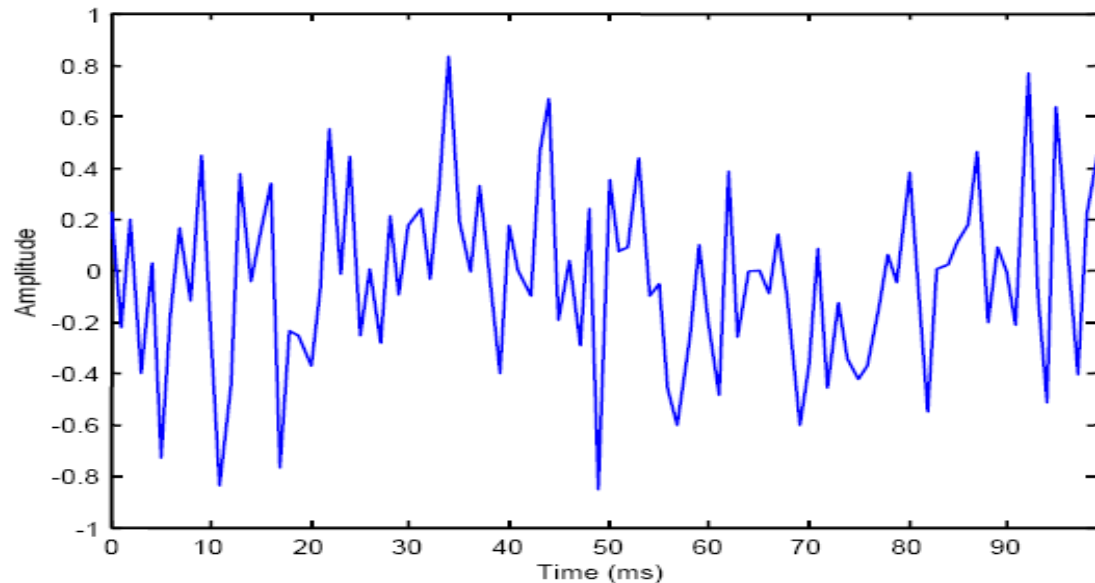


Image source: https://commons.wikimedia.org/wiki/File:AM_signals.svg



Random Motion

- ❑ Motion is not deterministic signal with no mathematical expression
- ❑ Vibration signal contains broad frequency band.
- ❑ Example: vehicle on uneven road surface, machine looseness.



Chaotic Motion

- Combination of random and periodic motion
- Random and repeatable characteristics combined in a non-linear fashion
- Vibration signal contains all frequencies in a given band but not in equal proportions

Transient Motion

- ❑ Any motion other than the above mentioned motion is called Transient motion
- ❑ Impulsive in nature, but not regularly repeated

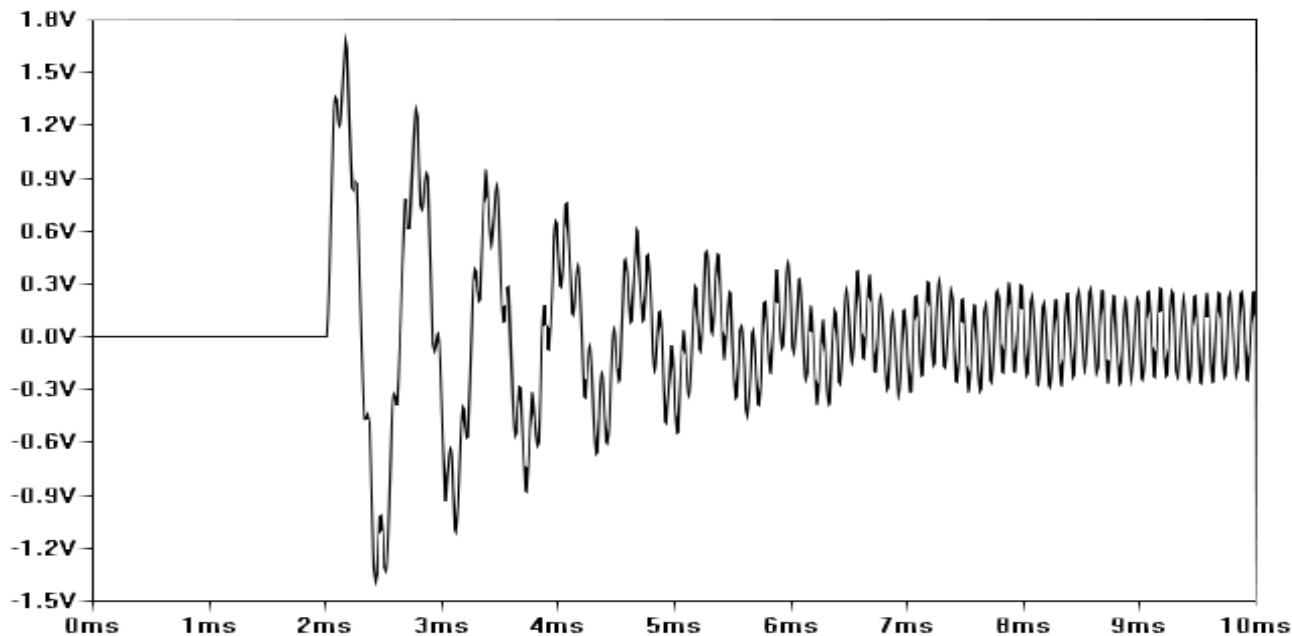


Image source: https://commons.wikimedia.org/wiki/File:Transiten_power_supply.svg

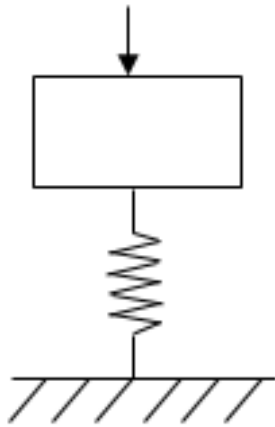


Basic Concepts of Vibration

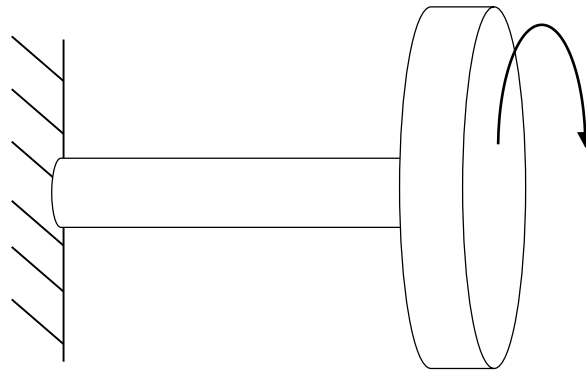
- Degree of freedom (DOF) is the minimum no. of independent coordinate systems required to define the position of the mass at any instant of time
- Depending on the independent coordinate, vibrating system is divided into the following
 - Single Degree of Freedom (SDOF) Systems
 - Multi Degree of Freedom (MDOF) Systems
 - Continuous System (Infinite DOF) systems

Basic Concepts of Vibration

□ Single degree of freedom system



Translation motion

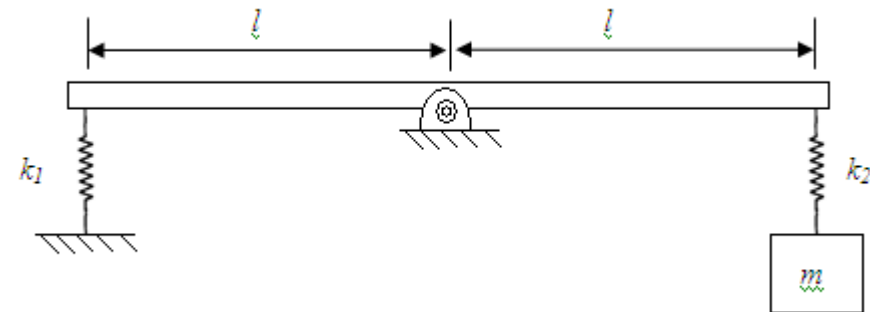
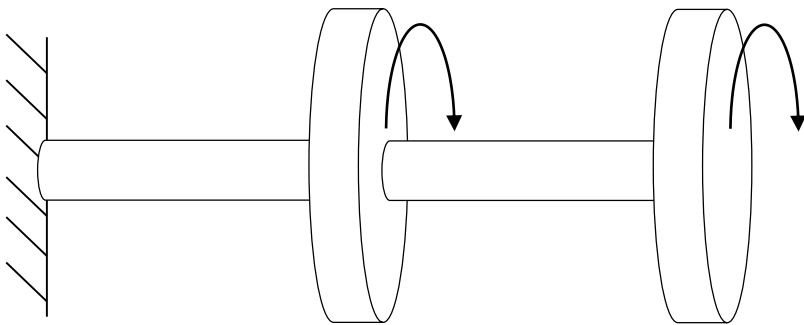
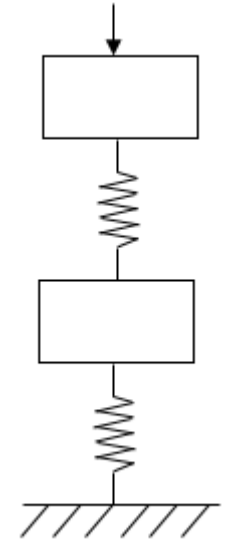


Torsional motion

Basic Concepts of Vibration

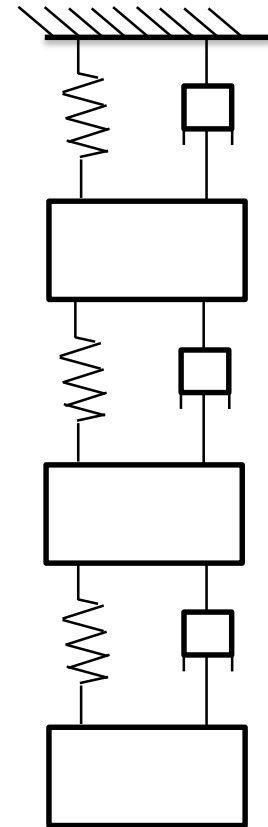
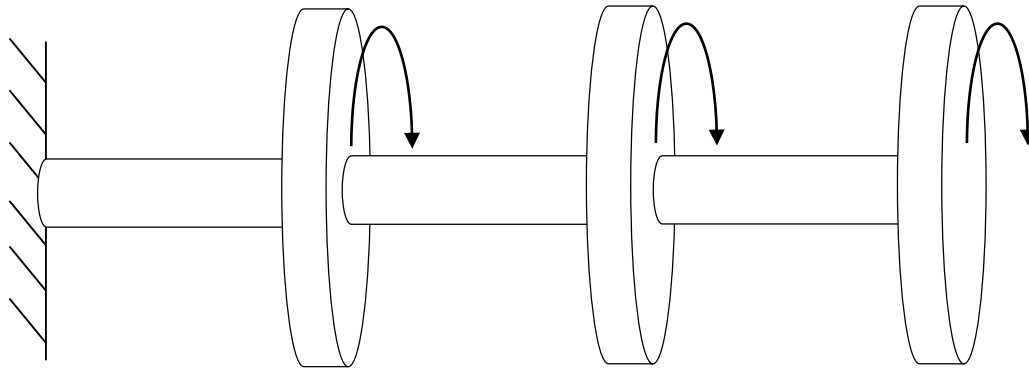
□ Examples of Two degree-of-freedom systems:

□ If more than one independent coordinate is required to define at any instant the position of different points in the system, it is referred to as a MDOF.



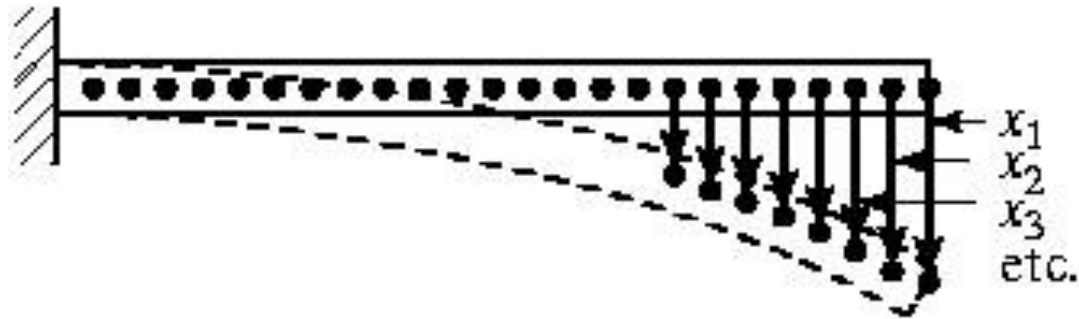
Basic Concepts of Vibration

□ Examples of Three degree of freedom systems:



Basic Concepts of Vibration

- Example of Continuous (Infinite-number-of-degrees-of-freedom) system:



- Infinite number of degrees of freedom (n-DOF) system are termed continuous or distributed systems
- Finite number of degrees of freedom are termed discrete or lumped parameter systems
- High n-DOF will produce more accurate results

Thank You

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