

# Hydraulics & Pneumatics

## Chapter 3: Electro-fluids (Circuit Design

by

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# Lesson Outcome

- By the end of this lecture, student should be able to:
  - Design and analyze advanced electro-hydraulic circuit with multiple actuators using solenoid valves.

# Multi Actuator Circuit

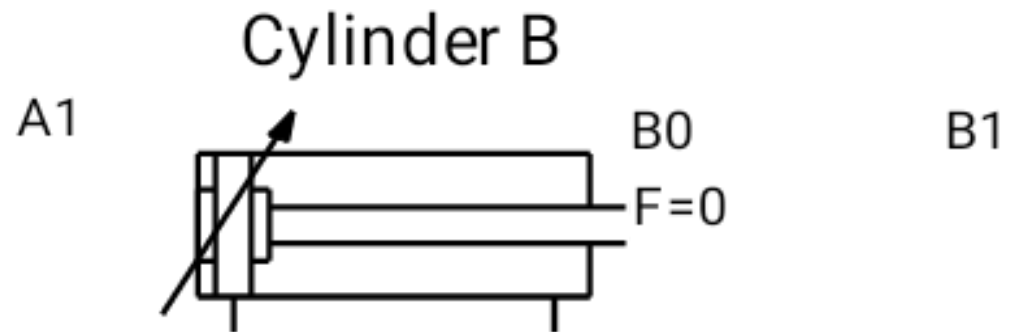
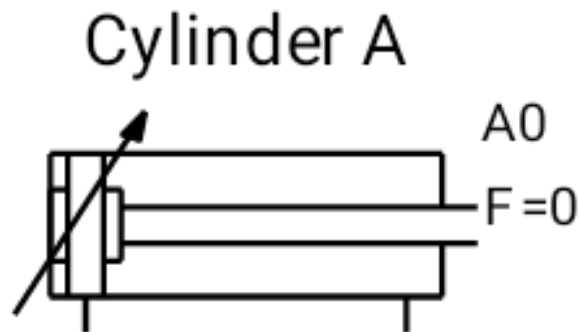
- More than 1 actuator
- 1 cylinder needs 1 valve
- Tips for circuit design:
  - Identify sequence of movement
  - Identify limit switch/sensor status

# Multi Actuator Circuit

- Example:
  - ⊠ A hydraulic actuated drilling machine contains two double acting cylinders (DACs). When the work piece is located at its position, cylinder A will clamp the work piece. Then, the drilling process starts, where the spindle is controlled by cylinder B. After completion of drilling, cylinder B will retract to the initial position, before the clamping cylinder retracts.
  - ⊠ Sequence: A (extend) -> B (extend) -> B (retract) -> A (retract)

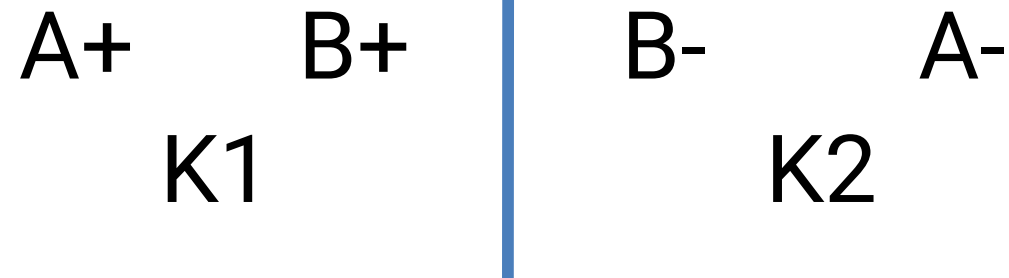
# Step 1: Sequence

- Identify sequence of movement  
A+      B+      B-      A-



## Step 2: Grouping

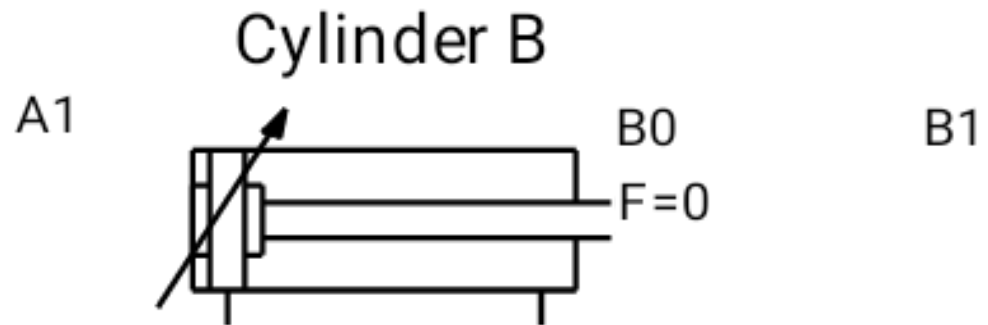
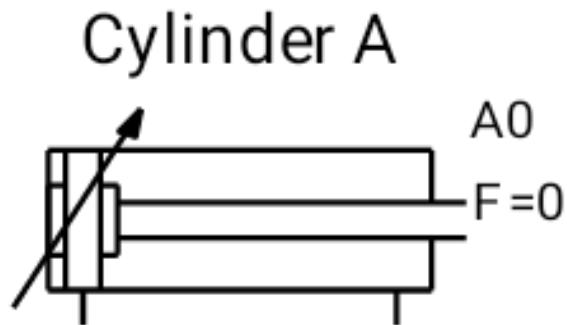
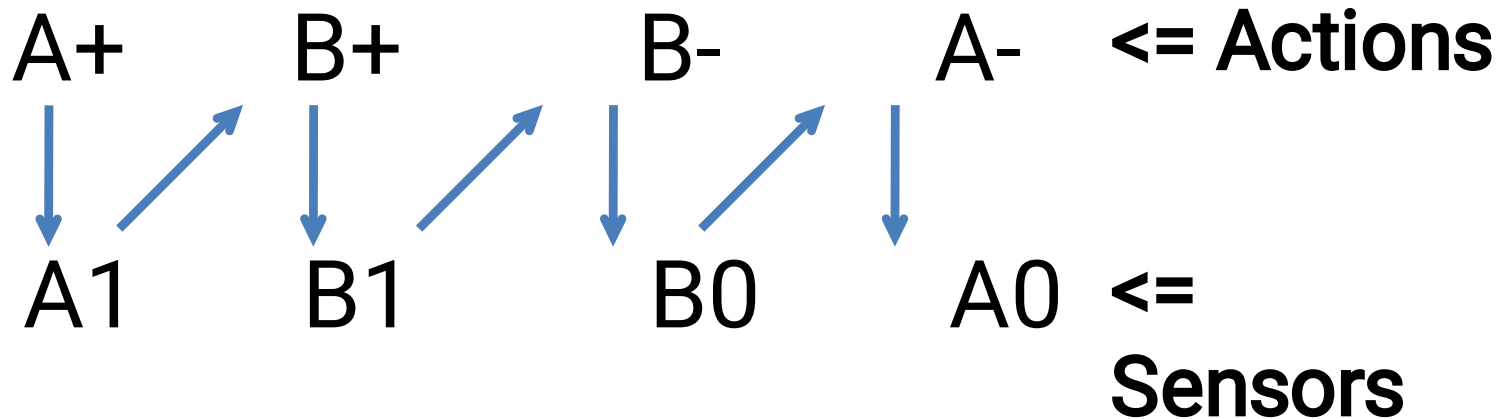
- Make the group



- A group must contain different elements
- 1 group represents 1 coil

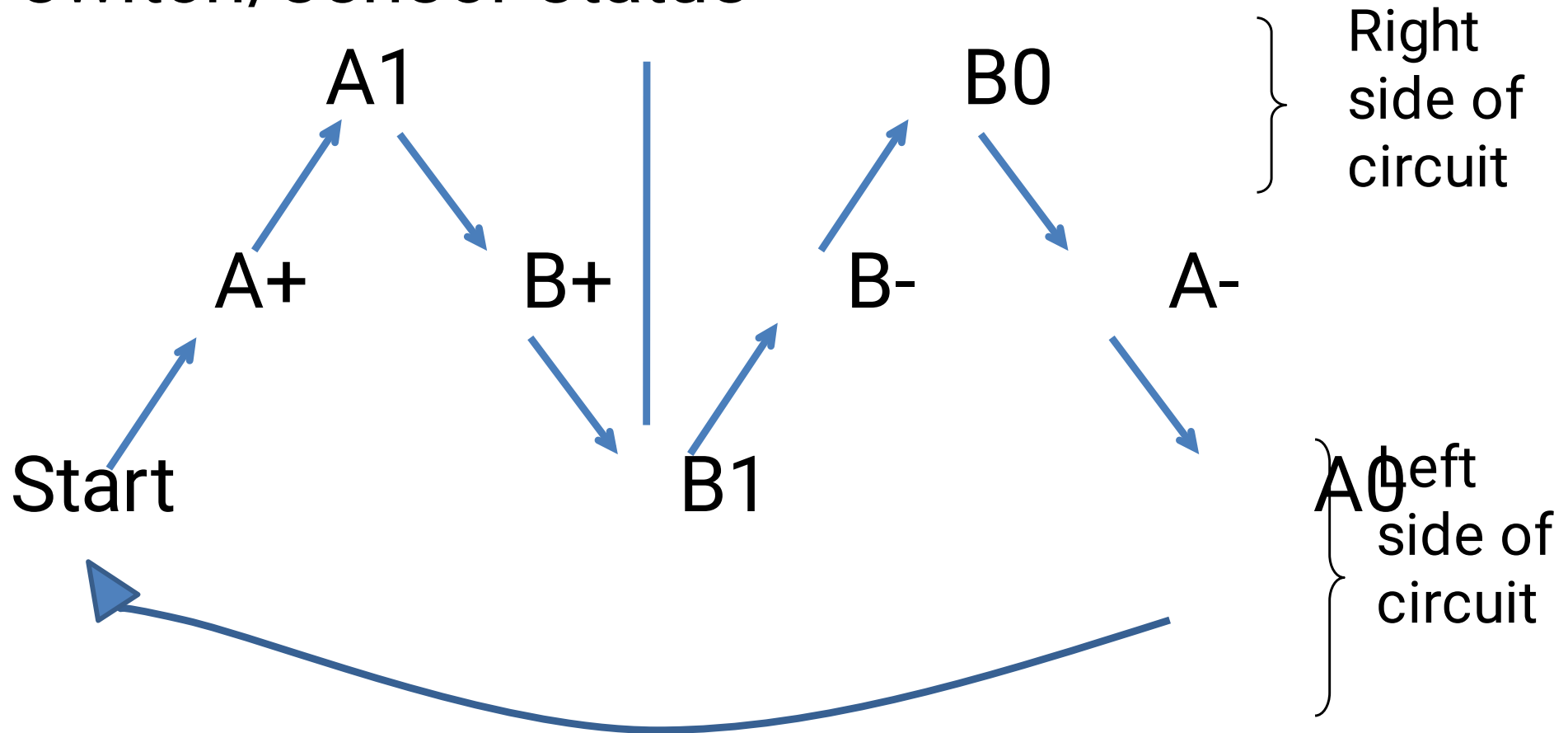
# Step 3: Limit switch/sensor status

## Identify limit switch/sensor status



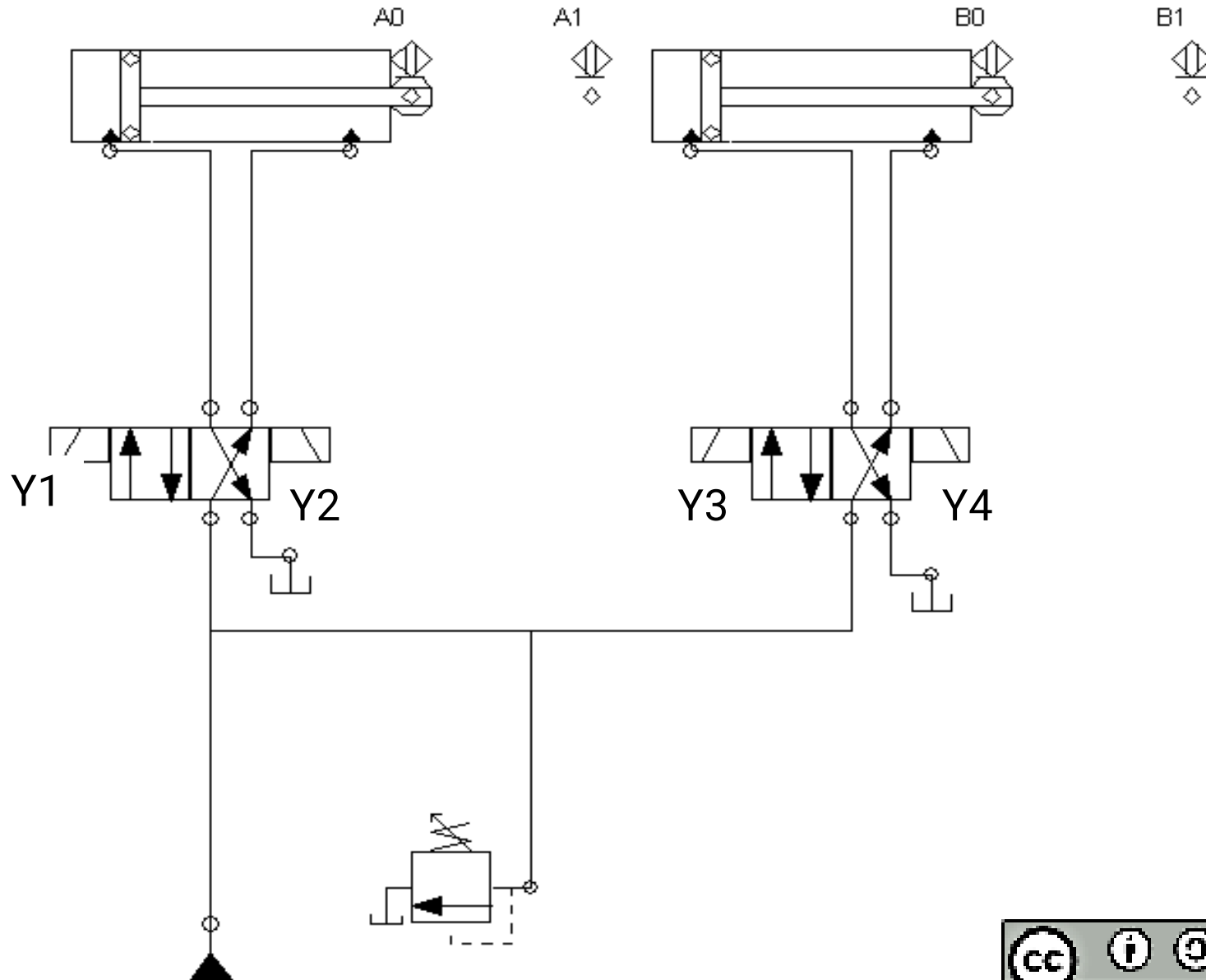
# Step 4: Rephrase

- ⊠ Rephrasing the sequence and limit switch/sensor status





# Designing of Hydraulic Circuit

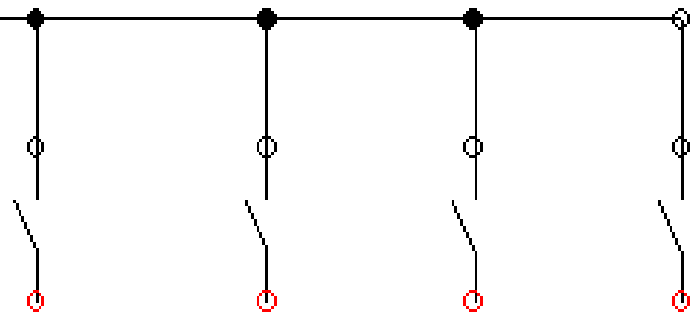


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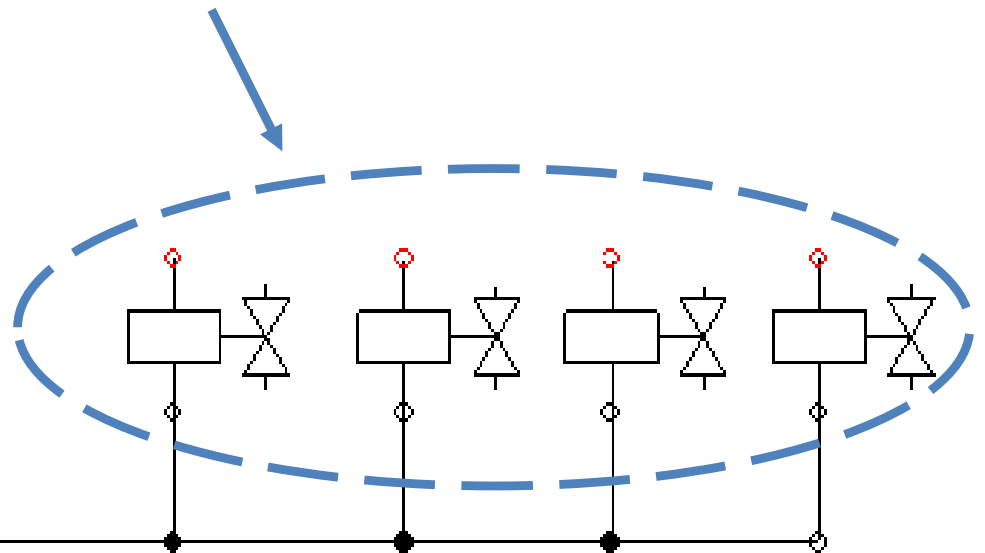
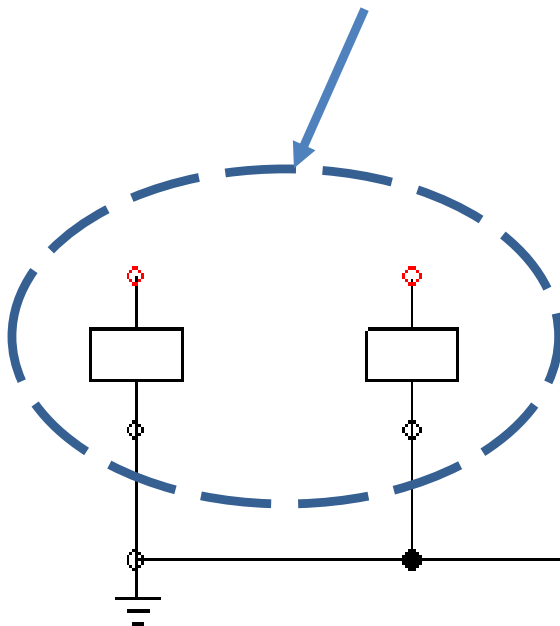


24V



2 coil for  
2 groups

4 solenoid for  
Y1, Y2, Y3 & Y4

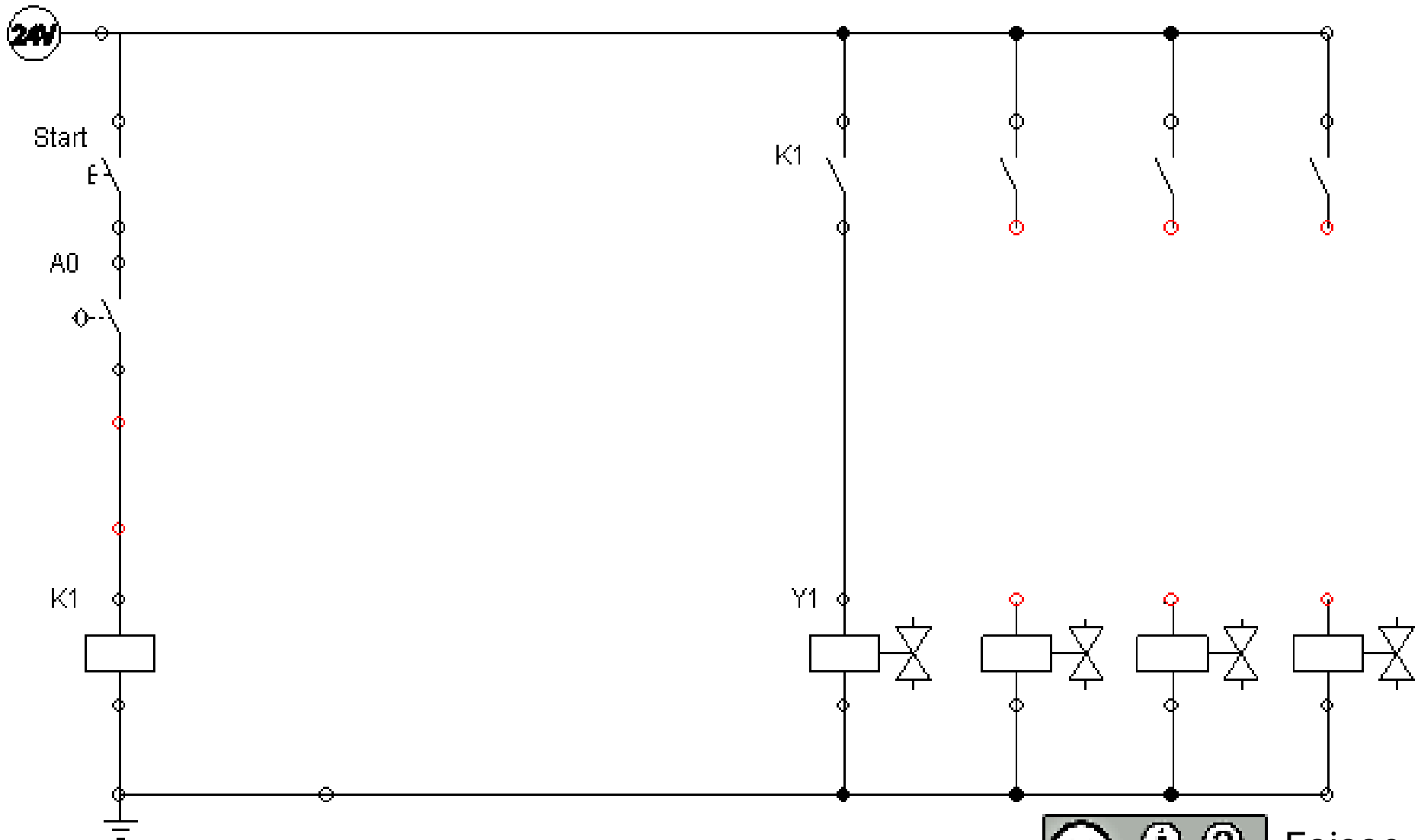


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# A+ → K1 Start A0



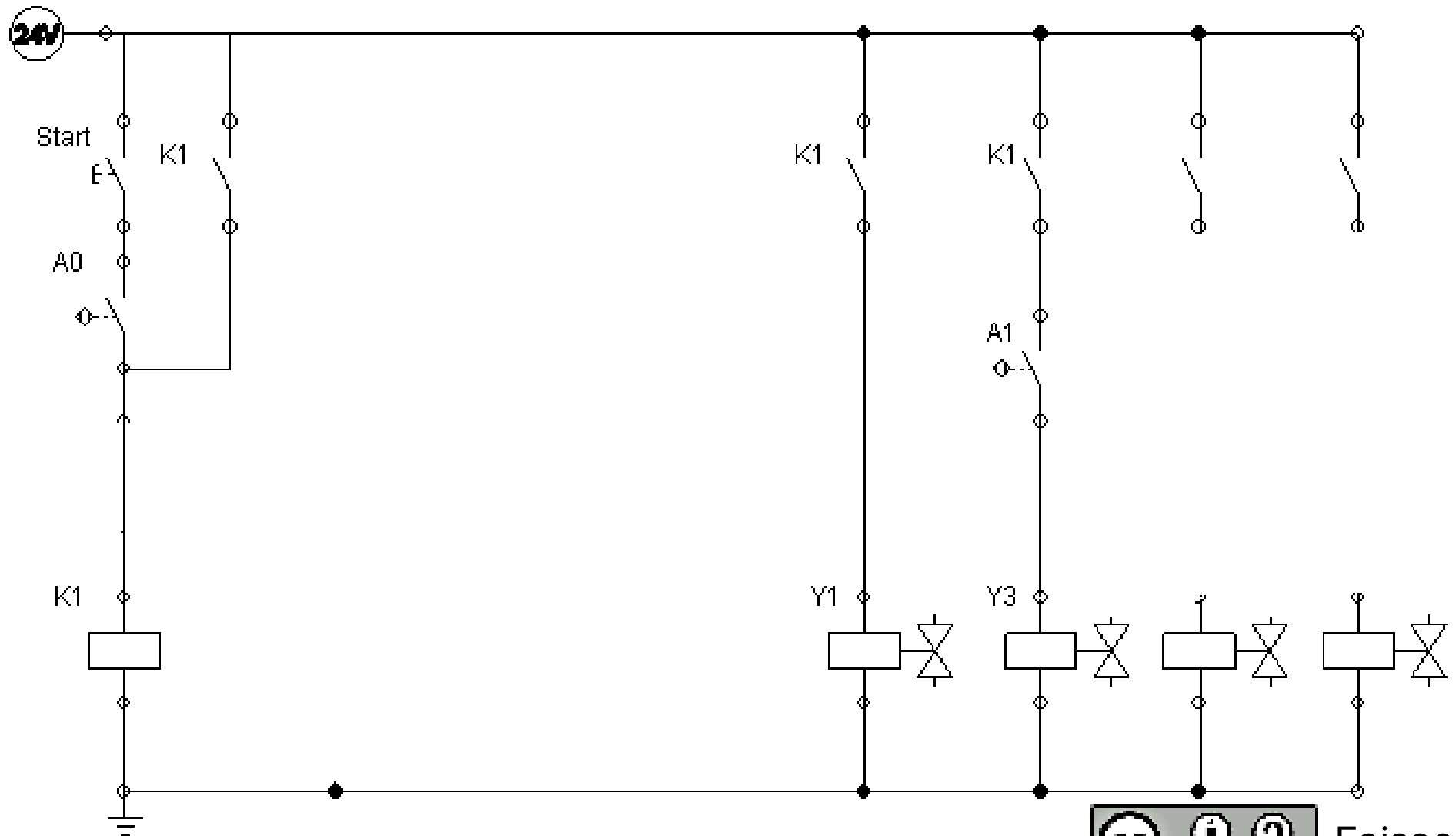
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# Latching

B  $\rightarrow$  K1  $\rightarrow$  A1



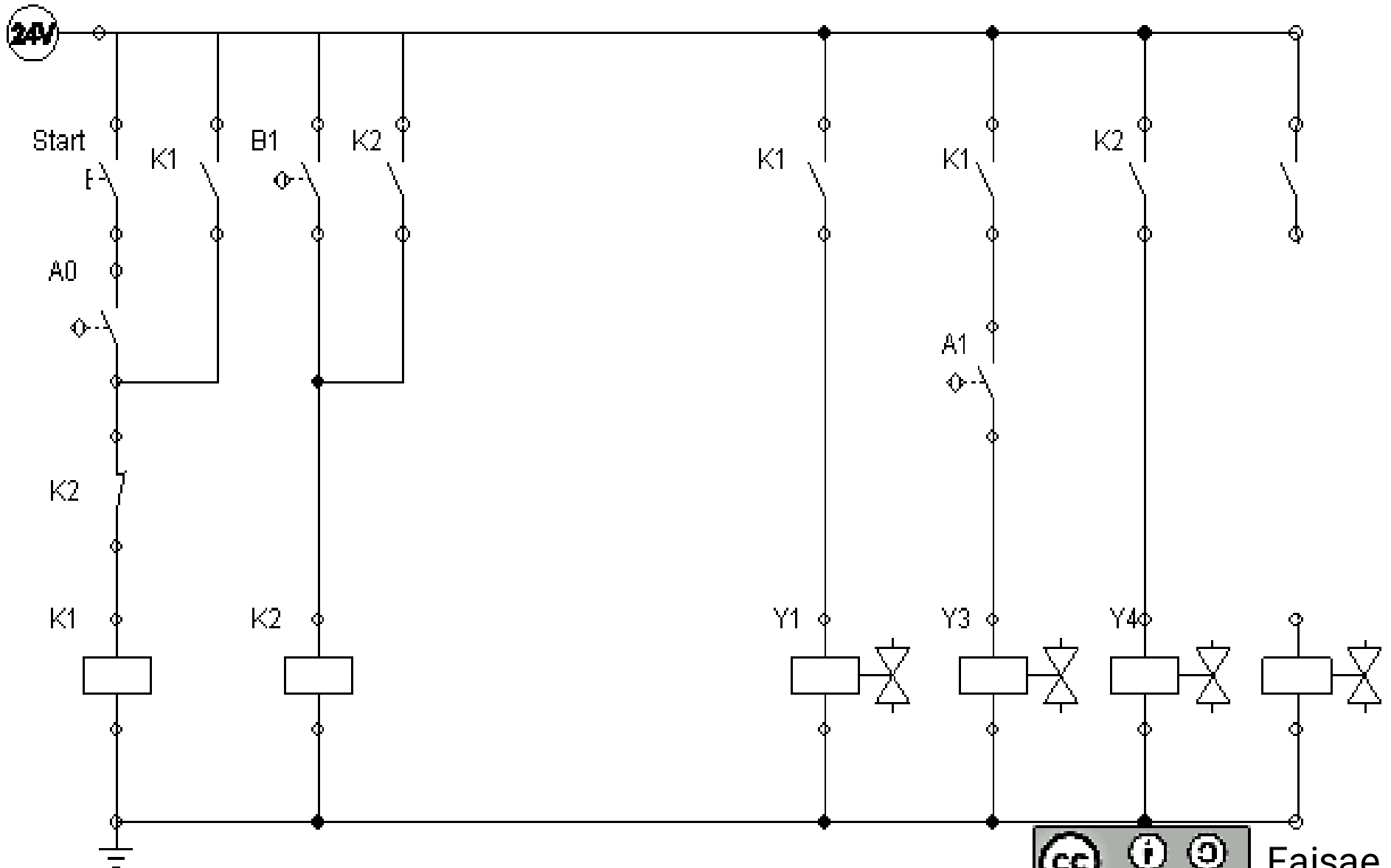
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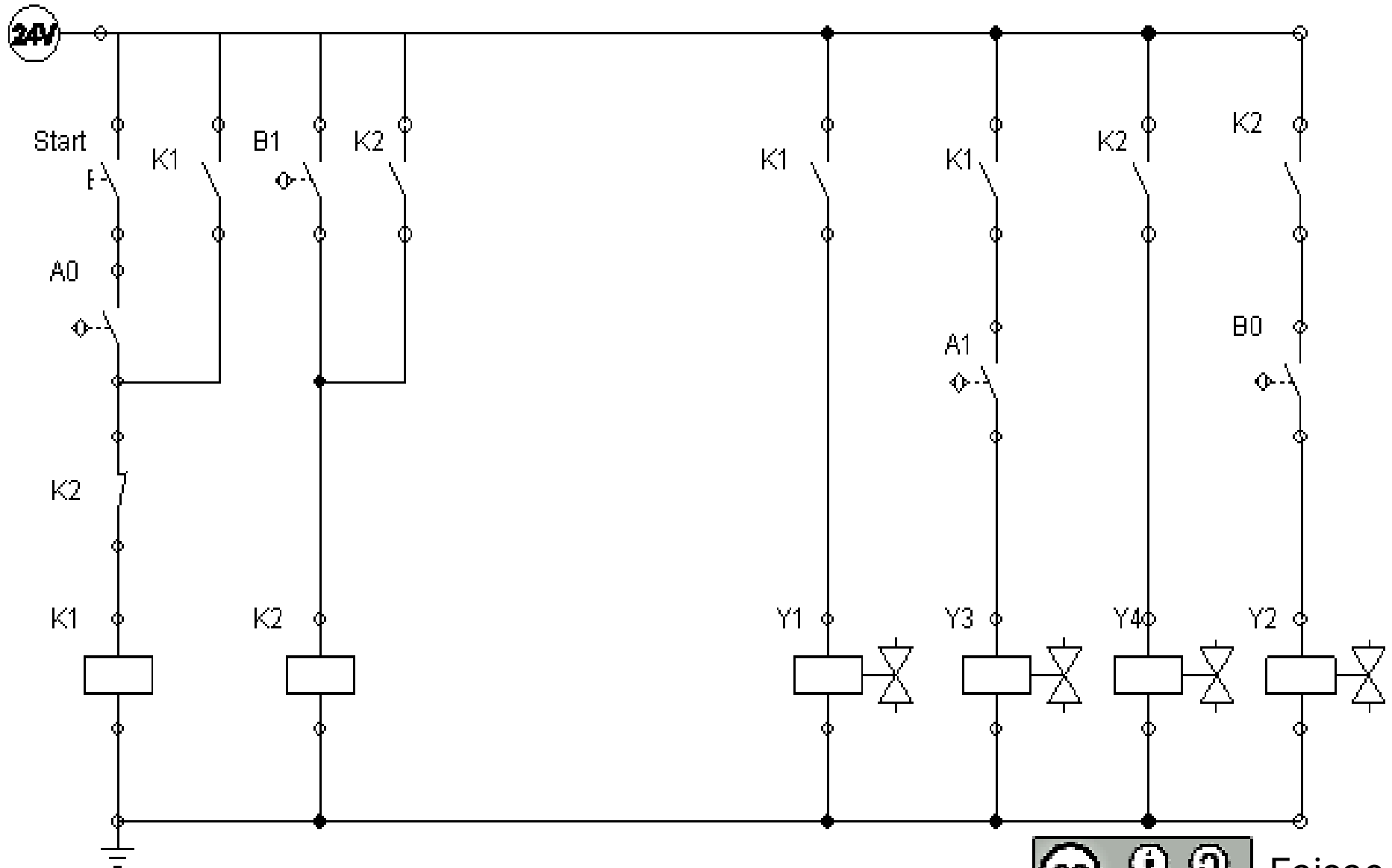
B- → K2 ☰ B1

# K2 due to changing group



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# A- → K2 ☰ B0



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# Exercise

- Design an electro hydraulics to conduct this sequence:
  - Cylinder 1 & 3 extend simultaneously
  - Cylinder 2 extend
  - Cylinder 2 retract
  - Cylinder 1 & 3 retract simultaneously

# Summary

- We have learn how to design an electro-hydraulics circuit with multiple actuators.